

Dynamical Analysis Of Vehicle Systems Theoretical Foundations And Advanced Applications Cism International Centre For Mechanical Sciences

Dynamic Analysis of High-Speed Railway Alignment: Theory and Practice elaborates on the dynamic analysis theory and method on spatial alignment parameters of high-speed railways, revealing the interaction mechanism between vehicle-track dynamic performance and track parameters of high-speed railways. It ascertains the influence rules of track structure and track geometry on vehicle-track dynamic performance, establishes the relationship models between vehicle-track dynamic performance and curve dynamic characteristic parameters, and defines the calculation relationship between lateral acceleration of car body on curves and track parameters. This book can be used as a reference book for scientific researchers, engineering technicians and management engaged in railway engineering, and will be very helpful for railway technicians who want to learn more about route planning, design, and construction and maintenance technologies of high-speed railways. Presents the dynamic effects between the running speed of high-speed trains on curves and spatial curve technical parameters Provides dynamic analysis, theory and methods on curve parameters of high-speed railways and improves the calculation theory on spatial alignment of high-speed railways Covers minimum curve radius, transition curve length, minimum radius of vertical curve, steepest slope, minimum slope length and length of intermediate straight line

This set includes Race Car Vehicle Dynamics, and Race Car Vehicle Dynamics - Problems, Answers and Experiments. Written for the engineer as well as the race car enthusiast, Race Car Vehicle Dynamics includes much information that is not available in any other vehicle dynamics text. Truly comprehensive in its coverage of the fundamental concepts of vehicle dynamics and their application in a racing environment, this book has become the definitive reference on this topic. Although the primary focus is on the race car, the engineering fundamentals detailed are also applicable to passenger car design and engineering. Authors Bill and Doug Milliken have developed many of the original vehicle dynamics theories and principles covered in this book, including the Moment Method, "g-g" Diagram, pair analysis, lap time simulation, and tyre data normalization. The book also includes contributions from other experts in the field. Chapters cover: *The Problem Imposed by Racing *Tire Behavior *Aerodynamic Fundamentals *Vehicle Axis Systems and more. Written for the engineer as well as the race car enthusiast and students, the companion workbook to the original classic book, Race Car Vehicle Dynamics, includes: *Detailed worked solutions to all of the problems *Problems for every chapter in Race Car Vehicle Dynamics, including many new problems *The Race Car Vehicle Dynamics Program Suite (for Windows) with accompanying exercises *Experiments to try with your own vehicle *Educational appendix with additional references and course outlines *Over 90 figures and graphs This workbook is widely used as a college textbook and has been an SAE International best seller since its introduction in 1995.

This is the first book to combine classical vehicle dynamics with electronic control. The equation-based presentation of the theory behind vehicle dynamics enables readers to develop a thorough understanding of the key attribute to both a vehicle's driveability and its active safety. Supported by MATLAB tools, the key areas that affect vehicle dynamics are explored including tire mechanics, the steering system, vehicle roll, traction and braking, 4WS and vehicle dynamics, vehicle dynamics by vehicle and human control, and controllability. As a professional reference volume, this book is an essential addition to the resources available to anyone working in vehicle design and development. Written by a leading authority in the field (who himself has considerable practical experience), the book has a unique blend of theory and practice that will be of immense value in this applications based field. Get a thorough understand of why vehicles respond they way they do with a complete treatment of vehicle dynamics from theory to application Full of case studies and worked examples using MATLAB/Simulink Covers all variables of vehicle dynamics including tire and vehicle motion, control aspects, human control and external disturbances

An introduction to vehicle dynamics and the fundamentals of mathematical modeling Fundamentals of Vehicle Dynamics and Modeling is a student-focused textbook providing an introduction to vehicle dynamics, and covers the fundamentals of vehicle model development. It illustrates the process for construction of a mathematical model through the application of the equations of motion. The text describes techniques for solution of the model, and demonstrates how to conduct an analysis and interpret the results. A significant portion of the book is devoted to the classical linear dynamic models, and provides a foundation for understanding and predicting vehicle behaviour as a consequence of the design parameters. Modeling the pneumatic tire is also covered, along with methods for solving the suspension kinematics problem, and prediction of acceleration and braking performance. The book introduces the concept of multibody dynamics as applied to vehicles and provides insight into how large and high fidelity models can be constructed. It includes the development of a method suitable for computer implementation, which can automatically generate and solve the linear equations of motion for large complex models. Key features: ? Accompanied by a website hosting MATLAB® code. ? Supported by the Global Education Delivery channels. Fundamentals of Vehicle Dynamics and Modeling is an ideal textbook for senior undergraduate and graduate courses on vehicle dynamics.

Vehicle Dynamics comprehensively covers the fundamentals of vehicle dynamics with application to automotive mechatronics. It is divided into the three parts covering longitudinal, vertical and lateral dynamics and considers the application of these to modern mechatronic systems including the anti-lock braking system and dynamic stability control. It also covers driving resistances, powertrain with IC engines and converters, hybrid powertrains and wheel loads and braking process. The conflict Between safety and comfort is discussed, and dynamic behaviour, the suspension system and the electronic stability program are also all considered. Vehicle Dynamics includes exercise problems, MATLAB® codes and is accompanied by a website hosting animations.

This textbook is appropriate for senior undergraduate and first year graduate students in mechanical and automotive engineering. The contents in this book are presented at a theoretical-practical level. It explains vehicle dynamics concepts in detail, concentrating on their practical use. Related theorems and formal proofs are provided, as are real-life applications. Students, researchers and practicing engineers alike will appreciate the user-friendly presentation of a wealth of topics, most notably steering, handling, ride, and related components. This book also: Illustrates all key concepts with examples Includes exercises for each chapter Covers front, rear, and four wheel steering systems, as well as the advantages and disadvantages of different steering schemes Includes an emphasis on design throughout the text, which provides a practical, hands-on approach

This volume presents an integrated approach of the common fundamentals of rail and road vehicles based on multibody system dynamics, rolling wheel contact and control system design. The methods presented allow an efficient and reliable analysis of the resulting state equations. The book provides also a better understanding of the basic physical phenomena of vehicle dynamics. Particular attention is paid to developments of future rail and road vehicles including motorcycles.

Dynamics of Railway Vehicle Systems offers a comprehensive and analytical treatment of the rail-wheel interaction problem and its effect on vehicle dynamics. The development of mathematical models and their applications to dynamic analyses and the design of railway vehicles are discussed. This book consists of 11 chapters and opens with an

overview of the background material required to study the dynamics of railway vehicles, with emphasis on analytical techniques used to determine the dynamic response of single- and multiple-degree-of-freedom systems. Numerical solutions of linear and nonlinear dynamic systems are also given, and various problems associated with the dynamic behavior of railway vehicles are addressed. Several mathematical models are proposed to study these problems. The following chapters focus on the wheel-rail rolling contact theories being applied in railway vehicle dynamics problems; modeling of the vehicle and its components on both tangent and curved railroad tracks; and the interaction between railway vehicles and bridges. The final chapter underscores the needs for validating mathematical models that are used to study the dynamic behavior of railway vehicles and train consists. This monograph will be of value to design and research engineers, transportation officials, mathematicians, analysts, and research workers interested in the dynamics of railway vehicle systems.

Provides a detailed overview of the dynamics of road vehicle systems, giving readers an understanding of how physical laws, human factor considerations, and design choices affect ride, handling, braking, acceleration, and vehicle safety. Chapters cover analysis of dynamic systems, tyre dynamics, ride dynamics, vehicle rollover analysis, handling dynamics, braking, acceleration, total vehicle dynamics, and accident reconstruction.

This book integrates essential knowledge of car vehicle dynamics and control theory with NI LabVIEW software product application, resulting in a practical yet highly technical guide for designing advanced vehicle dynamics controllers. Presenting a clear overview of fundamental vehicle dynamics and vehicle system mathematical models, the book covers the design of model based classical PID, adaptive, quadratic optimal and inverse dynamics-based controllers of linear and non-linear systems. It details Kalman-Bucy filtering, and its practical applications, alongside the basic kinematics and dynamics of a vehicle in planar motion, deriving equations of wheel dynamics and tire forces in forms appropriate for control design. The book also discusses lateral vehicle dynamics and vehicle vertical dynamics, high level controllers and vehicle sensor signal estimation, alongside a clear explanation of basic control principles for regenerative braking in both electric and hybrid vehicles, and torque vectoring systems. LabVIEW fundamentals are provided and used to design and implement controller examples in the book. The book will be of interest to engineering students, automotive engineering students and automotive engineers and researchers.

Ground Vehicle Dynamics is devoted to the mathematical modelling and dynamical analysis of ground vehicle systems composed of the vehicle body, the guidance and suspension devices and the corresponding guideway. Automobiles on uneven roads and railways on flexible tracks are prominent representatives of ground vehicle systems. All these different kinds of systems are treated in a common way by means of analytical dynamics and control theory. In addition to a detailed modelling of vehicles as multibody systems, the contact theory for rolling wheels and the modelling of guideways by finite element systems as well as stochastic processes are presented. As a particular result of this integrated approach the state equations of the global systems are obtained including the complete interactions between the subsystems considered as independent modules. The fundamentals of vehicle dynamics for longitudinal, lateral and vertical motions and vibrations of automobiles and railways are discussed in detail.

Featuring contributions from leading experts, the Road and Off-Road Vehicle System Dynamics Handbook provides comprehensive, authoritative coverage of all the major issues involved in road vehicle dynamic behavior. While the focus is on automobiles, this book also highlights motorcycles, heavy commercial vehicles, and off-road vehicles. The authors

The authors examine in detail the fundamentals and mathematical descriptions of the dynamics of automobiles. In this context, different levels of complexity are presented, starting with basic single-track models up to complex three-dimensional multi-body models. A particular focus is on the process of establishing mathematical models based on real cars and the validation of simulation results. The methods presented are explained in detail by means of selected application scenarios. In addition to some corrections, further application examples for standard driving maneuvers have been added for the present second edition. To take account of the increased use of driving simulators, both in research, and in industrial applications, a new section on the conception, implementation and application of driving simulators has been added.

Vehicle Dynamics and Control: Advanced Methodologies features the latest information on advanced dynamics and vehicle motion control, including a comprehensive overview of passenger cars and articulated vehicles, fundamentals, and emerging developments. This book provides a unified, balanced treatment of advanced approaches to vehicle dynamics and control. It proceeds to cover advanced vehicle control strategies, such as identification and estimation, adaptive nonlinear control, new robust control techniques, and soft computing. Other topics, such as the integrated control of passenger cars and articulated heavy vehicles, are also discussed with a significant amount of material on engineering methodology, simulation, modeling, and mathematical verification of the systems. This book discusses and solves new challenges in vehicle dynamics and control problems and helps graduate students in the field of automotive engineering as well as researchers and engineers seeking theoretical/practical design procedures in automotive control systems. Provides a vast spectrum of advanced vehicle dynamics and control systems topics and current research trends Provides an extensive discussion in some advanced topics on commercial vehicles, such as dynamics and control of semitrailer carrying liquid, integrated control system design, path planning and tracking control in the autonomous articulated vehicle

The 18th Symposium of the International Association for Vehicle System Dynamics was held at Kanagawa Institute of Technology, Atsugi, Kanagawa, Japan. The symposium was hosted by KAIT as one of the memorial events of the 40th anniversary of KAIT. Though overwhelming numbers of high quality papers were applied in response to the call for papers for the presentation

at the symposium, the Scientific Committee accepted 89 papers for the oral presentation and 38 for the poster presentation. Finally, 82 papers were presented at the oral sessions and 29 papers at the poster sessions in the symposium. There were five States-of-the-Arts papers presented at the plenary sessions in the symposium.

Vehicle Collision Dynamics provides a unified framework and timely collection of up-to-date results on front crash, side crash and car to car crashes. The book is ideal as a reference, with an approach that's simple, clear, and easy to comprehend. As the mathematical and software-based modelling and analysis of vehicle crash scenarios have not been systematically investigated, this is an ideal source for further study. Numerous academic and industry studies have analyzed vehicle safety during physical crash scenarios, thus material responses during crashes serve as one of the most important performance indices for mechanical design problems. In addition to mathematical methodologies, this book provides thorough coverage of computer simulations, software-based modeling, and an analysis of methods capable of providing more flexibility. Unifies existing and emerging concepts concerning vehicle crash dynamics Provides a series of latest results in mathematical-based modeling from front and oblique perspectives Contains almost everything needed to capture the essence of model development and analysis for vehicle crash Includes both numerical and simulation results given in each chapter Presents a comprehensive, up-to-date reference that encourages further study

This book attempts to find a middle ground by balancing engineering principles and equations of use to every automotive engineer with practical explanations of the mechanics involved, so that those without a formal engineering degree can still comprehend and use most of the principles discussed. Either as an introductory text or a practical professional overview, this book is an ideal reference.

The methods of computational mechanics have been used extensively in modeling many physical systems. The use of multibody-system techniques, in particular, has been applied successfully in the study of various, fundamentally different applications. Railroad Vehicle Dynamics: A Computational Approach presents a computational multibody-system approach that can be used to develop complex models of railroad vehicle systems. The book examines several computational multibody-system formulations and discusses their computer implementation. The computational algorithms based on these general formulations can be used to develop general- and special-purpose railroad vehicle computer programs for use in the analysis of railroad vehicle systems, including the study of derailment and accident scenarios, design issues, and performance evaluation. The authors focus on the development of fully nonlinear formulations, supported by an explanation of the limitations of the linearized formulations that are frequently used in the analysis of railroad vehicle systems. The chapters of the book are organized to guide readers from basic concepts and definitions through a final understanding of the utility of fully nonlinear multibody- system formulations in the analysis of railroad vehicle systems. Railroad Vehicle Dynamics: A Computational Approach is a valuable reference for researchers and practicing engineers who commonly use general-purpose, multibody-system computer programs in the analysis, design, and performance evaluation of railroad vehicle systems.

The book combines vehicle systems dynamics with the latest theoretical developments in dynamics of non-smooth systems and numerical analysis of differential-algebraic dynamical systems with discontinuities. These two fields are fundamental for the modelling and analysis of vehicle dynamical systems. The results are also applicable to other non-smooth dynamical systems.

This textbook covers handling and performance of both road and race cars. Mathematical models of vehicles are developed always paying attention to state the relevant assumptions and to provide explanations for each step. This innovative approach provides a deep, yet simple, analysis of the dynamics of vehicles. The reader will soon achieve a clear understanding of the subject, which will be of great help both in dealing with the challenges of designing and testing new vehicles and in tackling new research topics. The book deals with several relevant topics in vehicle dynamics that are not discussed elsewhere and this new edition includes thoroughly revised chapters, with new developments, and many worked exercises. Praise for the previous edition: Great book! It has changed drastically our approach on many topics. We are now using part of its theory on a daily basis to constantly improve ride and handling performances. --- Antonino Pizzuto, Head of Chassis Development Group at Hyundai Motor Europe Technical Center Astonishingly good! Everything is described in a very compelling and complete way. Some parts use a different approach than other books. --- Andrea Quintarelli, Automotive Engineer

Featuring contributions from leading experts, the Road and Off-Road Vehicle System Dynamics Handbook provides comprehensive, authoritative coverage of all the major issues involved in road vehicle dynamic behavior. While the focus is on automobiles, this book also highlights motorcycles, heavy commercial vehicles, and off-road vehicles. The authors of the individual chapters, both from automotive industry and universities, address basic issues, but also include references to significant papers for further reading. Thus the handbook is devoted both to the beginner, wishing to acquire basic knowledge on a specific topic, and to the experienced engineer or scientist, wishing to have up-to-date information on a particular subject. It can also be used as a textbook for master courses at universities. The handbook begins with a short history of road and off-road vehicle dynamics followed by detailed, state-of-the-art chapters on modeling, analysis and optimization in vehicle system dynamics, vehicle concepts and aerodynamics, pneumatic tires and contact wheel-road/off-road, modeling vehicle subsystems, vehicle dynamics and active safety, man-vehicle interaction, intelligent vehicle systems, and road accident reconstruction and passive safety. Provides extensive coverage of modeling, simulation, and analysis techniques Surveys all vehicle subsystems from a vehicle dynamics point of view Focuses on pneumatic tires and contact wheel-road/off-road Discusses intelligent vehicle systems technologies and active safety Considers safety factors and accident reconstruction procedures Includes chapters written by leading experts from all over the world This text provides an applicable source of information for all people interested in a deeper understanding of road vehicle dynamics and related problems.

MASTER AND INTEGRATE THE GEOMETRY AND MECHANICS OF RAILROAD VEHICLE SYSTEM ENGINEERING WITH ONE PRACTICAL RESOURCE Mathematical Foundation of Railroad Vehicle Systems: Geometry and Mechanics delivers a comprehensive treatment of the mathematical foundations of railroad vehicle systems. The book includes a strong emphasis on the integration of geometry and mechanics to create an accurate and accessible formulation of nonlinear dynamic equations and general computational algorithms that can be effectively used in the virtual prototyping, analysis, design, and performance evaluation of railroad vehicle systems. Using basic concepts, formulations, and computational algorithms, including mechanics-based approaches like the absolute nodal coordinate formulation (ANCF), readers will understand how to integrate the geometry and mechanics of railroad vehicle systems. The book also discusses new problems and issues in this area and describes how geometric and mechanical

approaches can be used in derailment investigations. Mathematical Foundation of Railroad Vehicle Systems covers: The mathematical foundation of railroad vehicle systems through the integration of geometry and mechanics Basic concepts, formulations, and computational algorithms used in railroad vehicle system dynamics New mechanics-based approaches, like the ANCF, and their use to achieve an integration of geometry and mechanics Use of geometry and mechanics to study derailments New problems and issues in the area of railroad vehicle systems Designed for researchers and practicing engineers who work with railroad vehicle systems, Mathematical Foundation of Railroad Vehicle Systems: Geometry and Mechanics can also be used in senior undergraduate and graduate mechanical, civil, and electrical engineering programs and courses.

Handbook of Railway Vehicle Dynamics, Second Edition, provides expanded, fully updated coverage of railway vehicle dynamics. With chapters by international experts, this work surveys the main areas of rolling stock and locomotive dynamics. Through mathematical analysis and numerous practical examples, it builds a deep understanding of the wheel-rail interface, suspension and suspension component design, simulation and testing of electrical and mechanical systems, and interaction with the surrounding infrastructure, and noise and vibration. Topics added in the Second Edition include magnetic levitation, rail vehicle aerodynamics, and advances in traction and braking for full trains and individual vehicles.

The interaction phenomenon is very common between different components of a mechanical system. It is a natural phenomenon and is found with the impact force in aircraft landing; the estimation of degree of ripeness of an apple from impact on a beam; the interaction of the magnetic head of a computer disk leading to miniature development of modern c

Multibody Systems Approach to Vehicle Dynamics aims to bridge a gap between the subject of classical vehicle dynamics and the general-purpose computer-based discipline known as multibody systems analysis (MBS). The book begins by describing the emergence of MBS and providing an overview of its role in vehicle design and development. This is followed by separate chapters on the modeling, analysis, and post-processing capabilities of a typical simulation software; the modeling and analysis of the suspension system; tire force and moment generating characteristics and subsequent modeling of these in an MBS simulation; and the modeling and assembly of the rest of the vehicle, including the anti-roll bars and steering systems. The final two chapters deal with the simulation output and interpretation of results, and a review of the use of active systems to modify the dynamics in modern passenger cars. This book intended for a wide audience including not only undergraduate, postgraduate and research students working in this area, but also practicing engineers in industry who require a reference text dealing with the major relevant areas within the discipline. * Full of practical examples and applications * Uses industry standard ADAMS software based applications * Accompanied by downloadable ADAMS models and data sets available from the companion website that enable readers to explore the material in the book * Guides readers from modelling suspension movement through to full vehicle models able to perform handling manoeuvres

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"Space Vehicle Dynamics and Control provides a solid foundation in dynamic modeling, analysis, and control of space vehicles. More than 200 figures, photographs, and tables are featured in detailed sections covering the fundamentals of controlling orbital, attitude, and structural motions of space vehicles. The textbook highlights a range of orbital maneuvering and control problems: orbital transfer, rendezvous, and halo orbit determination and control. Rotational maneuvering and attitude control problems of space vehicles under the influence of reaction jet firings, internal energy dissipation, or momentum transfer via reaction wheels and control moment gyros are treated in detail. The textbook also highlights the analysis and design of attitude control systems in the presence of structural flexibility and/or propellant sloshing. At the end of each chapter, Dr. Wie includes a helpful list of references for graduate students and working professionals studying spacecraft dynamics and control. A bibliography of more than 350 additional references in the field of spacecraft guidance, control, and dynamics is also provided at the end of the book. This text requires a thorough knowledge of vector and matrix algebra, calculus, ordinary differential equations, engineering mechanics, and linear system dynamics and control. The first two chapters provide a summary of such necessary background material. Since some problems may require the use of software for the analysis, control design, and numerical simulation, readers should have access to computational software (i.e., MATLAB) on a personal computer.

Vehicle Dynamics and Control provides a comprehensive coverage of vehicle control systems and the dynamic models used in the development of these control systems. The control system applications covered in the book include cruise control, adaptive cruise control, ABS, automated lane keeping, automated highway systems, yaw stability control, engine control, passive, active and semi-active suspensions, tire-road friction coefficient estimation, rollover prevention, and hybrid electric vehicles. In developing the dynamic model for each application, an effort is made to both keep the model simple enough for control system design but at the same time rich enough to capture the essential features of the dynamics. A special effort has been made to explain the several different tire models commonly used in literature and to interpret them physically. In the second edition of the book, chapters on roll dynamics, rollover prevention and hybrid electric vehicles have been added, and the chapter on electronic stability control has been enhanced. The use of feedback control systems on automobiles is growing rapidly. This book is intended to serve as a useful resource to researchers who work on the development of such control systems, both in the automotive industry and at universities. The book can also serve as a textbook for a graduate level course on Vehicle Dynamics and Control.

Essentials of Vehicle Dynamics explains the essential mathematical basis of vehicle dynamics in a concise and clear way, providing engineers and students with the qualitative understanding of vehicle handling performance needed to underpin chassis-related research and development. Without a sound understanding of the mathematical tools and

principles underlying the complex models in vehicle dynamics, engineers can end up with errors in their analyses and assumptions, leading to costly mistakes in design and virtual prototyping activities. Author Joop P. Pauwelussen looks to rectify this by drawing on his 15 years' experience of helping students and professionals understand the vehicle as a dynamic system. He begins as simply as possible before moving on to tackle models of increasing complexity, emphasizing the critical role played by tire-road contact and the different analysis tools required to consider non-linear dynamical systems. Providing a basic mathematical background that is ideal for students or those with practical experience who are struggling with the theory, Essentials of Vehicle Dynamics is also intended to help engineers from different disciplines, such as control and electronic engineering, move into the automotive sector or undertake multi-disciplinary vehicle dynamics work. Focuses on the underlying mathematical fundamentals of vehicle dynamics, equipping engineers and students to grasp and apply more complex concepts with ease. Written to help engineers avoid the costly errors in design and simulation brought about by incomplete understanding of modeling tools and approaches. Includes exercises to help readers test their qualitative understanding and explain results in physical and vehicle dynamics terms.

This book deals with the analysis of off-road vehicle dynamics from kinetics and kinematics perspectives and the performance of vehicle traversing over rough and irregular terrain. The authors consider the wheel performance, soil-tire interactions and their interface, tractive performance of the vehicle, ride comfort, stability over maneuvering, transient and steady state conditions of the vehicle traversing, modeling the aforementioned aspects and optimization from energetic and vehicle mobility perspectives. This book brings novel figures for the transient dynamics and original wheel terrain dynamics at on-the-go condition.

This book systematically presents the theory, numerical implementation, field experiments and practical engineering applications of the 'Vehicle–Track Coupled Dynamics'. Representing a radical departure from classic vehicle system dynamics and track dynamics, the vehicle–track coupled dynamics theory considers the vehicle and track as one interactive and integrated system coupled through wheel–rail interaction. This new theory enables a more comprehensive and accurate solution to the train–track dynamic interaction problem which is a fundamental and important research topic in railway transportation system, especially for the rapidly developed high-speed and heavy-haul railways. It has been widely applied in practical railway engineering. Dr. Wanming Zhai is a Chair Professor of Railway Engineering at Southwest Jiaotong University, where he is also chairman of the Academic Committee and Director of the Train and Track Research Institute. He is a member of the Chinese Academy of Sciences and one of the leading scientists in railway system dynamics. Professor Zhai is Editor-in-Chief of both the International Journal of Rail Transportation, published by Taylor & Francis Group, and the Journal of Modern Transportation, published by Springer. In addition, he is a trustee of the International Association for Vehicle System Dynamics, Vice President of the Chinese Society of Theoretical and Applied Mechanics, and Vice President of the Chinese Society for Vibration Engineering. /div

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