

Open Source Robotics And Process Control Cookbook Designing And Building Robust Dependable Real Time Systems

This volume presents the proceedings of the seventh annual Robotics: Science and Systems conference, held in 2011 at the University of Southern California. spans a wide spectrum of robotics, bringing together researchers working on the algorithmic or mathematical foundations of robotics, ED by Durrant-Whyte CEO of ICT Australia.

This book gathers a selection of papers presented at ROBOT 2019 – the Fourth Iberian Robotics Conference, held in Porto, Portugal, on November 20th–22nd, 2019. ROBOT 2019 is part of a series of conferences jointly organized by the SPR – Sociedade Portuguesa de Robótica (Portuguese Society for Robotics) and SEIDROB – Sociedad Española para la Investigación y Desarrollo en Robótica (Spanish Society for Research and Development in Robotics). ROBOT 2019 built upon several previous successful events, including three biannual workshops and the three previous installments of the Iberian Robotics Conference, and chiefly focused on presenting the latest findings and applications in robotics from the Iberian Peninsula, although the event was also open to research and researchers from other countries. The event featured five plenary talks on state-of-the-art topics and 16 special sessions, plus a main/general robotics track. In total, after a stringent review process, 112 high-quality papers written by authors from 24 countries were selected for publication.

This book presents the proceedings of two conferences, the 37th and 38th in the WoTUG series; Communicating Process Architectures (CPA) 2015, held in Canterbury, England, in August 2015, and CPA 2016, held in Copenhagen, Denmark, in August 2016. Fifteen papers were accepted for presentation at the 2015 conference. They cover a spectrum of concurrency concerns: mathematical theory, programming languages, design and support tools, verification, multicore infrastructure and applications ranging from supercomputing to embedded. Three workshops and two evening fringe sessions also formed part of the conference, and the workshop position papers and fringe abstracts are included in this book. Fourteen papers covering the same broad spectrum of topics were presented at the 2016 conference, one of them in the form of a workshop. They are all included here, together with abstracts of the five fringe sessions from the conference.

This proceedings volume showcases the latest achievements in research and development in Educational Robotics presented at the 7th International Conference on Robotics in Education (RiE) held in Vienna, Austria, during April 14-15, 2016. The book offers a range of methodologies for teaching robotics and presents various educational robotics curricula. It includes dedicated chapters for the design and analysis of learning environments as well as evaluation means for measuring the impact of robotics on the students' learning success. Moreover, the book presents interesting programming approaches as well as new applications, the latest tools, systems and components for using robotics. The presented applications cover the whole educative range, from elementary school to high school, college, university and beyond, for continuing education and possibly outreach and workforce development. The book provides a framework involving two complementary kinds of contributions: on the one hand on technical aspects and on the other hand on matters of didactic.

This book brings together experts from research and practice. It includes the design of innovative Robot Process Automation (RPA) concepts, the discussion of related research fields (e.g., Artificial Intelligence, AI), the evaluation of existing software products, and findings from real-life implementation projects. Similar to the substitution of physical work in manufacturing (blue collar automation), Robotic Process Automation tries to substitute intellectual work in office and administration processes with software robots (white-collar

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automation). The starting point for the development of RPA was the observation that – despite the use of process-oriented enterprise systems (such as ERP, CRM and BPM systems) – additional manual activities are still indispensable today. In the RPA approach, these manual activities are learned and automated by software robots, either by defining rules or by observing manual activities. RPA is related to business process management, machine learning, and artificial intelligence. Tools for RPA originated from dedicated stand-alone software. Today, RPA functionalities are also integrated into elaborated process management suites. From a conceptual perspective, RPA can be structured into input components (sensors in the wide sense), an intelligence center, and output components (actuators in the wide sense). From a strategic perspective, the impact of RPA can be related to the support of existing tasks, the complete substitution of human activities, and the innovation of processes as well as business models. At present, high expectations are related to the use of RPA in the improvement of software-supported business processes. Manual activities are learned and automated by software robots that interact with existing applications via the presentation layer. In combination with artificial intelligence (AI) as well as innovative interfaces (e. g., voice recognition) RPA creates a novel level of automation for office and administration processes. Its benefit potential reaches a return on investment (ROI) up-to 800% that is documented in various case studies.

These volumes of "Advances in Intelligent Systems and Computing" highlight papers presented at the "Third Iberian Robotics Conference (ROBOT 2017)". Held from 22 to 24 November 2017 in Seville, Spain, the conference is a part of a series of conferences co-organized by SEIDROB (Spanish Society for Research and Development in Robotics) and SPR (Portuguese Society for Robotics). The conference is focused on Robotics scientific and technological activities in the Iberian Peninsula, although open to research and delegates from other countries. Thus, it has more than 500 authors from 21 countries. The volumes present scientific advances but also robotic industrial applications, looking to promote new collaborations between industry and academia.

Embedded Systems and Robotics with Open-Source Tools provides easy-to-understand and easy-to-implement guidance for rapid prototype development. Designed for readers unfamiliar with advanced computing technologies, this highly accessible book: Describes several cutting-edge open-source software and hardware technologies Examines a number of embedded computer systems and their practical applications Includes detailed projects for applying rapid prototype development skills in real time Embedded Systems and Robotics with Open-Source Tools effectively demonstrates that, with the help of high-performance microprocessors, microcontrollers, and highly optimized algorithms, one can develop smarter embedded devices.

This proceedings volume comprises the latest achievements in research and development in educational robotics presented at the 9th International Conference on Robotics in Education (RIE) held in Qawra, St. Paul's Bay, Malta, during April 18-20, 2018. Researchers and educators will find valuable methodologies and tools for robotics in education that encourage learning in the fields of science, technology, engineering, arts and mathematics (STEAM) through the design, creation and programming of tangible artifacts for creating personally meaningful objects and addressing real-world societal needs. This also involves the introduction of technologies ranging from robotics platforms to programming environments and languages. Extensive evaluation results are presented that highlight the impact of robotics on the students' interests and competence development. The presented approaches cover the whole educative range from elementary school to the university level in both formal as well as informal settings.

Artificial Intelligence for Future Generation Robotics offers a vision for potential future robotics applications for AI technologies. Each chapter includes theory and

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mathematics to stimulate novel research directions based on the state-of-the-art in AI and smart robotics. Organized by application into ten chapters, this book offers a practical tool for researchers and engineers looking for new avenues and use-cases that combine AI with smart robotics. As we witness exponential growth in automation and the rapid advancement of underpinning technologies, such as ubiquitous computing, sensing, intelligent data processing, mobile computing and context aware applications, this book is an ideal resource for future innovation. Brings AI and smart robotics into imaginative, technically-informed dialogue Integrates fundamentals with real-world applications Presents potential applications for AI in smart robotics by use-case Gives detailed theory and mathematical calculations for each application Stimulates new thinking and research in applying AI to robotics

This Robotics Process Automation book describes the RPA platform for the future of business process automation. More precisely this RPA book has tried to innumerate the followings: 1. RPA that brings speed to your digital transformation. 2. RPA helps to get rid of resource burden and it's consequences. 3. This emphasizes Business process automation must be in the hands forntline. 4. Only Automation Anywhere Enterprise combines consumer-like usability with enterprise-class reliability, and security for RPA that empowers the workforce to automate on their own, in real time. 5. What does RPA mean for business? Optimize labour investment Increase capacity on demand Increase speed and productivity Maximize availability Improve business process compliance Improve controls Improve auditability Enhance security deliver business intelligence Enable digital transformation Improve employee morale 6. Putting RPA to work and deploy your digital workforce in your businesses like insurance, finance, manufacturing and health care and also other. Deploy, manage and audit your Digital Workforce through a highly-intuitive RPA central command center, on-premise or in the cloud. This RPA book also enable you to learn more about AI and machine language also factory automation, safeguard your data, analyze ald predict business performance, streamline your blended anywhere, big data ready for analytics. This book is made for BS/B,TECH and MS/M.TECH/MCA/MBA student who will have in-depth knowledge about RPA and its associated technologies falls in the same platform.

Design, simulate, and program interactive robots Key Features Design, simulate, build, and program an interactive autonomous mobile robot Leverage the power of ROS, Gazebo, and Python to enhance your robotic skills A hands-on guide to creating an autonomous mobile robot with the help of ROS and Python Book Description Robot Operating System (ROS) is one of the most popular robotics software frameworks in research and industry. It has various features for implementing different capabilities in a robot without implementing them from scratch. This book starts by showing you the fundamentals of ROS so you understand the basics of differential robots. Then, you'll learn about robot modeling and how to design and simulate it using ROS. Moving on, we'll design robot hardware and interfacing actuators. Then, you'll learn to configure and program depth sensors and LIDARs using ROS. Finally, you'll create a GUI for your robot using the Qt framework. By the end of this tutorial, you'll have a clear idea of how to integrate and assemble everything into a robot and how to bundle the software package. What you will learn Design a differential robot from scratch Model a differential robot using ROS and URDF Simulate a differential robot using ROS and Gazebo Design robot hardware electronics Interface robot actuators with embedded

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boards Explore the interfacing of different 3D depth cameras in ROS Implement autonomous navigation in ChefBot Create a GUI for robot control Who this book is for This book is for those who are conducting research in mobile robotics and autonomous navigation. As well as the robotics research domain, this book is also for the robot hobbyist community. You're expected to have a basic understanding of Linux commands and Python.

In this practical reference, popular author Lewin Edwards shows how to develop robust, dependable real-time systems for robotics and other control applications, using open-source tools. It demonstrates efficient and low-cost embedded hardware and software design techniques, based on Linux as the development platform and operating system and the Atmel AVR as the primary microcontroller. The book provides comprehensive examples of sensor, actuator and control applications and circuits, along with source code for a number of projects. It walks the reader through the process of setting up the Linux-based controller, from creating a custom kernel to customizing the BIOS, to implementing graphical control interfaces. Including detailed design information on: · ESBUS PC-host interface · Host-module communications protocol · A speed-controlled DC motor with tach feedback and thermal cut-off · A stepper motor controller · A two-axis attitude sensor using a MEMS accelerometer · Infrared remote control in Linux using LIRC · Machine vision using Video4Linux The first-ever book on using open source technology for robotics design! Covers hot topics such as GPS navigation, 3-D sensing, and machine vision, all using a Linux platform!

This carefully edited volume is the outcome of the eleventh edition of the Workshop on Algorithmic Foundations of Robotics (WAFR), which is the premier venue showcasing cutting edge research in algorithmic robotics. The eleventh WAFR, which was held August 3-5, 2014 at Bo?aziçi University in Istanbul, Turkey continued this tradition. This volume contains extended versions of the 42 papers presented at WAFR. These contributions highlight the cutting edge research in classical robotics problems (e.g. manipulation, motion, path, multi-robot and kinodynamic planning), geometric and topological computation in robotics as well novel applications such as informative path planning, active sensing and surgical planning. This book - rich by topics and authoritative contributors - is a unique reference on the current developments and new directions in the field of algorithmic foundations.

This book presents state-of-the-art research, challenges and solutions in the area of human-robot collaboration (HRC) in manufacturing. It enables readers to better understand the dynamic behaviour of manufacturing processes, and gives more insight into on-demand adaptive control techniques for industrial robots. With increasing complexity and dynamism in today's manufacturing practice, more precise, robust and practical approaches are needed to support real-time shop-floor operations. This book presents a collection of recent developments and innovations in this area, relying on a wide range of research efforts. The book is divided into five parts. The first part presents a broad-based review of the key areas of HRC, establishing a common ground of understanding in key aspects. Subsequent chapters focus on selected areas of HRC subject to intense recent interest. The second part discusses human safety within HRC. The third, fourth and fifth parts provide in-depth views of relevant methodologies and algorithms. Discussing dynamic planning and monitoring, adaptive control and multi-modal decision making, the latter parts facilitate a better

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understanding of HRC in real situations. The balance between scope and depth, and theory and applications, means this book appeals to a wide readership, including academic researchers, graduate students, practicing engineers, and those within a variety of roles in manufacturing sectors.

This book presents in a systematic manner the advanced technologies used for various modern robot applications. By bringing fresh ideas, new concepts, novel methods and tools into robot control, robot vision, human robot interaction, teleoperation of robot and multiple robots system, we are to provide a state-of-the-art and comprehensive treatment of the advanced technologies for a wide range of robotic applications. Particularly, we focus on the topics of advanced control and obstacle avoidance techniques for robot to deal with unknown perturbations, of visual servoing techniques which enable robot to autonomously operate in a dynamic environment, and of advanced techniques involved in human robot interaction. The book is primarily intended for researchers and engineers in the robotic and control community. It can also serve as complementary reading for robotics at the both graduate and undergraduate levels.

While Robotic Process Automation (RPA) has been around for about 20 years, it has hit an inflection point because of the convergence of cloud computing, big data and AI. This book shows you how to leverage RPA effectively in your company to automate repetitive and rules-based processes, such as scheduling, inputting/transferring data, cut and paste, filling out forms, and search. Using practical aspects of implementing the technology (based on case studies and industry best practices), you'll see how companies have been able to realize substantial ROI (Return On Investment) with their implementations, such as by lessening the need for hiring or outsourcing. By understanding the core concepts of RPA, you'll also see that the technology significantly increases compliance – leading to fewer issues with regulations – and minimizes costly errors. RPA software revenues have recently soared by over 60 percent, which is the fastest ramp in the tech industry, and they are expected to exceed \$1 billion by the end of 2019. It is generally seamless with legacy IT environments, making it easier for companies to pursue a strategy of digital transformation and can even be a gateway to AI. The Robotic Process Automation Handbook puts everything you need to know into one place to be a part of this wave. What You'll Learn Develop the right strategy and plan Deal with resistance and fears from employees Take an in-depth look at the leading RPA systems, including where they are most effective, the risks and the costs Evaluate an RPA system Who This Book Is For IT specialists and managers at mid-to-large companies

Comprehensive Materials Processing provides students and professionals with a one-stop resource consolidating and enhancing the literature of the materials processing and manufacturing universe. It provides authoritative analysis of all processes, technologies, and techniques for converting industrial materials from a raw state into finished parts or products. Assisting scientists and engineers in the selection, design, and use of materials, whether in the lab or in industry, it matches the adaptive complexity of emergent materials and processing technologies. Extensive traditional article-level academic discussion of core theories and applications is supplemented by applied case studies and advanced multimedia features. Coverage encompasses the general categories of solidification, powder, deposition, and deformation processing,

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and includes discussion on plant and tool design, analysis and characterization of processing techniques, high-temperatures studies, and the influence of process scale on component characteristics and behavior. Authored and reviewed by world-class academic and industrial specialists in each subject field Practical tools such as integrated case studies, user-defined process schemata, and multimedia modeling and functionality Maximizes research efficiency by collating the most important and established information in one place with integrated applets linking to relevant outside sources

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This book focuses on the fundamentals and recent advances in RGB-D imaging as well as covering a range of RGB-D applications. The topics covered include: data acquisition, data quality assessment, filling holes, 3D reconstruction, SLAM, multiple depth camera systems, segmentation, object detection, saliency detection, pose estimation, geometric modelling, fall detection, autonomous driving, motor rehabilitation therapy, people counting and cognitive service robots. The availability of cheap RGB-D sensors has led to an explosion over the last five years in the capture and application of colour plus depth data. The addition of depth data to regular RGB images vastly increases the range of applications, and has resulted in a demand for robust and real-time processing of RGB-D data. There remain many technical challenges, and RGB-D image processing is an ongoing research area. This book covers the full state of the art, and consists of a series of chapters by internationally renowned experts in the field. Each chapter is written so as to provide a detailed overview of that topic. RGB-D Image Analysis and Processing will enable both students and professional developers alike to quickly get up to speed with contemporary techniques, and apply RGB-D imaging in their own projects.

This book presents various recent applications of Artificial Intelligence in Information and Communication Technologies such as Search and Optimization methods, Machine Learning, Data Representation and Ontologies, and Multi-agent Systems. The main aim of this book is to help Information and Communication Technologies (ICT) practitioners in managing efficiently their platforms using AI tools and methods and to provide them with sufficient Artificial Intelligence background to deal with real-life problems.

This book constitutes the refereed proceedings of the Third International Conference on Simulation, Modeling, and Programming for Autonomous Robots, SIMPAR 2012, held in Tsukuba, Japan, in November 2012. The 33 revised full papers and presented together with 3 invited talks were carefully reviewed and selected from 46 submissions. Ten papers describe design of complex behaviors of autonomous robots, 9 address software layers, 8 papers refer to related modeling and learning. The papers are organized in topical sections on mobile robots, software modeling and architecture and humanoid and biped robots.

This book presents a comprehensive overview of the human dimension of social robots by discussing both transnational features and national peculiarities. Addressing several issues that explore the human side of social robots, this book investigates what a social robot is and how we might come to think about social robots in the different areas of everyday life. Organized around three sections that deal with Perceptions and Attitudes to Social Robots, Human Interaction with Social Robots, and Social Robots in Everyday

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Life, it explores the idea that even if the challenges of robot technologies can be overcome from a technological perspective, the question remains as to what kind of machine we want to have and use in our daily lives. Lessons learned from previous widely adopted technologies, such as smartphones, indicate that robot technologies could potentially be absorbed into the everyday lives of humans in such a way that it is the human that determines the human-machine interaction. In a similar way to how today's information and communication technologies were initially designed for professional/industrial use, but were soon commercialized for the mass market and then personalized by humans in the course of daily practice, the use of social robots is now facing the same revolution of 'domestication.' In the context of this transformation, which involves the profound embedding of robots in everyday life, the 'human' aspect of social robots will play a major part. This book sheds new light on this highly topical issue, one of the central subjects that will be taught and studied at universities worldwide and that will be discussed widely, publicly and repeatedly in the near future.

This book provides a review of precision agriculture technology development, followed by a presentation of the state-of-the-art and future requirements of precision agriculture technology. It presents different styles of precision agriculture technologies suitable for large scale mechanized farming; highly automated community-based mechanized production; and fully mechanized farming practices commonly seen in emerging economic regions. The book emphasizes the introduction of core technical features of sensing, data processing and interpretation technologies, crop modeling and production control theory, intelligent machinery and field robots for precision agriculture production. Publisher's Note: Products purchased from Third Party sellers are not guaranteed by the publisher for quality, authenticity, or access to any online entitlements included with the product. Robotics is becoming an increasingly popular field for hobbyists and professionals alike. The cost of the mechanics and electronics required to build a robot are low enough that almost anybody can afford it. The hardware that used to require government funding or a large university is now available to the average person. At the same time, programming is becoming a more common skill. This book combines the most sophisticated parts of robotics and programming to fill a real gap in available information. Most robotics books today use microcontrollers as the "brains" of the robots. This approach is fine for smaller, less expensive projects, but has serious limitations. When attempting to build a robot with sophisticated movements, navigation abilities, vision, and picture-capturing abilities, it is better to use a single board computer (SBC) such as Linux as the controller.

This book offers students and AI programmers a new perspective on the study of artificial intelligence concepts. The essential topics and theory of AI are presented, but it also includes practical information on data input & reduction as well as data output (i.e., algorithm usage). Because traditional AI concepts such as pattern recognition, numerical optimization and data mining are now simply types of algorithms, a different approach is needed. This "sensor / algorithm / effector" approach grounds the algorithms with an environment, helps students and AI practitioners to better understand them, and subsequently, how to apply them. The book has numerous up to date applications in game programming, intelligent agents, neural networks, artificial immune systems, and more. A CD-ROM with simulations, code, and figures

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accompanies the book.

Like the Internet before it, robotics is a socially and economically transformative technology. Robot Law explores how the increasing sophistication of robots and their widespread deployment into hospitals, public spaces, and battlefields requires rethinking of a wide variety of philosophical and public policy issues, including how this technology interacts with existing legal regimes, and thus may inspire changes in policy and in law. This volume collects the efforts of a diverse group of scholars who each, in their own way, has worked to overcome barriers in order to facilitate necessary and timely discussions of a technology in its infancy. Identifying controversial legal, ethical, and philosophical problems, the authors reveal how issues surrounding robotics and regulation are more complicated than engineers could have anticipated, and just how much definitional and applied work remains to be done. This groundbreaking examination of a brand-new reality will be of interest and of use to a variety of groups as the authors include engineers, ethicists, lawyers, roboticists, philosophers, and serving military.

This book includes a selection of papers from the 2017 International Conference on Software Process Improvement (CIMPS'17), presenting trends and applications in software engineering. Held from 18th to 20th October 2017 in Zacatecas, Mexico, the conference provided a global forum for researchers and practitioners to present and discuss the latest innovations, trends, results, experiences and concerns in various areas of software engineering, including but not limited to software processes, security in information and communication technology, and big data. The main topics covered are organizational models, standards and methodologies, software process improvement, knowledge management, software systems, applications and tools, information and communication technologies and processes in non-software domains (mining, automotive, aerospace, business, health care, manufacturing, etc.) with a demonstrated relationship to software engineering challenges.

"This book explores the theory and practice of educational robotics in the K-12 formal and informal educational settings, providing empirical research supporting the use of robotics for STEM learning"--Provided by publisher.

Papers from a flagship conference reflect the latest developments in the field, including work in such rapidly advancing areas as human-robot interaction and formal methods. Robotics: Science and Systems VII spans a wide spectrum of robotics, bringing together researchers working on the algorithmic or mathematical foundations of robotics, robotics applications, and analysis of robotics systems. This volume presents the proceedings of the seventh annual Robotics: Science and Systems conference, held in 2011 at the University of Southern California. The papers presented cover a wide range of topics in robotics, spanning mechanisms, kinematics, dynamics and control, human-robot interaction and human-centered systems, distributed systems, mobile systems and mobility, manipulation, field robotics, medical robotics, biological robotics, robot perception, and estimation and learning in robotic systems. The conference and its proceedings reflect not only the tremendous growth of robotics as a discipline but also the desire in the robotics community for a flagship event at which the best of the research in the field can be presented.

This volume contains the refereed proceedings of the 13th International Conference on Logic Programming and Nonmonotonic Reasoning, LPNMR 2015, held in September

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2015 in Lexington, KY, USA. The 290long and 11 short papers presented together with 3 invited talks, the paper reporting on the Answer Set Programming competition, and four papers presented by LPNMR student attendees at the doctoral consortium were carefully reviewed and selected from 60 submissions. LPNMR is a forum for exchanging ideas on declarative logic programming, nonmonotonic reasoning, and knowledge representation. The aim of the LPNMR conferences is to facilitate interactions between researchers interested in the design and implementation of logic-based programming languages and database systems, and researchers who work in the areas of knowledge representation and nonmonotonic reasoning.

This volume contains the proceedings of the 26th International Conference on Robotics in Alpe-Adria-Danube Region, RAAD 2017, held at the Polytechnic University of Turin, Italy, from June 21-23, 2017. The conference brought together academic and industrial researchers in robotics from 30 countries, the majority of them affiliated to the Alpe-Adria-Danube Region, and their worldwide partners. RAAD 2017 covered all major areas of R&D and innovation in robotics, including the latest research trends. The book provides an overview on the advances in service and industrial robotics. The topics are presented in a sequence starting from the classical robotic subjects, such as kinematics, dynamics, structures, control, and ending with the newest topics, like human-robot interaction and biomedical applications. Researchers involved in the robotic field will find this an extraordinary and up-to-date perspective on the state of the art in this area.

Focuses on the concept of open source prototyping and product development and designing sensor networks and covers IoT base applications This book will serves as a single source of introductory material and reference for programming smart computing and Internet of Things (IoT) devices using Arduino with the use of Python It covers number of comprehensive DIY experiments through which the reader can design various intelligent systems

Learn how to get started with robotics programming using Robot Operation System (ROS). Targeted for absolute beginners in ROS, Linux, and Python, this short guide shows you how to build your own robotics projects. ROS is an open-source and flexible framework for writing robotics software. With a hands-on approach and sample projects, Robot Operating System for Absolute Beginners will enable you to begin your first robot project. You will learn the basic concepts of working with ROS and begin coding with ROS APIs in both C++ and Python. What You'll Learn Install ROS Review fundamental ROS concepts Work with frequently used commands in ROS Build a mobile robot from scratch using ROS Who This Book Is For Absolute beginners with little to no programming experience looking to learn robotics programming.

Intelligence and autonomy are among the most extraordinary capacities blossomed by human evolution. Yet, endowing humanoid robots with these two crucial capabilities is still one of the biggest problems for the robotics community, despite decades of research. On the software side, algorithms for artificial intelligence are still at an embryonic stage. On the hardware side, robotic actuators are a far cry from the muscular human system in terms of flexibility and adaptability, which in turn reduces autonomy and robustness. Underneath the nature of algorithms for intelligence and technology for autonomy, the importance of efficient, scalable implementations of robust software goes without saying. Among the large variety of humanoid robots, the

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iCub has emerged as one of the most diffused research platforms. It has been developed as part of the RobotCub EU project and subsequently adopted by more than 35 laboratories worldwide. Collaborations across laboratories are encouraged by writing code and libraries openly available. As a consequence, iCub is considered to be the ideal platform for experimenting and advancing open-source software for research in several domains, ranging from motor control to cognitive systems.

Although parallel robots are known to offer many advantages with respect to accuracy, dynamics, and stiffness, major breakthroughs in industrial applications have not yet taken place. This is due to a knowledge gap preventing fast and precise execution of industrial handling and assembly tasks. This book focuses on the design, modeling, and control of innovative parallel structures as well as the integration of novel machine elements. Special attention is paid to the integration of active components into lightweight links and passive joints. In addition, new control concepts are introduced to minimize structural vibrations. Although the optimization of robot systems itself allows a reduction of cycle times, these can be further decreased by improved path planning, robot programming, and automated assembly planning concepts described by 25 contributions within this book. The content of this volume is subdivided into four main parts dealing with Modeling and Design, System Implementation, Control and Programming as well as Adaptronics and Components. This book is aimed at researchers and postgraduates working in the field of parallel robots as well as practicing engineers dealing with industrial robot development and robotic applications. This book provides comprehensive and integrated approaches for rigid and flexible object assembly. It presents comparison studies with the available force-guided robotic processes and covers contact-state modeling, scheme control strategies, and position searching algorithms. Further, it includes experimental validations for different assembly situations, including those for the assembly of industrial parts taken from the automotive industry.

This book features high-quality research papers presented at the International Conference on Applications and Techniques in Cyber Security and Digital Forensics (ICCSDF 2021), held at The NorthCap University, Gurugram, Haryana, India, during April 3–4, 2021. This book discusses the topics ranging from information security to cryptography, mobile application attacks to digital forensics, and from cyber security to blockchain. The goal of the book is to provide 360-degree view of cybersecurity to the readers which include cyber security issues, threats, vulnerabilities, novel idea, latest technique and technology, and mitigation of threats and attacks along with demonstration of practical applications. This book also highlights the latest development, challenges, methodologies as well as other emerging areas in this field. It brings current understanding of common Web vulnerabilities while maintaining awareness and knowledge of contemporary standards, practices, procedures, and methods of Open Web Application Security Project. It also expounds how to recover information after a cybercrime.

This book presents the latest scientific research related to the field of Robotics. It involves different topics such as biomedicine, energy efficiency and home automation and robotics. The book is written by technical experts and researchers from academia and industry working on robotics applications. The book could be used as supplementary material for courses related to Robotics and Domotics.

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This book highlights cutting-edge research in multidisciplinary areas of Engineering, Physics, Medicine and Healthcare presented at the 4th IRC Conference on Science, Engineering and Technology (IRC-SET 2018), which was held at the Agency for Science Technology and Research (A*STAR), Singapore. The book also contains excerpts of the speeches made by eminent personalities who attended the occasion, thereby providing a written documentation of the event.

This book presents extensive research on two main problems in robotics: the path planning problem and the multi-robot task allocation problem. It is the first book to provide a comprehensive solution for using these techniques in large-scale environments containing randomly scattered obstacles. The research conducted resulted in tangible results both in theory and in practice. For path planning, new algorithms for large-scale problems are devised and implemented and integrated into the Robot Operating System (ROS). The book also discusses the parallelism advantage of cloud computing techniques to solve the path planning problem, and, for multi-robot task allocation, it addresses the task assignment problem and the multiple traveling salesman problem for mobile robots applications. In addition, four new algorithms have been devised to investigate the cooperation issues with extensive simulations and comparative performance evaluation. The algorithms are implemented and simulated in MATLAB and Webots.

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