

Intelligent Control A Hybrid Approach Based On Fuzzy Logic Neural Networks And Genetic Algorithms Studies In Computational Intelligence

Despite the available general literature in intelligent control, there is a definite lack of knowledge and know-how in practical applications of intelligent control in drying. This book fills that gap. Intelligent Control in Drying serves as an innovative and practical guide for researchers and professionals in the field of drying technologies, providing an overview of control principles and systems used in drying operations, from classical to model-based to adaptive and optimal control. At the same time, it lays out approaches to synthesis of control systems, based on the objectives and control strategies, reflecting complexity of drying process and material under drying. This essential reference covers both fundamental and practical aspects of intelligent control, sensor fusion and dynamic optimization with respect to drying.

The goal of this book is to provide, in a friendly and refreshing manner, both theoretical concepts and practical techniques for the important and exciting field of Artificial Intelligence that can be directly applied to real-world healthcare problems. Healthcare – the final frontier. Lately, it seems like Pandora opened the box and evil was released into the world. Fortunately, there

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was one thing left in the box: hope. In recent decades, hope has been increasingly represented by Intelligent Decision Support Systems. Their continuing mission: to explore strange new diseases, to seek out new treatments and drugs, and to intelligently manage healthcare resources and patients. Hence, this book is designed for all those who wish to learn how to explore, analyze and find new solutions for the most challenging domain of all time: healthcare.

The quest to create machines that can solve problems as humans do leads us to intelligent control. This field encompasses control systems that can adapt to changes and learn to improve their actions—traits typically associated with human intelligence. In this work we seek to determine how intelligent these classes of control systems are by quantifying their level of adaptability and learning. First we describe the stages of development towards intelligent control and present a definition based on literature. Based on the key elements of this definition, we propose a novel taxonomy of intelligent control methods, which assesses the extent to which they handle uncertainties in three areas: the environment, the controller, and the goals. This taxonomy is applicable to a variety of robotic and other autonomous systems, which we demonstrate through several examples of intelligent control methods and their classifications. Looking at the spread of classifications based on this taxonomy can help researchers identify where control systems can be made more intelligent. "Advances in intelligent Control" is a collection of essays covering the latest research in the field. Based on a

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special issue of "The International Journal of Control", the book is arranged in two parts. Part one contains recent contributions of artificial neural networks to modelling and control. Part two concerns itself primarily with aspects of fuzzy logic in intelligent control, guidance and estimation, although some of the contributions either make direct equivalence relationships to neural networks or use hybrid methods where a neural network is used to develop the fuzzy rule base.

Proceedings of the European Control Conference 1995, Rome, Italy 5-8 September 1995

Induction motors are the most important workhorses in industry. They are mostly used as constant-speed drives when fed from a voltage source of fixed frequency.

Advent of advanced power electronic converters and powerful digital signal processors, however, has made possible the development of high performance, adjustable speed AC motor drives. This book aims to explore new areas of induction motor control based on artificial intelligence (AI) techniques in order to make the controller less sensitive to parameter changes. Selected AI techniques are applied for different induction motor control strategies. The book presents a practical computer simulation model of the induction motor that could be used for studying various induction motor drive operations. The control strategies explored include expert-system-based acceleration control, hybrid-fuzzy/PI two-stage control, neural-network-based direct self control, and genetic algorithm based extended Kalman filter for rotor speed estimation. There are also chapters on neural-network-based parameter estimation,

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genetic-algorithm-based optimized random PWM strategy, and experimental investigations. A chapter is provided as a primer for readers to get started with simulation studies on various AI techniques. Presents major artificial intelligence techniques to induction motor drives Uses a practical simulation approach to get interested readers started on drive development Authored by experienced scientists with over 20 years of experience in the field Provides numerous examples and the latest research results Simulation programs available from the book's Companion Website This book will be invaluable to graduate students and research engineers who specialize in electric motor drives, electric vehicles, and electric ship propulsion. Graduate students in intelligent control, applied electric motion, and energy, as well as engineers in industrial electronics, automation, and electrical transportation, will also find this book helpful. Simulation materials available for download at www.wiley.com/go/chanmotor

This book is concerned with Intelligent Control methods and applications. The field of intelligent control has been expanded very much during the recent years and a solid body of theoretical and practical results are now available. These results have been obtained through the synergetic fusion of concepts and techniques from a variety of fields such as automatic control, systems science, computer science, neurophysiology and operational research. Intelligent control systems have to perform anthropomorphic tasks fully autonomously or interactively with the human under known or unknown and uncertain environmental conditions. Therefore the

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basic components of any intelligent control system include cognition, perception, learning, sensing, planning, numeric and symbolic processing, fault detection/repair, reaction, and control action. These components must be linked in a systematic, synergetic and efficient way. Predecessors of intelligent control are adaptive control, self-organizing control, and learning control which are well documented in the literature. Typical application examples of intelligent controls are intelligent robotic systems, intelligent manufacturing systems, intelligent medical systems, and intelligent space teleoperators. Intelligent controllers must employ both quantitative and qualitative information and must be able to cope with severe temporal and spatial variations, in addition to the fundamental task of achieving the desired transient and steady-state performance. Of course the level of intelligence required in each particular application is a matter of discussion between the designers and users. The current literature on intelligent control is increasing, but the information is still available in a sparse and disorganized way.

Soft computing embraces various methodologies for the development of intelligent systems that have been successfully applied to a large number of real-world problems. *Soft Computing in Industry* contains a collection of papers that were presented at the 6th On-line World Conference on Soft Computing in Industrial Applications that was held in September 2001. It provides a comprehensive overview of recent theoretical developments in soft computing as well as of successful industrial applications. It is divided into seven parts

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covering material on: keynote papers on various subjects ranging from computing with autopoietic systems to the effects of the Internet on education; intelligent control; classification, clustering and optimization; image and signal processing; agents, multimedia and Internet; theoretical advances; prediction, design and diagnosis. The book is aimed at researchers and professional engineers who develop and apply intelligent systems in computer engineering.

Engineering Intelligent Hybrid Multi-Agent Systems is about building intelligent hybrid systems. Included is coverage of applications and design concepts related to fusion systems, transformation systems and combination systems. These applications are in areas involving hybrid configurations of knowledge-based systems, case-based reasoning, fuzzy systems, artificial neural networks, genetic algorithms, and in knowledge discovery and data mining. Through examples and applications a synergy of these subjects is demonstrated. The authors introduce a multi-agent architectural theory for engineering intelligent associative hybrid systems. The architectural theory is described at both the task structure level and the computational level. This problem-solving architecture is relevant for developing knowledge agents and information agents. An enterprise-wide system modeling framework is outlined to facilitate forward and backward integration of systems developed in the knowledge, information, and data engineering layers of an organization. In the modeling process, software engineering aspects like agent oriented analysis, design and reuse are developed and described. Engineering Intelligent Hybrid Multi-Agent Systems is the first book in the field to provide details of a multi-agent architecture for building intelligent hybrid systems.

We describe in this book, new methods and applications of

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hybrid intelligent systems using soft computing techniques.

Soft Computing (SC) consists of several intelligent computing paradigms, including fuzzy logic, neural networks, and evolutionary algorithms, which can be used to produce powerful hybrid intelligent systems. The book is organized in five main parts, which contain a group of papers around a similar subject. The first part consists of papers with the main theme of intelligent control, which are basically papers that use hybrid systems to solve particular problems of control. The second part contains papers with the main theme of pattern recognition, which are basically papers using soft computing techniques for achieving pattern recognition in different applications. The third part contains papers with the themes of intelligent agents and social systems, which are papers that apply the ideas of agents and social behavior to solve real-world problems. The fourth part contains papers that deal with the hardware implementation of intelligent systems for solving particular problems. The fifth part contains papers that deal with modeling, simulation and optimization for real-world applications.

This book presents recent advances on the design of intelligent systems based on fuzzy logic, neural networks and nature-inspired optimization and their application in areas such as, intelligent control and robotics, pattern recognition, time series prediction and optimization of complex problems. The book is organized in eight main parts, which contain a group of papers around a similar subject. The first part consists of papers with the main theme of theoretical aspects of fuzzy logic, which basically consists of papers that propose new concepts and algorithms based on fuzzy systems. The second part contains papers with the main theme of neural networks theory, which are basically papers dealing with new concepts and algorithms in neural networks. The third part contains papers describing applications of neural networks in

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diverse areas, such as time series prediction and pattern recognition. The fourth part contains papers describing new nature-inspired optimization algorithms. The fifth part presents diverse applications of nature-inspired optimization algorithms. The sixth part contains papers describing new optimization algorithms. The seventh part contains papers describing applications of fuzzy logic in diverse areas, such as time series prediction and pattern recognition. Finally, the eighth part contains papers that present enhancements to meta-heuristics based on fuzzy logic techniques.

The increasing complexity of space vehicles such as satellites, and the cost reduction measures that have affected satellite operators are increasingly driving the need for more autonomy in satellite diagnostics and control systems.

Current methods for detecting and correcting anomalies onboard the spacecraft as well as on the ground are primarily manual and labor intensive, and therefore, tend to be slow.

Operators inspect telemetry data to determine the current satellite health. They use various statistical techniques and models, but the analysis and evaluation of the large volume of data still require extensive human intervention and expertise that is prone to error. Furthermore, for spacecraft and most of these satellites, there can be potentially unduly long delays in round-trip communications between the ground station and the satellite. In this context, it is desirable to have onboard fault-diagnosis system that is capable of detecting, isolating, identifying or classifying faults in the system without the involvement and intervention of operators. Toward this end, the principle goal here is to improve the efficiency, accuracy, and reliability of the trend analysis and diagnostics techniques through utilization of intelligent-based and hybrid-based methodologies.

This book describes in a detailed fashion the application of hybrid intelligent systems using soft computing techniques for

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intelligent control and mobile robotics. Soft Computing (SC) consists of several intelligent computing paradigms, including fuzzy logic, neural networks, and bio-inspired optimization algorithms, which can be used to produce powerful hybrid intelligent systems. The prudent combination of SC techniques can produce powerful hybrid intelligent systems that are capable of solving real-world problems. This is illustrated in this book with a wide range of applications, with particular emphasis in intelligent control and mobile robotics. The book is organized in five main parts, which contain a group of papers around a similar subject. The first part consists of papers with the main theme of theory and algorithms, which are basically papers that propose new models and concepts, which can be the basis for achieving intelligent control and mobile robotics. The second part contains papers with the main theme of intelligent control, which are basically papers using bio-inspired techniques, like evolutionary algorithms and neural networks, for achieving intelligent control of non-linear plants. The third part contains papers with the theme of optimization of fuzzy controllers, which basically consider the application of bio-inspired optimization methods to automate the de-sign process of optimal type-1 and type-2 fuzzy controllers. The fourth part contains papers that deal with the application of SC techniques in times series prediction and intelligent agents. The fifth part contains papers with the theme of computer vision and robotics, which are papers considering soft computing methods for applications related to vision and robotics.

Investigating the ways in which police practices have evolved in relation to labour strikes and protests, Intelligent Control examines the means by which police forces have developed more coercive and consent-based approaches to regulating social unrest.

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This book describes the latest findings related to fuzzy techniques, discussing applications in control, economics, education, humor studies, industrial engineering, linguistics, management, marketing, medicine and public health, military engineering, robotics, ship design, sports, transportation, and many other areas. It also presents recent fuzzy-related algorithms and theoretical results that can be used in other application areas. Featuring selected papers from the Joint World Congress of the International Fuzzy Systems Association (IFSA) and the Annual Conference of the North American Fuzzy Information Processing Society (NAFIPS) IFSA-NAFIPS'2019, held in Lafayette, Louisiana, USA, on June 18–21, 2019, the book is of interest to practitioners wanting to use fuzzy techniques to process imprecise expert knowledge. It is also a valuable resource for researchers wishing to extend the ideas from these papers to new application areas, for graduate students and for anyone else interested in problems involving fuzziness and uncertainty. The two-volume set LNAI 7629 and LNAI 7630 constitutes the refereed proceedings of the 11th Mexican International Conference on Artificial Intelligence, MICAI 2012, held in San Luis Potosí, Mexico, in October/November 2012. The 80 revised papers presented were carefully reviewed and selected from 224 submissions. The second volume includes 40 papers focusing on soft computing. The papers are organized in the following topical sections: natural language processing; evolutionary and nature-inspired metaheuristic algorithms; neural networks and hybrid intelligent systems; fuzzy systems and probabilistic models in decision making. This book presents state-of-the-art research advances in the field of biologically inspired cooperative control theories and their applications. It describes various biologically inspired cooperative control and optimization approaches and highlights real-world examples in complex industrial

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processes. Multidisciplinary in nature and closely integrating theory and practice, the book will be of interest to all university researchers, control engineers and graduate students in intelligent systems and control who wish to learn the core principles, methods, algorithms, and applications.

Waste Biorefinery: Value Addition through Resources Utilization provides scientific and technical information surrounding the most advanced and innovative processing technologies used for the conversion of biogenic waste to biofuels, energy products and biochemicals. The book covers recent developments and achievements in the field of biochemical, thermo-chemical and hybrid methods and the necessities and potentials generated by different kinds of residual streams, including biomass in presumably more decentralized biorefineries. An assortment of case-studies from developing and developed countries illustrate the topics presented, covering energy, chemicals, fuels, food for animal recovery from different waste matrices, and more. Finally, the advantages and limitations of different technologies are discussed, considering local energy demand, government policies, environmental impacts and education in bioenergy.

This book will serve as an excellent resource for science graduates, chemical engineers, environmental engineers, biotechnologists and industrial experts in these areas.

Provides information on the most advanced and innovative processes for biomass conversion
Covers information on biochemical and thermochemical processes and product developments surrounding the principles of biorefining

Presents information on the integration of processes and technologies for the production of biofuels, energy products and biochemicals

As robotic systems make their way into standard practice, they have opened the door to a wide spectrum of complex applications. Such applications usually demand that the

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robots be highly intelligent. Future robots are likely to have greater sensory capabilities, more intelligence, higher levels of manual dexterity, and adequate mobility, compared to humans. In order to ensure high-quality control and performance in robotics, new intelligent control techniques must be developed, which are capable of coping with task complexity, multi-objective decision making, large volumes of perception data and substantial amounts of heuristic information. Hence, the pursuit of intelligent autonomous robotic systems has been a topic of much fascinating research in recent years. On the other hand, as emerging technologies, Soft Computing paradigms consisting of complementary elements of Fuzzy Logic, Neural Computing and Evolutionary Computation are viewed as the most promising methods towards intelligent robotic systems. Due to their strong learning and cognitive ability and good tolerance of uncertainty and imprecision, Soft Computing techniques have found wide application in the area of intelligent control of robotic systems.

This volume presents some recent and principal developments related to computational intelligence and optimization methods in control. Theoretical aspects and practical applications of control engineering are covered by 14 self-contained contributions. Additional gems include the discussion of future directions and research perspectives designed to add to the reader's understanding of both the challenges faced in control engineering and the insights into the developing of new techniques. With the knowledge obtained, readers are encouraged to determine the appropriate control method for specific applications. This book presents recent advances on hybrid intelligent systems using soft computing techniques for intelligent control and robotics, pattern recognition, time series prediction and optimization of complex problems. Soft

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Computing (SC) consists of several intelligent computing paradigms, including fuzzy logic, neural networks, and bio-inspired optimization algorithms, which can be used to produce powerful hybrid intelligent systems. The book is organized in five main parts, which contain groups of papers around a similar subject. The first part consists of papers with the main theme of hybrid intelligent systems for control and robotics, which are basically state of the art papers that propose new models and concepts, which can be the basis for achieving intelligent control and mobile robotics. The second part contains papers with the main theme of hybrid intelligent systems for pattern recognition and time series prediction, which are basically papers using nature-inspired techniques, like evolutionary algorithms, fuzzy logic and neural networks, for achieving efficient pattern recognition or time series prediction. The third part contains papers with the theme of bio-inspired and genetic optimization methods, which basically consider the proposal of new methods and applications of bio-inspired optimization to solve complex optimization of real problems. The fourth part contains papers that deal with the application of intelligent optimization techniques in real world problems in scheduling, planning and manufacturing. The fifth part contains papers with the theme of evolutionary methods and intelligent computing, which are papers considering soft computing methods for applications related to diverse areas, such as natural language processing, recommending systems and optimization. In industrial engineering and manufacturing, control of individual processes and systems is crucial to developing a quality final product. Rapid developments in technology are pioneering new techniques of research in control and automation with multi-disciplinary applications in electrical, electronic, chemical, mechanical, aerospace, and instrumentation engineering. The Handbook of Research on

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Advanced Intelligent Control Engineering and Automation presents the latest research into intelligent control technologies with the goal of advancing knowledge and applications in various domains. This text will serve as a reference book for scientists, engineers, and researchers, as it features many applications of new computational and mathematical tools for solving complicated problems of mathematical modeling, simulation, and control.

This book is divided into three parts. The first part, ?Mathematical Tools and New Developments?, provides basic tools to treat fuzzy set theory, rough set theory, fuzzy control, fuzzy modelling, decision support systems, and related applications. The second part, ?Intelligent Engineering Applications?, reports on engineering problems such as man-machine interface, risk analysis, image processing, robotics, knowledge-based engineering, expert systems, process control integration, diagnosis, measurements and interpretation by intelligent techniques and soft computing used for general engineering applications. The third part, ?Nuclear Engineering Applications?, concentrates on nuclear applications and covers several topics such as nuclear energy, nuclear safety assessment, radioactive waste management, nuclear measurements, nuclear safeguards, nuclear reactor operation, reactor controller design, fuel reload pattern design, signal validation, nuclear power plants, and optimizations in nuclear applications.

Intelligent Control A Hybrid Approach Based on Fuzzy Logic, Neural Networks and Genetic Algorithms Springer

We describe in this book, new methods for intelligent manufacturing using soft computing techniques and fractal theory. Soft Computing (SC) consists of several computing paradigms, including fuzzy logic, neural networks, and genetic algorithms, which can be used to produce powerful

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hybrid intelligent systems. Fractal theory provides us with the mathematical tools to understand the geometrical complexity of natural objects and can be used for identification and modeling purposes. Combining SC techniques with fractal theory, we can take advantage of the "intelligence" provided by the computer methods and also take advantage of the descriptive power of the fractal mathematical tools. Industrial manufacturing systems can be considered as non-linear dynamical systems, and as a consequence can have highly complex dynamic behaviors. For this reason, the need for computational intelligence in these manufacturing systems has now been well recognized. We consider in this book the concept of "intelligent manufacturing" as the application of soft computing techniques and fractal theory for achieving the goals of manufacturing, which are production planning and control, monitoring and diagnosis of faults, and automated quality control. As a prelude, we provide a brief overview of the existing methodologies in Soft Computing. We then describe our own approach in dealing with the problems in achieving intelligent manufacturing. Our particular point of view is that to really achieve intelligent manufacturing in real-world applications we need to use SC techniques and fractal theory.

Intelligent Control considers non-traditional modelling and control approaches to nonlinear systems. Fuzzy logic, neural networks and evolutionary computing techniques are the main tools used. The book presents a modular switching fuzzy logic controller where a PD-type fuzzy controller is executed first followed by a PI-type fuzzy controller thus improving the performance of the controller compared with a PID-type fuzzy controller. The advantage of the switching-type fuzzy controller is that it uses one rule-base thus minimises the rule-base during execution. A single rule-base is developed by merging the membership functions for

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change of error of the PD-type controller and sum of error of the PI-type controller. Membership functions are then optimized using evolutionary algorithms. Since the two fuzzy controllers were executed in series, necessary further tuning of the differential and integral scaling factors of the controller is then performed. Neural-network-based tuning for the scaling parameters of the fuzzy controller is then described and finally an evolutionary algorithm is applied to the neurally-tuned-fuzzy controller in which the sigmoidal function shape of the neural network is determined. The important issue of stability is addressed and the text demonstrates empirically that the developed controller was stable within the operating range. The text concludes with ideas for future research to show the reader the potential for further study in this area. Intelligent Control will be of interest to researchers from engineering and computer science backgrounds working in the intelligent and adaptive control.

This book constitutes the refereed proceedings of the 9th International Conference on Bioinspired Optimization Methods and Their Applications, BIOMA 2020, held in Brussels, Belgium, in November 2020. The 24 full papers presented in this book were carefully reviewed and selected from 68 submissions. The papers in this BIOMA proceedings specialized in bioinspired algorithms as a means for solving the optimization problems and came in two categories: theoretical studies and methodology advancements on the one hand, and algorithm adjustments and their applications on the other. Due to the Corona pandemic BIOMA 2020 was held as a virtual event.

This book describes the latest advances in fuzzy logic, neural networks and optimization algorithms, as well as their hybrid combinations, and their applications in areas such as: intelligent control and robotics, pattern recognition, medical diagnosis, time series prediction, and optimization of complex

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problems. The book is divided into five main parts. The first part proposes new concepts and algorithms based on type-1 and type-2 fuzzy logic and their applications; the second explores new concepts and algorithms in neural networks and fuzzy logic applied to recognition. The third part examines the theory and practice of meta-heuristics in various areas of application, while the fourth highlights diverse applications of fuzzy logic, neural networks and hybrid intelligent systems in medical contexts. Finally, the fifth part focuses on applications of fuzzy logic, neural networks and meta-heuristics to robotics problems.

Intelligent Control of Connected Plug-in Hybrid Electric Vehicles presents the development of real-time intelligent control systems for plug-in hybrid electric vehicles, which involves control-oriented modelling, controller design, and performance evaluation. The controllers outlined in the book take advantage of advances in vehicle communications technologies, such as global positioning systems, intelligent transportation systems, geographic information systems, and other on-board sensors, in order to provide look-ahead trip data. The book contains simple and efficient models and fast optimization algorithms for the devised controllers to address the challenge of real-time implementation in the design of complex control systems. Using the look-ahead trip information, the authors of the book propose intelligent optimal model-based control systems to minimize the total energy cost, for both grid-derived electricity and fuel. The multilayer intelligent control system proposed consists of trip planning, an ecological cruise controller, and a route-based energy management system. An algorithm that is designed to take advantage of previewed trip information to optimize battery depletion profiles is presented in the book. Different control strategies are compared and ways in which connecting vehicles via vehicle-to-vehicle communication can

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improve system performance are detailed. Intelligent Control of Connected Plug-in Hybrid Electric Vehicles is a useful source of information for postgraduate students and researchers in academic institutions participating in automotive research activities. Engineers and designers working in research and development for automotive companies will also find this book of interest. Advances in Industrial Control reports and encourages the transfer of technology in control engineering. The rapid development of control technology has an impact on all areas of the control discipline. The series offers an opportunity for researchers to present an extended exposition of new work in all aspects of industrial control.

Hybrid Computational Intelligence: Challenges and Utilities is a comprehensive resource that begins with the basics and main components of computational intelligence. It brings together many different aspects of the current research on HCI technologies, such as neural networks, support vector machines, fuzzy logic and evolutionary computation, while also covering a wide range of applications and implementation issues, from pattern recognition and system modeling, to intelligent control problems and biomedical applications. The book also explores the most widely used applications of hybrid computation as well as the history of their development. Each individual methodology provides hybrid systems with complementary reasoning and searching methods which allow the use of domain knowledge and empirical data to solve complex problems. Provides insights into the latest research trends in hybrid intelligent algorithms and architectures Focuses on the application of hybrid intelligent techniques for pattern mining and recognition, in big data analytics, and in human-computer interaction Features hybrid intelligent applications in biomedical engineering and healthcare informatics

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In recent years, intelligent control has emerged as one of the most active and fruitful areas of research and development. Until now, however, there has been no comprehensive text that explores the subject with focus on the design and analysis of biological and industrial applications. Intelligent Control Systems Using Soft Computing Methodologies does all that and more. Beginning with an overview of intelligent control methodologies, the contributors present the fundamentals of neural networks, supervised and unsupervised learning, and recurrent networks. They address various implementation issues, then explore design and verification of neural networks for a variety of applications, including medicine, biology, digital signal processing, object recognition, computer networking, desalination technology, and oil refinery and chemical processes. The focus then shifts to fuzzy logic, with a review of the fundamental and theoretical aspects, discussion of implementation issues, and examples of applications, including control of autonomous underwater vehicles, navigation of space vehicles, image processing, robotics, and energy management systems. The book concludes with the integration of genetic algorithms into the paradigm of soft computing methodologies, including several more industrial examples, implementation issues, and open problems and open problems related to intelligent control technology. Suitable as a textbook or a reference, Intelligent Control Systems explores recent advances in the field from both the theoretical and the practical viewpoints. It also integrates intelligent control design methodologies to give designers a set of flexible, robust controllers and provide students with a tool for solving the examples and exercises within the book.

This book describes recent advances on hybrid intelligent systems using soft computing techniques for diverse areas of application, such as intelligent control and robotics, pattern

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recognition, time series prediction and optimization complex problems. Soft Computing (SC) consists of several intelligent computing paradigms, including fuzzy logic, neural networks and bio-inspired optimization algorithms, which can be used to produce powerful hybrid intelligent systems. The book is organized in five main parts, which contain a group of papers around a similar subject. The first part consists of papers with the main theme of type-2 fuzzy logic, which basically consists of papers that propose new models and applications for type-2 fuzzy systems. The second part contains papers with the main theme of bio-inspired optimization algorithms, which are basically papers using nature-inspired techniques to achieve optimization of complex optimization problems in diverse areas of application. The third part contains papers that deal with new models and applications of neural networks in real world problems. The fourth part contains papers with the theme of intelligent optimization methods, which basically consider the proposal of new methods of optimization to solve complex real world optimization problems. The fifth part contains papers with the theme of evolutionary methods and intelligent computing, which are papers considering soft computing methods for applications related to diverse areas, such as natural language processing, recommending systems and optimization.

"Recent Advances in Intelligent Control Systems"

gathers contributions from workers around the world and presents them in four categories according to the style of control employed: fuzzy control; neural control; fuzzy neural control; and intelligent control. The contributions illustrate the interdisciplinary antecedents of intelligent control and contrast its results with those of more traditional control methods. A variety of design examples, drawn primarily from robotics and

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mechatronics but also representing process and production engineering, large civil structures, network flows, and others, provide instances of the application of computational intelligence for control. Presenting state-of-the-art research, this collection will be of benefit to researchers in automatic control, automation, computer science (especially artificial intelligence) and mechatronics while graduate students and practicing control engineers working with intelligent systems will find it a good source of study material.

This book discusses systematic designs of stable adaptive fuzzy logic controllers employing hybridizations of Lyapunov strategy-based approaches/H[∞] theory-based approaches and contemporary stochastic optimization techniques. The text demonstrates how candidate stochastic optimization techniques like Particle swarm optimization (PSO), harmony search (HS) algorithms, covariance matrix adaptation (CMA) etc. can be utilized in conjunction with the Lyapunov theory/H[∞] theory to develop such hybrid control strategies. The goal of developing a series of such hybridization processes is to combine the strengths of both Lyapunov theory/H[∞] theory-based local search methods and stochastic optimization-based global search methods, so as to attain superior control algorithms that can simultaneously achieve desired asymptotic performance and provide improved transient responses. The book also demonstrates how these intelligent adaptive control algorithms can be effectively utilized in real-life applications such as in temperature control for air heater systems with transportation delay, vision-based

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navigation of mobile robots, intelligent control of robot manipulators etc.

"This book focuses on the latest innovations in the process of manufacturing in engineering"--Provided by publisher.

This book provides a hybrid approach to fault detection and diagnostics. It presents a detailed analysis related to practical applications of the fault detection and diagnostics framework, and highlights recent findings on power plant nonlinear model identification and fault diagnostics. The effectiveness of the methods presented is tested using data acquired from actual cogeneration and cooling plants (CCPs). The models presented were developed by applying Neuro-Fuzzy (NF) methods. The book offers a valuable resource for researchers and practicing engineers alike.

This book describes recent advances on fuzzy logic, neural networks and optimization algorithms, as well as their hybrid combinations, and their application in areas such as intelligent control and robotics, pattern recognition, medical diagnosis, time series prediction and optimization of complex problems. The book contains a collection of papers focused on hybrid intelligent systems based on soft computing. There are some papers with the main theme of type-1 and type-2 fuzzy logic, which basically consists of papers that propose new concepts and algorithms based on type-1 and type-2 fuzzy logic and their applications. There are also some papers that present theory and practice of meta-heuristics in different areas of application. Another group of papers describes diverse applications of fuzzy

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logic, neural networks and hybrid intelligent systems in medical applications. There are also some papers that present theory and practice of neural networks in different areas of application. In addition, there are papers that present theory and practice of optimization and evolutionary algorithms in different areas of application. Finally, there are some papers describing applications of fuzzy logic, neural networks and meta-heuristics in pattern recognition problems.

We describe in this book, hybrid intelligent systems based mainly on type-2 fuzzy logic for intelligent control. Hybrid intelligent systems combine several intelligent computing paradigms, including fuzzy logic, and bio-inspired optimization algorithms, which can be used to produce powerful automatic control systems. The book is organized in three main parts, which contain a group of chapters around a similar subject. The first part consists of chapters with the main theme of theory and design algorithms, which are basically chapters that propose new models and concepts, which can be the basis for achieving intelligent control with interval type-2 fuzzy logic. The second part of the book is comprised of chapters with the main theme of evolutionary optimization of type-2 fuzzy systems in intelligent control with the aim of designing optimal type-2 fuzzy controllers for complex control problems in diverse areas of application, including mobile robotics, aircraft dynamics systems and hardware implementations. The third part of the book is formed with chapters dealing with the theme of bio-inspired optimization of type-2 fuzzy systems in intelligent control, which includes the application of

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particle swarm intelligence and ant colony optimization algorithms for obtaining optimal type-2 fuzzy controllers. This volume introduces new approaches in intelligent control area from both the viewpoints of theory and application. It consists of eleven contributions by prominent authors from all over the world and an introductory chapter. This volume is strongly connected to another volume entitled "New Approaches in Intelligent Image Analysis" (Eds. Roumen Kountchev and Kazumi Nakamatsu). The chapters of this volume are self-contained and include summary, conclusion and future works. Some of the chapters introduce specific case studies of various intelligent control systems and others focus on intelligent theory based control techniques with applications. A remarkable specificity of this volume is that three chapters are dealing with intelligent control based on paraconsistent logics.

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