

Industrial Robotics Technology Programming And Applications Mikell P Groover

This book covers a wide range of topics relating to advanced industrial robotics, sensors and automation technologies. Although being highly technical and complex in nature, the papers presented in this book represent some of the latest cutting edge technologies and advancements in industrial robotics technology. This book covers topics such as networking, properties of manipulators, forward and inverse robot arm kinematics, motion path-planning, machine vision and many other practical topics too numerous to list here. The authors and editor of this book wish to inspire people, especially young ones, to get involved with robotic and mechatronic engineering technology and to develop new and exciting practical applications, perhaps using the ideas and concepts presented herein.

Robotics is an applied engineering science that has been referred to as a combination of machine tool technology and computer science. It includes diverse fields such as machine design, control theory, microelectronics, computer programming, artificial intelligence, human factors and production theory. The present book provides a comprehensive introduction to robotics. The book covers a fair amount of kinematics and dynamics of the robots. It also covers the sensors and actuators used in robotics system. This book will be useful for mechanical, electrical, electronics and computer engineering students. Key Features Latest technological developments in robotics * Robotic classifications, robot programming, robotic sensors and actuators. * Kinematics and dynamic analysis of the Robot * Modular systems in

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robotics Advances in Robotics systems * Fuzzy logic control in Robotic systems * Biped robot * Bio-mimetic robot * Robot safety and layout * Robot calibration Numerical examples Relative merits and demerits of different robot systems About Author: Appu Kuttan KK is working as professor in Mechanical Engineering, NITK, Surathkal. He has worked as Head of the department during 2000-2004. Eleven Ph.D students have completed their degree under his guidance. He has contributed more than one hundred papers in international and national journals and conferences. He has 25 years of teaching and 22 years of research experience. His areas of interest are CAD/CAM, Robotics, Mechatronics, Finite element method, Smart materials and Control engineering

Providing a broad, semi-detailed review of various robotic applications based on process, this text incorporates existing articles, as well as the author's own knowledge to describe points of interest and background.

The purpose of this book is to present an introduction to the multidisciplinary field of automation and robotics for industrial applications. The companion files include numerous video tutorial projects and a chapter on the history and modern applications of robotics. The book initially covers the important concepts of hydraulics and pneumatics and how they are used for automation in an industrial setting. It then moves to a discussion of circuits and using them in hydraulic, pneumatic, and fluidic design. The latter part of the book deals with electric and electronic controls in automation and final chapters are devoted to robotics, robotic programming, and applications of robotics in industry. eBook Customers: Companion files are available for downloading with order number/proof of purchase by writing to the publisher at info@merclearning.com. Features: * Begins with introductory concepts on automation,

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hydraulics, and pneumatics * Covers sensors, PLC's, microprocessors, transfer devices and feeders, robotic sensors, robotic grippers, and robot programming

Over the past five years robot vision has emerged as a subject area with its own identity. A text based on the proceedings of the Symposium on Computer Vision and Sensor-based Robots held at the General Motors Research Laboratories, Warren, Michigan in 1978, was published by Plenum Press in 1979. This book, edited by George G. Dodd and Lothar Rosso!, probably represented the first identifiable book covering some aspects of robot vision. The subject of robot vision and sensory controls (RoViSeC) occupied an entire international conference held in the Hilton Hotel in Stratford, England in May 1981. This was followed by a second RoViSeC held in Stuttgart, Germany in November 1982. The large attendance at the Stratford conference and the obvious interest in the subject of robot vision at international robot meetings, provides the stimulus for this current collection of papers. Users and researchers entering the field of robot vision for the first time will encounter a bewildering array of publications on all aspects of computer vision of which robot vision forms a part. It is the grey area dividing the different aspects of computer vision which is not easy to identify. Even those involved in research sometimes find difficulty in separating the essential differences between vision for automated inspection and vision for robot applications. Both of these are to some extent applications of pattern recognition with the underlying philosophy of each defining the techniques used.

In the modern world, highly repetitive and tiresome tasks are being delegated to machines. The demand for industrial robots is growing not only because of the need to improve production efficiency and the quality of the end products, but also due to rising employment

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costs and a shortage of skilled professionals. The industrial robot market is projected to grow by 16% year-on-year in the immediate future. The industry's progressing automation is increasing the demand for specialists who can operate robots. If you would like to join this sought-after and well-paid professional group, it's time to learn how to operate and program robots using modern methods. This book provides all the information you will need to enter the industry without spending money on training or looking for someone willing to introduce you to the world of robotics. You will learn about all aspects of programming and implementing robots in a company. The book consists of four parts: general introduction to robotics for non-technical people; part two describes industry robotisation; part three depicts the principles and methods of programming robots; the final part touches upon the safety of industrial robots and cobots. Are you a student of a technical faculty, or even a manager of a plant who would like to robotise production? If you are interested in this subject, you won't find a better book!

Industrial Robotics Fundamentals is an introduction to the principles of industrial robotics, related systems, and applications. The technical aspects of industrial robotics are covered in four units: Principles of Robotics; Power Supplies and Movement Systems; Sensing and End-of-Arm Tooling; and Control Systems and Maintenance. This 4th edition reflects new evolutions in the industrial robotics field, including coverage of Industry 4.0, the Industrial Internet of Things (IIoT), and Light Detection and Ranging (LiDAR). Special features address pioneers in the field, careers in the industry, and applications of technology, including robot lawnmowers and machine-to-machine communications.

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The PLC is the device at the heart of most automated control systems and instrumentation in industry. The bestselling first edition of this book was the first user guide and tutorial to the standard IEC 1131-3; this revised edition includes

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all IEC proposed amendments and corrections, as agreed by the IEC working group. It accurately describes the languages and concepts, and interprets the standard for practical implementation and applications.

Robotics: Theory and Industrial Applications is an introduction to the principles of industrial robotics, related systems, and applications. This text is a comprehensive tool in learning the technical aspects of robotics and includes coverage of power supply systems, degrees of freedom, programming methods, sensors, end effectors, implementation planning, and system maintenance. Each chapter begins with an outline of topics, learning objectives, and a listing of technical terms. The key concepts are discussed using a systems approach to enhance student learning. The second edition is updated with full-color illustrations and photos that reflect changes in both the field of robotics and technology in general. The content has been revised to keep pace with robotic technology and reorganized to maximize student comprehension. Various features throughout the text address special interest topics, including pioneers in the field of robotics, careers in robotics, and exciting applications of robotic technology. This bundle includes a copy of the Student Text and an Online Text (6-Year Classroom Subscription). Students can instantly access the Online Text with browser-based devices, including iPads, netbooks, PCs, and Mac

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* Fun and easy-to-grasp, yet based on solid programming principles of object-oriented programming * Visually oriented—teaches programming by commanding turtle to move through loops, variables, procedures, and AI * Suitable for any reader, from curious children to adults, who'd like a gentle, methodical approach to core programming concepts

Micro-Facts has proved to be a useful ready reference for practising food microbiologists and others concerned with ensuring the microbiological safety of foods. Micro-Facts 6th Edition is an invaluable tool for food microbiologists everywhere, as a source book of information relevant to the prevention of food-poisoning hazards worldwide.

Written for senior level or first year graduate level robotics courses, this text includes material from traditional mechanical engineering, control theoretical material and computer science. It includes coverage of rigid-body transformations and forward and inverse positional kinematics.

Comprehensive and extensively illustrated, this outstanding reference provides a unique overview of robotics, its hardware, various types, their functions, social

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issues surrounding their use, and their future in industry.

Industrial Robots Programming focuses on designing and building robotic manufacturing cells, and explores the capabilities of today's industrial equipment as well as the latest computer and software technologies. Special attention is given to the input devices and systems that create efficient human-machine interfaces, and how they help non-technical personnel perform necessary programming, control, and supervision tasks. Drawing upon years of practical experience and using numerous examples and illustrative applications, J. Norberto Pires covers robotics programming as it applies to: The current industrial robotic equipment including manipulators, control systems, and programming environments. Software interfaces that can be used to develop distributed industrial manufacturing cells and techniques which can be used to build interfaces between robots and computers. Real-world applications with examples designed and implemented recently in the lab. Industrial Robots Programming has been selected for indexing by Scopus. For more information about Industrial Robotics, please find the author's Industrial Robotics collection at the iTunesU University of Coimbra channel.

The authors, who have over four decades of experience in the industry and academia, have enhanced the coverage of the work by comprehensively adding

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the latest developments in the field. New topics include robot dynamics, drives, actuator systems, mechatronics, modeling of intelligent systems based on soft computing techniques, CAD/CAM based numerical control part programming, robotic assembly in CIM environment and other industrial applications.

In this book, a new approach to the Industry 4.0 revolution is given. New policies and challenges appear and education in robotics also needs to be adapted to this new era. Together with new factory conceptualization, novel applications introduce new paradigms and new solutions to old problems. The factory opens its walls and outdoor applications are solved with new robot morphologies and new sensors that were unthinkable before Industry 4.0 era. This book presents nine chapters that propose a new outlook for an unstoppable revolution in industrial robotics, from drones to software robots

The New York Times-bestselling guide to how automation is changing the economy, undermining work, and reshaping our lives Winner of Best Business Book of the Year awards from the Financial Times and from Forbes "Lucid, comprehensive, and unafraid...;an indispensable contribution to a long-running argument."--Los Angeles Times What are the jobs of the future? How many will there be? And who will have them? As technology continues to accelerate and machines begin taking care of themselves, fewer people will be necessary.

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Artificial intelligence is already well on its way to making "good jobs" obsolete: many paralegals, journalists, office workers, and even computer programmers are poised to be replaced by robots and smart software. As progress continues, blue and white collar jobs alike will evaporate, squeezing working- and middle-class families ever further. At the same time, households are under assault from exploding costs, especially from the two major industries-education and health care-that, so far, have not been transformed by information technology. The result could well be massive unemployment and inequality as well as the implosion of the consumer economy itself. The past solutions to technological disruption, especially more training and education, aren't going to work. We must decide, now, whether the future will see broad-based prosperity or catastrophic levels of inequality and economic insecurity. Rise of the Robots is essential reading to understand what accelerating technology means for our economic prospects-not to mention those of our children-as well as for society as a whole. Master the principles and practices of industrial robotics Written by a pair of technology experts and accomplished educators, this comprehensive resource provides a solid foundation in applied industrial robotics and robot technology. You will get straightforward explanations of the latest components, techniques, and capabilities along with practical examples and detailed illustrations. The book

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takes a look at the entire field of robotics?from design and production to deployment, operation, and maintenance. Valuable appendices provide information on specific robot models, pendants, and controllers. Robots and Robotics: Principles, Systems and Industrial Applications covers:

- Robot and robotics fundamentals
- Identification of components
- Robot parts and robotic motion capabilities
- Programs, programming languages, and microprocessors
- Drive systems, pumps, motors, and sensors
- Control methods
- Industrial applications
- Specifications and capabilities
- Troubleshooting and maintenance
- Emerging technologies and the future of robotics

Gain experience of building a next-generation collaboration robot Key Features Get up and running with the fundamentals of robotic programming Program a robot using Python and the Raspberry Pi 3 Learn to build a smart robot with interactive and AI-enabled behaviors Book Description We live in an age where the most difficult human tasks are now automated. Smart and intelligent robots, which will perform different tasks precisely and efficiently, are the requirement of the hour. A combination of Raspberry Pi and Python works perfectly when making these kinds of robots. Learn Robotics Programming starts by introducing you to the basic structure of a robot, along with how to plan, build, and program it. As you make your way through the book, you will gradually progress to adding

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different outputs and sensors, learning new building skills, and writing code for interesting behaviors with sensors. You'll also be able to update your robot, and set up web, phone, and Wi-Fi connectivity in order to control it. By the end of the book, you will have built a clever robot that can perform basic artificial intelligence (AI) operations. What you will learn Configure a Raspberry Pi for use in a robot Interface motors and sensors with a Raspberry Pi Implement code to make interesting and intelligent robot behaviors Understand the first steps in AI behavior such as speech recognition visual processing Control AI robots using Wi-Fi Plan the budget for requirements of robots while choosing parts Who this book is for Learn Robotics Programming is for programmers, developers, and enthusiasts interested in robotics and developing a fully functional robot. No major experience required just some programming knowledge would be sufficient.

A comprehensive overview of robotics principles, systems, and applications This practical, straightforward guide gives readers a solid foundation in applied industrial robotics and robotics technology. The book offers start-to-finish coverage of the entire field—from robot design and production to industrial placement and operation. The latest tools and devices used in the trade are clearly explained. Robots and Robotics: Principles, Systems, and Industrial

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Applications provides hands-on instruction through concise explanations, examples, and hundreds of detailed illustrations. Free downloadable material reinforces key concepts and gives readers access to more advanced information. The book covers programming, power systems, maintenance and repair, sensors, control architecture, and much more. • Equips the reader with the concepts needed to start a career in robotics • Presented in a plain-language, easy-to-understand style • Written by a pair of experienced technical professionals and educators

As the capability and utility of robots has increased dramatically with new technology, robotic systems can perform tasks that are physically dangerous for humans, repetitive in nature, or require increased accuracy, precision, and sterile conditions to radically minimize human error. The Robotics and Automation Handbook addresses the major aspects of designing, fabricating, and enabling robotic systems and their various applications. It presents kinetic and dynamic methods for analyzing robotic systems, considering factors such as force and torque. From these analyses, the book develops several controls approaches, including servo actuation, hybrid control, and trajectory planning. Design aspects include determining specifications for a robot, determining its configuration, and utilizing sensors and actuators. The featured applications focus on how the

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specific difficulties are overcome in the development of the robotic system. With the ability to increase human safety and precision in applications ranging from handling hazardous materials and exploring extreme environments to manufacturing and medicine, the uses for robots are growing steadily. The Robotics and Automation Handbook provides a solid foundation for engineers and scientists interested in designing, fabricating, or utilizing robotic systems. The second edition of this handbook provides a state-of-the-art overview on the various aspects in the rapidly developing field of robotics. Reaching for the human frontier, robotics is vigorously engaged in the growing challenges of new emerging domains. Interacting, exploring, and working with humans, the new generation of robots will increasingly touch people and their lives. The credible prospect of practical robots among humans is the result of the scientific endeavour of a half a century of robotic developments that established robotics as a modern scientific discipline. The ongoing vibrant expansion and strong growth of the field during the last decade has fueled this second edition of the Springer Handbook of Robotics. The first edition of the handbook soon became a landmark in robotics publishing and won the American Association of Publishers PROSE Award for Excellence in Physical Sciences & Mathematics as well as the organization's Award for Engineering & Technology. The second edition of the

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handbook, edited by two internationally renowned scientists with the support of an outstanding team of seven part editors and more than 200 authors, continues to be an authoritative reference for robotics researchers, newcomers to the field, and scholars from related disciplines. The contents have been restructured to achieve four main objectives: the enlargement of foundational topics for robotics, the enlightenment of design of various types of robotic systems, the extension of the treatment on robots moving in the environment, and the enrichment of advanced robotics applications. Further to an extensive update, fifteen new chapters have been introduced on emerging topics, and a new generation of authors have joined the handbook's team. A novel addition to the second edition is a comprehensive collection of multimedia references to more than 700 videos, which bring valuable insight into the contents. The videos can be viewed directly augmented into the text with a smartphone or tablet using a unique and specially designed app. Springer Handbook of Robotics Multimedia Extension Portal: <http://handbookofrobotics.org/>

Niku offers comprehensive, yet concise coverage of robotics that will appeal to engineers. Robotic applications are drawn from a wide variety of fields. Emphasis is placed on design along with analysis and modeling. Kinematics and dynamics are covered extensively in an accessible style. Vision systems are discussed in

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detail, which is a cutting-edge area in robotics. Engineers will also find a running design project that reinforces the concepts by having them apply what they've learned.

This comprehensive textbook covers in detail the principal programmable automation technologies used in industry - the building blocks from which all automated manufacturing is developed. It is a one-stop source for developing CNC, robotics, and PLC programming skills, is replete with numerous examples, and it identifies and discusses readily available simulation software to experiment with. The text is primarily intended for undergraduate engineering technology students. Besides, anyone with a technical background and a general understanding of manufacturing and manufacturing processes will find this text useful, as well as to those who wish, simply, to study and understand the use of these technologies. The text is organized into four sections. Section One is introductory: Chapter 1 provides some background on manufacturing and defines programmable automation. Chapter 2 explains calculation methods used to justify automation expenditures, as motivated by productivity concepts. Section Two covers computer numerical control: Chapter 3 introduces CNC technology, Chapter 4 discusses CNC programming, and Chapter 5 addresses CNC simulation. Robotics is covered in Section Three: Chapter 6 introduces robotics technology and Chapter 7 goes over both robotics programming and simulation. Section Four addresses PLCs: Chapter 8 introduces PLCs and Chapter 9 covers programming and simulation of PLCs. Finally, Chapter 10 concludes the text with a discussion of how all three technologies are brought together to create programmable automated workstations and work cells.

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INDUSTRIAL ROBOTICS delivers an introduction to the industry and basic understanding of the subjects needed for starting a career in industrial robotics. It provides a background on the history and development of industrial automation before moving into subjects such as robot mechanical unit configurations, controller architecture, and general software structure. A general overview of programming and end of arm tooling is also included. The first edition highlights three subjects not typically addressed in robotic texts -- industrial sensors, vision systems, and maintenance. Numerous general maintenance concepts help prepare students for entry into the job market. Coverage also includes the economic aspects of robots in the workplace as well as the issues of human/robot interfaces. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version.

Industrial Robots Programming focuses on designing and building robotic manufacturing cells, and explores the capabilities of today's industrial equipment as well as the latest computer and software technologies. Special attention is given to the input devices and systems that create efficient human-machine interfaces, and how they help non-technical personnel perform necessary programming, control, and supervision tasks. Drawing upon years of practical experience and using numerous examples and illustrative applications, J. Norberto Pires covers robotics programming as it applies to: The current industrial robotic equipment including manipulators, control systems, and programming environments. Software interfaces that can be used to develop distributed industrial manufacturing cells and techniques which can be used to build interfaces between robots and computers. Real-world applications with examples designed and implemented recently in the lab. For more information about Industrial Robotics,

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This monograph by Florian Röhrbein, Germano Veiga and Ciro Natale is an edited collection of 15 authoritative contributions in the area of robot technology transfer between academia and industry. It comprises three parts on Future Industrial Robotics, Robotic Grasping as well as Human-Centered Robots. The book chapters cover almost all the topics nowadays considered 'hot' within the robotics community, from reliable object recognition to dexterous grasping, from speech recognition to intuitive robot programming, from mobile robot navigation to aerial robotics, from safe physical human-robot interaction to body extenders. All contributions stem from the results of ECHORD – the European Clearing House for Open Robotics Development, a large-scale integrating project funded by the European Commission within the 7th Framework Programme from 2009 to 2013. ECHORD's two main pillars were the so-called experiments, 52 small-sized industry-driven research projects, and the structured dialog, a powerful interaction instrument between the stakeholders. The results described in this volume are expected to shed new light on innovation and technology transfer from academia to industry in the field of robotics.

This book contains a selection of articles from The 2015 World Conference on Information Systems and Technologies (WorldCIST'15), held between the 1st and 3rd of April in Funchal, Madeira, Portugal, a global forum for researchers and practitioners to present and discuss recent results and innovations, current trends, professional experiences and challenges of modern Information Systems and Technologies research, technological development and applications. The main topics covered are: Information and Knowledge Management;

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Organizational Models and Information Systems; Intelligent and Decision Support Systems; Big Data Analytics and Applications; Software Systems, Architectures, Applications and Tools; Multimedia Systems and Applications; Computer Networks, Mobility and Pervasive Systems; Human-Computer Interaction; Health Informatics; Information Technologies in Education; Information Technologies in Radio communications.

A modern and unified treatment of the mechanics, planning, and control of robots, suitable for a first course in robotics.

"This book explores the theory and practice of educational robotics in the K-12 formal and informal educational settings, providing empirical research supporting the use of robotics for STEM learning"--Provided by publisher.

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McGraw-Hill College
Industrial Robots Programming Building Applications for the Factories of the Future
Springer Science & Business Media

THE REAL THING by Isaac Asimov
Back in 1939, when I was still a teenager, I began to write (and publish) a series of stories about robots which, for the first time in science fiction, were pictured as having been deliberately engineered to do their job safely. They were not intended to be creaky Gothic menaces, nor outlets for mawkish sentiment. They were simply well-designed machines. Beginning in 1942, I crystallized this notion in what I called 'The Three Laws of Robotics' and, in 1950, nine of my robot stories were collected into a book, I,

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Robot. I did not at that time seriously believe that I would live to see robots in action and robotics becoming a booming industry Yet here we are, better yet, I am alive to see it. But then, why shouldn't they be with us? Robots fulfil an important role in industry. They do simple and repetitive jobs more steadily, more reliably, and more uncomplainingly than a human being could - or should. Does a robot displace a human being? Certainly, but he does so at a job that, simply because a robot can do it, is beneath the dignity of a human being; a job that is no more than mindless drudgery. Better and more human jobs can be found for human beings - and should.

The book presents a collection of 103 peer-reviewed articles from the Second International Conference on Intelligent Systems in Production Engineering and Maintenance (ISPEM 2018). The conference was organized by the Faculty of Mechanical Engineering and CAMT (Centre for Advanced Manufacturing Technologies), Wrocław University of Science and Technology and was held in Wrocław (Poland) on 17–18 September 2018. The conference topics included the possibility of using a wide range of intelligent methods in production engineering, presenting and discussing new solutions for innovative plants, research findings and case studies demonstrating advances in production and maintenance from the point of view of Industry 4.0 – particularly applications of

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intelligent systems, methods and tools in production engineering, maintenance, logistics, quality management, information systems and product development. The book is divided into two parts: the first includes papers related to intelligent systems in production engineering, while the second is dedicated to special sessions focusing on: 1. Computer Aided methods in Production Engineering 2. Mining 4.0 and Intelligent Mining Transportation 3. Modelling and Simulation of Production Processes 4. Multi-Faceted Modelling of Networks and Processes 5. Product Design and Product Manufacturing in Industry 4.0 This book is an excellent source of information for scientists in the field of manufacturing engineering and for top managers in production enterprises.

This book, a unique text on robotics and welding, will be bought by graduate students, and researchers and practitioners in robotics and manufacturing. Parallel Kinematic Machines (PKMs) are one of the most radical innovations in production equipment. They attempt to combine the dexterity of robots with the accuracy of machine tools to respond to several industrial needs. This book contains the proceedings of the first European-American Forum on Parallel Kinematic Machines, held in Milan, Italy from 31 August - 1 September 1998. The Forum was established to provide institutions, technology suppliers and industrial end users with an improved understanding of the real advantages to be gained

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from using PKMs. This book contributes to a mid-term strategy oriented to reduce time to market and costs, improve production flexibility and minimize environmental impacts to increase worldwide competitiveness. In particular the authors focus on enabling technologies and emerging concepts for future manufacturing applications of PKMs. Topics include: Current status of PKM R&D in Europe, the USA and Asia. Industrial requirements, roadblocks and application opportunities. Research issues and possibilities. Industrial applications and requirements.

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