

## Building A Beaglebone Black Super Cluster Reichel Andreas Josef

Take your idea from concept to production with this unique guide Whether it's called physical computing, ubiquitous computing, or the Internet of Things, it's a hot topic in technology: how to channel your inner Steve Jobs and successfully combine hardware, embedded software, web services, electronics, and cool design to create cutting-edge devices that are fun, interactive, and practical. If you'd like to create the next must-have product, this unique book is the perfect place to start. Both a creative and practical primer, it explores the platforms you can use to develop hardware or software, discusses design concepts that will make your products eye-catching and appealing, and shows you ways to scale up from a single prototype to mass production. Helps software engineers, web designers, product designers, and electronics engineers start designing products using the Internet-of-Things approach Explains how to combine sensors, servos, robotics, Arduino chips, and more with various networks or the Internet, to create interactive, cutting-edge devices Provides an overview of the necessary steps to take your idea from concept through production If you'd like to design for the future, Designing the Internet of Things is a great place to start.

Your one-stop guide to the Robot Operating System About This Book Model your robot on a virtual world and learn how to simulate it Create, visualize, and process Point Cloud information Easy-to-follow, practical tutorials to program your own robots Who This Book Is For If you are a robotic enthusiast who wants to learn how to build and program your own robots in an easy-to-develop, maintainable, and shareable way, this book is for you. In order to make the most of the book, you should have a C++ programming background, knowledge of GNU/Linux systems, and general skill in computer science. No previous background on ROS is required, as this book takes you from the ground up. It is also advisable to have some knowledge of version control systems, such as svn or git, which are often used by the community to share code. What You Will Learn Install a complete ROS Hydro system Create ROS packages and metapackages, using and debugging them in real time Build, handle, and debug ROS nodes Design your 3D robot model and simulate it in a virtual environment within Gazebo Give your robots the power of sight using cameras and calibrate and perform computer vision tasks with them Generate and adapt the navigation stack to work with your robot Integrate different sensors like Range Laser, Arduino, and Kinect with your robot Visualize and process Point Cloud information from different sensors Control and plan motion of robotic arms with multiple joints using MoveIt! In Detail If you have ever tried building a robot, then you know how cumbersome programming everything from scratch can be. This is where ROS comes into the picture. It is a collection of tools, libraries, and conventions that simplifies the robot building process. What's more, ROS encourages collaborative robotics software development, allowing you to connect with experts in various fields to collaborate and build upon each other's work. Packed full of examples, this book will help you understand the ROS framework to help you build your own robot applications in a simulated environment and share your knowledge with the large community supporting ROS. Starting at an introductory level, this book is a comprehensive guide to the fascinating world of robotics, covering sensor integration, modeling, simulation, computer vision, navigation algorithms, and more. You will then go on to explore concepts like topics, messages, and nodes. Next, you will learn how to make your robot see with HD cameras, or navigate obstacles with range sensors. Furthermore, thanks to the contributions of the vast ROS community, your robot will be able to navigate autonomously, and even recognize and interact with you in a matter of minutes. What's new in this updated edition? First and foremost, we are going to work with ROS Hydro this time around. You will learn how to create, visualize, and process Point Cloud information from different sensors. This edition will also show you how to control and plan motion of robotic arms with multiple joints using MoveIt! By the end of this book, you will have all the background you need to build your own robot and get started with ROS. Style and approach This book is an easy-to-follow guide that will help you find your way through the ROS framework. This book is packed with hands-on examples that will help you program your robot and give you complete solutions using ROS open source libraries and tools.

This book is for programmers and developers who want to improve the performance of their R programs by making them run faster with large data sets or who are trying to solve a pesky performance problem.

Whether you're a veteran or an absolute n00b, this is the best place to start with Kali Linux, the security professional's platform of choice, and a truly industrial-grade, and world-class operating system distribution-mature, secure, and enterprise-ready.

Building a BeagleBone Black Super ClusterPackt Publishing Ltd

An annotated guide to program and develop GNU/Linux Embedded systems quickly About This Book Rapidly design and build powerful prototypes for GNU/Linux Embedded systems Become familiar with the workings of GNU/Linux Embedded systems and how to manage its peripherals Write, monitor, and configure applications quickly and effectively, manage an external micro-controller, and use it as co-processor for real-time tasks Who This Book Is For This book targets Embedded System developers and GNU/Linux programmers who would like to program Embedded Systems and perform Embedded development. The book focuses on quick and efficient prototype building. Some experience with hardware and Embedded Systems is assumed, as is having done some previous work on GNU/Linux systems. Knowledge of scripting on GNU/Linux is expected as well. What You Will Learn Use embedded systems to implement your projects Access and manage peripherals for embedded systems Program embedded systems using languages such as C, Python, Bash, and PHP Use a complete distribution, such as Debian or Ubuntu, or an embedded one, such as OpenWrt or Yocto Harness device driver capabilities to optimize device communications Access data through several kinds of devices such as GPIO's, serial ports, PWM, ADC, Ethernet, WiFi, audio, video, I2C, SPI, One Wire, USB and CAN Practical example usage of several devices such as RFID readers, Smart card readers, barcode readers, z-Wave devices, GSM/GPRS modems Usage of several sensors such as light, pressure, moisture, temperature, infrared, power, motion In Detail Embedded computers have become very complex in the last few years and developers need to easily manage them by focusing on how to solve a problem without wasting time in finding supported peripherals or learning how to manage them. The main challenge with experienced embedded programmers and engineers is really how long it takes to turn an idea into reality, and we show you exactly how to do it. This book shows how to interact with external environments through specific peripherals used in the industry. We will use the latest Linux kernel release 4.4.x and Debian/Ubuntu distributions (with embedded distributions like OpenWrt and Yocto). The book will present popular boards in the industry that are user-friendly to base the rest of the projects on - BeagleBone Black, SAMA5D3 Xplained, Wandboard and system-on-chip manufacturers. Readers will be able to take their first steps in programming the embedded platforms, using C, Bash, and Python/PHP languages in order to get access to the external peripherals. More about using and programming device driver and accessing the peripherals will be covered to lay a strong foundation. The readers will learn how to read/write data from/to the external environment by using both C programs or a scripting language (Bash/PHP/Python) and how to configure a device driver for a specific hardware. After finishing this book, the readers will be able to gain a good knowledge level and understanding of writing, configuring, and managing drivers, controlling and monitoring applications with the help of efficient/quick programming and will be able to apply these skills into real-world projects. Style and approach This practical tutorial will get you quickly prototyping embedded systems on GNU/Linux. This book uses a variety of hardware to program the peripherals and build simple prototypes.

Learn how to write high-quality kernel module code, solve common Linux kernel programming issues, and understand the fundamentals of Linux kernel internals Key Features Discover how to write kernel

code using the Loadable Kernel Module framework Explore industry-grade techniques to perform efficient memory allocation and data synchronization within the kernel Understand the essentials of key internals topics such as kernel architecture, memory management, CPU scheduling, and kernel synchronization Book Description Linux Kernel Programming is a comprehensive introduction for those new to Linux kernel and module development. This easy-to-follow guide will have you up and running with writing kernel code in next-to-no time. This book uses the latest 5.4 Long-Term Support (LTS) Linux kernel, which will be maintained from November 2019 through to December 2025. By working with the 5.4 LTS kernel throughout the book, you can be confident that your knowledge will continue to be valid for years to come. This Linux book begins by showing you how to build the kernel from the source. Next, you'll learn how to write your first kernel module using the powerful Loadable Kernel Module (LKM) framework. The book then covers key kernel internals topics including Linux kernel architecture, memory management, and CPU scheduling. Next, you'll delve into the fairly complex topic of concurrency within the kernel, understand the issues it can cause, and learn how they can be addressed with various locking technologies (mutexes, spinlocks, atomic, and refcount operators). You'll also benefit from more advanced material on cache effects, a primer on lock-free techniques within the kernel, deadlock avoidance (with lockdep), and kernel lock debugging techniques. By the end of this kernel book, you'll have a detailed understanding of the fundamentals of writing Linux kernel module code for real-world projects and products. What you will learn Write high-quality modular kernel code (LKM framework) for 5.x kernels Configure and build a kernel from source Explore the Linux kernel architecture Get to grips with key internals regarding memory management within the kernel Understand and work with various dynamic kernel memory alloc/dealloc APIs Discover key internals aspects regarding CPU scheduling within the kernel Gain an understanding of kernel concurrency issues Find out how to work with key kernel synchronization primitives Who this book is for This book is for Linux programmers beginning to find their way with Linux kernel development. Linux kernel and driver developers looking to overcome frequent and common kernel development issues, as well as understand kernel internals, will benefit from this book. A basic understanding of Linux CLI and C programming is required.

Explore the Internet of Things and build useful, functioning Photon projects Quickly learn to construct your own electronics devices and control them over the Internet with help from this DIY guide.

Programming the Photon: Getting Started with the Internet of Things features clear explanations and step-by-step examples that use inexpensive, easy-to-find components. Discover how to connect to Wi-Fi networks, attach hardware to I/O ports, write custom programs, and work from the cloud. You will learn how to troubleshoot and tweak your Photon creations—even interface with social media sites! · Set up your Photon board and connect to the Particle cloud · Start constructing and programming custom IoT projects · Learn the syntax of both the C and Arduino languages · Incorporate switches, sensors, and other input devices · Control hardware through the Photon's outputs · Control your creations through the Internet · Add functions with Particle shields and add-on boards · Link real-time data to your board via the IFTTT Web Service · Integrate with websites—Facebook, Twitter, Gmail, and more!

Expand Raspberry Pi capabilities with fundamental engineering principles Exploring Raspberry Pi is the innovators guide to bringing Raspberry Pi to life. This book favors engineering principles over a 'recipe' approach to give you the skills you need to design and build your own projects. You'll understand the fundamental principles in a way that transfers to any type of electronics, electronic modules, or external peripherals, using a "learning by doing" approach that caters to both beginners and experts. The book begins with basic Linux and programming skills, and helps you stock your inventory with common parts and supplies. Next, you'll learn how to make parts work together to achieve the goals of your project, no matter what type of components you use. The companion website provides a full repository that structures all of the code and scripts, along with links to video tutorials and supplementary content that takes you deeper into your project. The Raspberry Pi's most famous feature is its adaptability. It can be used for thousands of electronic applications, and using the Linux OS expands the functionality even more. This book helps you get the most from your Raspberry Pi, but it also gives you the fundamental engineering skills you need to incorporate any electronics into any project. Develop the Linux and programming skills you need to build basic applications Build your inventory of parts so you can always "make it work" Understand interfacing, controlling, and communicating with almost any component Explore advanced applications with video, audio, real-world interactions, and more Be free to adapt and create with Exploring Raspberry Pi.

An easy-to-follow guide full of hands-on examples to help transform your house into a standalone home automation solution.If you are looking for ways to create a highly capable home automation system that is easily extendable and highly configurable, then this book is for you. Basic knowledge of electronics and programming in Python and/or Java languages will be helpful, but not mandatory.

Learn to easily build gadgets, gizmos, robots, and more using Arduino Written by Arduino expert Jeremy Blum, this unique book uses the popular Arduino microcontroller platform as an instrument to teach you about topics in electrical engineering, programming, and human-computer interaction. Whether you're a budding hobbyist or an engineer, you'll benefit from the perfectly paced lessons that walk you through useful, artistic, and educational exercises that gradually get more advanced. In addition to specific projects, the book shares best practices in programming and design that you can apply to your own projects. Code snippets and schematics will serve as a useful reference for future projects even after you've mastered all the topics in the book. Includes a number of projects that utilize different capabilities of the Arduino, while interfacing with external hardware Features chapters that build upon each other, tying in concepts from previous chapters to illustrate new ones Includes aspects that are accompanied by video tutorials and other multimedia content Covers electrical engineering and programming concepts, interfacing with the world through analog and digital sensors, communicating with a computer and other devices, and internet connectivity Explains how to combine smaller topics into more complex projects Shares downloadable materials and source code for everything covered in the book Projects compatible with many official Arduino boards including Arduino Uno; Arduino Leonardo; Arduino Mega 2560; Arduino Due; Arduino Nano; Arduino Mega ADK; LilyPad Arduino and may work with Arduino-compatible boards such as Freeduino and new third party certified boards such as the Intel Galileo Exploring Arduino takes you on an adventure and provides you with exclusive access to materials not found anywhere else!

The FreeBSD Handbook is a comprehensive FreeBSD tutorial and reference. It covers installation, day-to-day use of FreeBSD, and much more, such as the Ports collection, creating a custom kernel, security topics, the X Window System, how to use FreeBSD's Linux binary compatibility, and how to upgrade your system from source using the 'make world' command, to name a few.

Zero to Maker is part memoir and part how-to guidebook for anyone who is having thoughts like these: I feel like all I can do is write emails. I wish I had more hands-on skills even though I don't know what I would build... I have this one idea I've always wanted to make, but I don't know how to build it... I keep hearing about the "maker movement" but I'm not sure what that means or how I can join in... The book follows author David Lang's headfirst dive into the maker world and shows how he grew from an unskilled beginner to be a successful entrepreneur. You'll discover how to navigate this new community of makers, and find the best resources for learning the tools and skills you need to be a dynamic maker in your own right. The way we make things has changed. A new generation of tinkerers have emerged through online communities and powerful digital fabrication tools, and their creations are changing the world. This book follows the author's personal journey of transformation into a maker-entrepreneur. It is everyone's guide to combining inspiration and resources to effectively navigate this exciting new world. Lang reveals how he became a maker pro after losing his job and how the experience helped him start OpenROV, a DIY community and product line focused on underwater robotics. It all happened once he became an active member of the maker movement. Ready to take the plunge into the next Industrial Revolution? This guide provides a clear and inspiring roadmap. Take an eye-opening journey from unskilled observer to engaged maker Learn how to join this community, get access to tools and experts, and

pick up new skills Use a template for building a maker-based entrepreneurial lifestyle and prepare yourself for the careers of the future This book is for everyone who dreams of becoming a successful maker-entrepreneur. It not only satisfies the aspirational aspect but shows newcomers to the maker movement exactly how to join in. First published in 2013, this new edition features full-color photos and shares David's latest insights and experiences as he continues to grow as a maker entrepreneur and citizen scientist.

Over 60 recipes and solutions for inventors, makers, and budding engineers to create projects using the BeagleBone Black About This Book Learn how to develop applications with the BeagleBone Black and open source Linux software Sharpen your expertise in making sophisticated electronic devices Explore the BeagleBone Black with this easy-to-succeed recipe format Who This Book Is For If you are a hardware, Linux, and/or microcomputing novice, or someone who wants more power and possibilities with product prototypes, electronic art projects, or embedded computing experiments, then this book is for you. It is for Internet of Things enthusiasts who want to use more sophisticated hardware than the Raspberry Pi or the Arduino can provide. Whether you are an engineering student, a DIYer, an inventor, or a budding electronics enthusiast, this book delivers accessible, easy-to-succeed instructions for using an advanced microcomputing platform. What You Will Learn Set up and run the BeagleBone Black for the first time Learn the basics of microcomputing and Linux using the command line and easy kernel mods Make introductory projects with Python, JavaScript, BoneScript, and Node.js Explore physical computing and simple circuits using buttons, LEDs, sensors, and motors Discover the unique features of the BeagleBone Black and its real-time computing functions Build intermediate level audio and video applications Assemble and add ingredients for creating Internet of Things prototypes In Detail There are many single-board controllers and computers such as Arduino, Udoo, or Raspberry Pi, which can be used to create electronic prototypes on circuit boards. However, when it comes to creating more advanced projects, BeagleBone Black provides a sophisticated alternative. Mastering the BeagleBone Black enables you to combine it with sensors and LEDs, add buttons, and marry it to a variety of add-on boards. You can transform this tiny device into the brain for an embedded application or an endless variety of electronic inventions and prototypes. With dozens of how-tos, this book kicks off with the basic steps for setting up and running the BeagleBone Black for the first time, from connecting the necessary hardware and using the command line with Linux commands to installing new software and controlling your system remotely. Following these recipes, more advanced examples take you through scripting, debugging, and working with software source files, eventually working with the Linux kernel. Subsequently, you will learn how to exploit the board's real-time functions. We will then discover exciting methods for using sound and video with the system before marching forward into an exploration of recipes for building Internet of Things projects. Finally, the book finishes with a dramatic arc upward into outer space, when you explore ways to build projects for tracking and monitoring satellites. Style and approach This comprehensive recipe book deconstructs a complex, often confusing piece of technology, and transforms it to become accessible and fun with snappy, unintimidating prose, and extensive easy-to-succeed instructions.

Embedded Android is for Developers wanting to create embedded systems based on Android and for those wanting to port Android to new hardware, or creating a custom development environment. Hackers and moders will also find this an indispensable guide to how Android works.

Summary A hands-on guide that will teach how to design and implement scalable, flexible, and open IoT solutions using web technologies. This book focuses on providing the right balance of theory, code samples, and practical examples to enable you to successfully connect all sorts of devices to the web and to expose their services and data over REST APIs. Purchase of the print book includes a free eBook in PDF, Kindle, and ePub formats from Manning Publications. About the Technology Because the Internet of Things is still new, there is no universal application protocol. Fortunately, the IoT can take advantage of the web, where IoT protocols connect applications thanks to universal and open APIs. About the Book Building the Web of Things is a guide to using cutting-edge web technologies to build the IoT. This step-by-step book teaches you how to use web protocols to connect real-world devices to the web, including the Semantic and Social Webs. Along the way you'll gain vital concepts as you follow instructions for making Web of Things devices. By the end, you'll have the practical skills you need to implement your own web-connected products and services. What's Inside Introduction to IoT protocols and devices Connect electronic actuators and sensors (GPIO) to a Raspberry Pi Implement standard REST and Pub/Sub APIs with Node.js on embedded systems Learn about IoT protocols like MQTT and CoAP and integrate them to the Web of Things Use the Semantic Web (JSON-LD, RDFa, etc.) to discover and find Web Things Share Things via Social Networks to create the Social Web of Things Build a web-based smart home with HTTP and WebSocket Compose physical mashups with EVERYTHING, Node-RED, and IFTTT About the Reader For both seasoned programmers and those with only basic programming skills. About the Authors Dominique Guinard and Vlad Trifa pioneered the Web of Things and cofounded EVERYTHING, a large-scale IoT cloud powering billions of Web Things. Table of Contents PART 1 BASICS OF THE IOT AND THE WOT From the Internet of Things to the Web of Things Hello, World Wide Web of Things Node.js for the Web of Things Getting started with embedded systems Building networks of Things PART 2 BUILDING THE WOT Access: Web APIs for Things Implementing Web Things Find: Describe and discover Web Things Share: Securing and sharing Web Things

Linux® is being adopted by an increasing number of embedded systems developers, who have been won over by its sophisticated scheduling and networking, its cost-free license, its open development model, and the support offered by rich and powerful programming tools. While there is a great deal of hype surrounding the use of Linux in embedded systems, there is not a lot of practical information. Building Embedded Linux Systems is the first in-depth, hard-core guide to putting together an embedded system based on the Linux kernel. This indispensable book features arcane and previously undocumented procedures for: Building your own GNU development toolchain Using an efficient embedded development framework Selecting, configuring, building, and installing a target-specific kernel Creating a complete target root filesystem Setting up, manipulating, and using solid-state storage devices Installing and configuring a bootloader for the target Cross-compiling a slew of utilities and packages Debugging your embedded system using a plethora of tools and techniques Details are provided for various target architectures and hardware configurations, including a thorough review of Linux's support for embedded hardware. All explanations rely on the use of open source and free software packages. By presenting how to build the operating system components from pristine sources and how to find more documentation or help, this book greatly simplifies the task of keeping complete control over one's embedded operating system, whether it be for technical or sound financial reasons. Author Karim Yaghmour, a well-known designer and speaker who is responsible for the Linux Trace Toolkit, starts by discussing the strengths and weaknesses of Linux as an embedded operating system. Licensing issues are included, followed by a discussion of the basics of building embedded Linux systems. The configuration, setup, and use of over forty different open source and free software packages commonly used in embedded Linux systems are also covered. uClibc, BusyBox, U-Boot, OpenSSH, tftpd, tftp, strace, and gdb are among the packages discussed.

Learn to build amazing robotic projects using the powerful BeagleBone Black. About This Book Push your creativity to the limit through complex, diverse, and fascinating projects Develop applications with the BeagleBone Black and open source Linux software Sharpen your expertise in making sophisticated electronic devices Who This Book Is For This Learning Path is aimed at hobbyists who want to do creative projects that make their life easier and also push the boundaries of what can be done with the BeagleBone Black. This Learning Path's projects are for the aspiring maker, casual programmer, and budding engineer or tinkerer. You'll need some programming knowledge, and experience of working with mechanical systems to get the complete

experience from this Learning Path. What You Will Learn Set up and run the BeagleBone Black for the first time Get to know the basics of microcomputing and Linux using the command line and easy kernel mods Develop a simple web interface with a LAMP platform Prepare complex web interfaces in JavaScript and get to know how to stream video data from a webcam Find out how to use a GPS to determine where your sailboat is, and then get the bearing and distance to a new waypoint Use a wind sensor to sail your boat effectively both with and against the wind Build an underwater ROV to explore the underwater world See how to build an autonomous Quadcopter In Detail BeagleBone is a microboard PC that runs Linux. It can connect to the Internet and run OSes such as Android and Ubuntu. You can transform this tiny device into a brain for an embedded application or an endless variety of electronic inventions and prototypes. This Learning Path starts off by teaching you how to program the BeagleBone. You will create introductory projects to get yourselves acquainted with all the nitty gritty. Then we'll focus on a series of projects that are aimed at hobbyists like you and encompass the areas of home automation and robotics. With each project, we'll teach you how to connect several sensors and an actuator to the BeagleBone Black. We'll also create robots for land, sea, and water. Yes, really! The books used in this Learning Path are: BeagleBone Black Cookbook BeagleBone Home Automation Blueprints Mastering BeagleBone Robotics Style and approach This practical guide transforms complex and confusing pieces of technology to become accessible with easy- to-succeed instructions. Through clear, concise examples, you will quickly get to grips with the core concepts needed to develop home automation applications with the BeagleBone Black.

Milady has evolved for over 85 years to become what it is today, the cornerstone of beauty and wellness education. We are very excited and proud to announce the latest edition of Milady Standard Cosmetology, the most commonly used resource in cosmetology education. For decades since our first textbook published, it has been our commitment to provide students with the foundation in the principles and skills needed to master the science and art of cosmetology, and with this latest version that commitment has not waivered. For the new edition, celebrity stylist Ted Gibson served as Creative Director on the project. The result is a brilliant new design with over 750 new photos and a gorgeous layout, providing a visually stunning resource to engage today's learner. We also recruited a team of twelve authors, made up of top professionals and educators in the industry, to provide the most current information on concepts and techniques. During our extensive peer review and development process, we were asked for a resource that placed emphasis on essential content needed for licensure success, and we feel confident that we delivered. Milady Standard Cosmetology will continue to be a source of education that students can count on, not only while in school, but throughout their careers. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version.

BeagleBone Black is a low-cost, open hardware computer uniquely suited to interact with sensors and actuators directly and over the Web. Introduced in April 2013 by BeagleBoard.org, a community of developers first established in early 2008, BeagleBone Black is used frequently to build vision-enabled robots, home automation systems, artistic lighting systems, and countless other do-it-yourself and professional projects. BeagleBone variants include the original BeagleBone and the newer BeagleBone Black, both hosting a powerful 32-bit, super-scalar ARM Cortex A8 processor capable of running numerous mobile and desktop-capable operating systems, typically variants of Linux including Debian, Android, and Ubuntu. Yet, BeagleBone is small enough to fit in a small mint tin box. The "Bone" may be used in a wide variety of projects from middle school science fair projects to senior design projects to first prototypes of very complex systems. Novice users may access the power of the Bone through the user-friendly BoneScript software, experienced through a Web browser in most major operating systems, including Microsoft Windows, Apple Mac OS X, or the Linux operating systems. Seasoned users may take full advantage of the Bone's power using the underlying Linux-based operating system, a host of feature extension boards (Capes) and a wide variety of Linux community open source libraries. This book provides an introduction to this powerful computer and has been designed for a wide variety of users including the first time novice through the seasoned embedded system design professional. The book contains background theory on system operation coupled with many well-documented, illustrative examples. Examples for novice users are centered on motivational, fun robot projects while advanced projects follow the theme of assistive technology and image-processing applications.

Absolutely no experience needed! Learn robot building from the ground up, hands-on, in full color! Love robots? Start building them. It's way easier than you ever imagined! John Baichtal has helped thousands of people get started with robotics. He knows what beginners need to know. He knows your questions. He knows where you might need extra help. Now, he's brought together this practical knowledge in one incredibly easy tutorial. Hundreds of full-color photos guide you through every step, every skill. You'll start simple, as you build a working robot in the very first chapter. Then, you'll grow your skills to expert-level: powering motors, configuring sensors, constructing a chassis, even programming low-cost Arduino microcontrollers. You'll learn hands-on, through real step-by-step projects...and go straight to the cutting-edge with in-depth sidebars. Wondering just how much you can really do? Baichtal shows you 30 incredible robots built by people just like you! John Baichtal's books about toys, tools, robots, and hobby electronics include Hack This: 24 Incredible Hackerspace Projects from the DIY Movement; Basic Robot Building With Lego Mindstorms NXT 2.0; Arduino for Beginners; MAKE: Lego and Arduino Projects for MAKE (as coauthor); and the forthcoming Building Your Own Drones: The Beginner's Guide to UAVs and ROVs. A founding member of the pioneering Twin Cities Maker hackerspace, he got his start writing for Wired's legendary GeekDad blog, and for DIYer bible MAKE Magazine. Make your robots move with motors and wheels Build solar-powered robots that work without batteries Control robots via Wi-Fi, radio, or even across the Internet Program robots to respond to sensor inputs Use your standard TV remote to control your robots Create robots that detect intruders and shoot them with Nerf® darts Grab and carry objects using claws and grippers Build water-borne robots that float, submerge, and "swim" Create "artbots" that paint or draw original artworks Enable your robots to send text messages when they take specific actions Discover today's new generation of hobbyist-friendly robotics kits Organize your ultimate robot-builder's toolbox Master simple safety routines that protect you whatever you're building

The bestselling beginner Arduino guide, updated with new projects! Exploring Arduino makes electrical engineering and embedded software accessible. Learn step by step everything you need to know about electrical engineering, programming, and human-computer interaction through a series of increasingly complex projects. Arduino guru Jeremy Blum walks you through each build, providing code snippets and schematics that will remain useful for future projects. Projects are accompanied by downloadable source code, tips and tricks, and video tutorials to help you master Arduino. You'll gain the skills you need to develop your own microcontroller projects! This new 2nd edition has been updated to cover the rapidly-expanding Arduino

ecosystem, and includes new full-color graphics for easier reference. Servo motors and stepper motors are covered in richer detail, and you'll find more excerpts about technical details behind the topics covered in the book. Wireless connectivity and the Internet-of-Things are now more prominently featured in the advanced projects to reflect Arduino's growing capabilities. You'll learn how Arduino compares to its competition, and how to determine which board is right for your project. If you're ready to start creating, this book is your ultimate guide! Get up to date on the evolving Arduino hardware, software, and capabilities Build projects that interface with other devices—wirelessly! Learn the basics of electrical engineering and programming Access downloadable materials and source code for every project Whether you're a first-timer just starting out in electronics, or a pro looking to mock-up more complex builds, Arduino is a fantastic tool for building a variety of devices. This book offers a comprehensive tour of the hardware itself, plus in-depth introduction to the various peripherals, tools, and techniques used to turn your little Arduino device into something useful, artistic, and educational. Exploring Arduino is your roadmap to adventure—start your journey today!

Fiendishly Fun Ways to Use the BeagleBone Black! This wickedly inventive guide shows you how to program and build fun and fascinating projects with the BeagleBone Black. You'll learn how to connect the BeagleBone Black to your computer and program it, quickly mastering BoneScript and other programming tools so you can get started right away. 30 BeagleBone Black Projects for the Evil Genius is filled with a wide variety of do-it-yourself LED, sensor, robotics, display, audio, and spy gadgets. You'll also get tips and techniques that will help you design your own ingenious devices. Features step-by-step instructions and helpful illustrations Provides full schematic and breadboard layout diagrams for the projects Includes detailed programming code Removes the frustration factor—all required parts are listed along with sources Build these and other clever creations: High-powered LED Morse code sender RGB LED fader GPS tracker Temperature sensor Light level indicator Web-controlled rover Plant hydration system Sentinel turret 7-segment clock Display for sensor information Internet radio Imperial march indicator Intruder alert using Twitter API Lie detector Auto dog barker

The definitive, easy-to-use guide to the popular BeagleBone board BeagleBone For Dummies is the definitive beginner's guide to using the popular BeagleBone board to learn electronics and programming. Unlike other books that require previous knowledge of electronics, Linux, and Python, this one assumes you know nothing at all, and guides you step-by-step throughout the process of getting acquainted with your BeagleBone Original or BeagleBone Black. You'll learn how to get set up, use the software, build the hardware, and code your projects, with plenty of examples to walk you through the process. You'll move carefully through your first BeagleBone project, then get ideas for branching out from there to create even better, more advanced programs. The BeagleBone is a tiny computer board – about the size of a credit card – that has all the capability of a desktop. Its affordability and ease of use has made it popular among hobbyists, hardware enthusiasts, and programmers alike, and it's time for you to join their ranks as you officially dive into the world of microcomputers. This book removes the guesswork from using the popular BeagleBone board and shows you how to get up and running in no time. Download the operating system and connect your BeagleBone Learn to navigate the desktop environment Start programming with Python and Bonescript Build your first project, and find plans for many more To learn BeagleBone, you could spend hours on the Internet and still never find the information you need, or you can get everything you need here. This book appeals to all new and inexperienced hobbyists, tinkerers, electronics gurus, hackers, budding programmers, engineers, and hardware geeks who want to learn how to get the most out of their powerful BeagleBone.

Find out everything you need to know to build powerful robots with the most up-to-date ROS About This Book This comprehensive, yet easy-to-follow guide will help you find your way through the ROS framework Successfully design and simulate your 3D robot model and use powerful robotics algorithms and tools to program and set up your robots with an unparalleled experience by using the exciting new features from Robot Kinetic Use the latest version of gazebo simulator, OpenCV 3.0, and C++11 standard for your own algorithms Who This Book Is For This book is suitable for an ROS beginner as well as an experienced ROS roboticist or ROS user or developer who is curious to learn ROS Kinetic and its features to make an autonomous Robot. The book is also suitable for those who want to integrate sensors and embedded systems with other software and tools using ROS as a framework. What You Will Learn Understand the concepts of ROS, the command-line tools, visualization GUIs, and how to debug ROS Connect robot sensors and actuators to ROS Obtain and analyze data from cameras and 3D sensors Use Gazebo for robot/sensor and environment simulation Design a robot and see how to make it map the environment, navigate autonomously, and manipulate objects in the environment using MoveIt! Add vision capabilities to the robot using OpenCV 3.0 Add 3D perception capabilities to the robot using the latest version of PCL In Detail Building and programming a robot can be cumbersome and time-consuming, but not when you have the right collection of tools, libraries, and more importantly expert collaboration. ROS enables collaborative software development and offers an unmatched simulated environment that simplifies the entire robot building process. This book is packed with hands-on examples that will help you program your robot and give you complete solutions using open source ROS libraries and tools. It also shows you how to use virtual machines and Docker containers to simplify the installation of Ubuntu and the ROS framework, so you can start working in an isolated and control environment without changing your regular computer setup. It starts with the installation and basic concepts, then continues with more complex modules available in ROS such as sensors and actuators integration (drivers), navigation and mapping (so you can create an autonomous mobile robot), manipulation, Computer Vision, perception in 3D with PCL, and more. By the end of the book, you'll be able to leverage all the ROS Kinetic features to build a fully fledged robot for all your needs. Style and approach This book is packed with hands-on examples that will help you program your robot and give you complete solutions using ROS open source libraries and tools. All the robotics concepts and modules are explained and multiple examples are provided so that you can understand them easily.

This comprehensive book provides detailed materials for both novice and experienced programmers using all BeagleBone variants which host a powerful 32-bit, super-scalar TI Sitara ARM Cortex A8 processor. Authored by Steven F. Barrett and Jason Kridner, a seasoned ECE educator along with the founder of Beagleboard.org, respectively, the work may be used in a wide variety of projects from science fair projects to university courses and senior design projects to first prototypes of very complex systems. Beginners may access the power of the "Bone" through the user-friendly Bonescript examples. Seasoned users may take full advantage of the Bone's power using the underlying Linux-based operating system, a host of feature extension boards (Capes) and a wide variety of Linux community open source libraries. The book contains background theory on system operation coupled with many well-documented, illustrative examples. Examples for novice users are centered on motivational, fun robot projects while advanced projects follow the theme of assistive technology and image processing applications. Key Features: - Provides detailed examples for all BeagleBone variants, including the newest "next generation" BeagleBone Black - BeagleBone is a low cost, open hardware, expandable computer first introduced in november 2011 by beagleboard - BeagleBone variants, including the original BeagleBone and the new beaglebone black, hosts a powerful 32-bit, super-scalar arM Cortex A8 processor - BeagleBone is small enough to fit in a small mint tin box - "Bone" may be used in a wide variety of projects from middle school science fair projects to university courses and senior design projects to first prototypes of very complex systems - Novice users may access the power of the bone through the user-

friendly bonescript environment - Seasoned users may take full advantage of the Bone's power using the underlying Linux-based operating system - A host of feature extension boards (Capes) and a wide variety of Linux community open source libraries are available - The book provides an introduction to this powerful computer and has been designed for a wide variety of users - The book contains background theory on system operation coupled with many well-documented, illustrative examples - Examples for novice users are centered on motivational, fun robot projects - Advanced projects follow the theme of assistive technology and image processing applications

BeagleBone is a barebone computer that can be configured and customized for different applications and is almost half the price of a standard computer. This book will cover the basics of how BeagleBone Black's hardware interface subsystems work, and can be controlled using two popular Python libraries for BeagleBone Black. You will be introduced to BeagleBone Black's GPIO, PWM, ADC, UART, SPI, I2C, and eQEP subsystems. We will then dive deep into more complex built-in peripherals, demonstrating different ways to receive input from a user including buttons, potentiometers, and rotary encoders with the eQEP module. We will also learn about interfacing with external devices; this will be demonstrated using the serial modules to interface with external devices such as temperature sensors and accelerometers. Towards the end of the book, we will present a couple of real-world problems and demonstrate how to solve them with the skills you've acquired.

Hacking and Penetration Testing with Low Power Devices shows you how to perform penetration tests using small, low-powered devices that are easily hidden and may be battery-powered. It shows how to use an army of devices, costing less than you might spend on a laptop, from distances of a mile or more. Hacking and Penetration Testing with Low Power Devices shows how to use devices running a version of The Deck, a full-featured penetration testing and forensics Linux distribution, and can run for days or weeks on batteries due to their low power consumption. Author Philip Polstra shows how to use various configurations, including a device the size of a deck of cards that can easily be attached to the back of a computer. While each device running The Deck is a full-featured pen-testing platform, connecting systems together via 802.15.3 networking gives you even more power and flexibility. This reference teaches you how to construct and power these devices, install operating systems, and fill out your toolbox of small low-power devices with hundreds of tools and scripts from the book's companion website. Hacking and Pen Testing with Low Power Devices puts all these tools into your hands and will help keep you at the top of your game performing cutting-edge pen tests from anywhere in the world! Understand how to plan and execute an effective penetration test using an army of low-power devices Learn how to configure and use open-source tools and easy-to-construct low-power devices Leverage IEEE 802.15.4 networking to perform penetration tests from up to a mile away, or use 802.15.4 gateways to perform pen tests from anywhere in the world Access penetration testing operating systems with hundreds of tools and scripts on the book's companion web site

This book contains the practical labs corresponding to the "Linux Kernel and Driver Development: Training Handouts" book from Bootlin. Get your hands on an embedded board based on an ARM processor (the Beagle Bone Black board), and apply what you learned: write a Device Tree to declare devices connected to your board, configure pin multiplexing, and implement drivers for I2C and serial devices. You will learn how to manage multiple devices with the same driver, to access and write hardware registers, to allocate memory, to register and manage interrupts, as well as how to debug your code and interpret the kernel error messages. You will also keep an eye on the board and CPU datasheets so that you will always understand the values that you feed to the kernel.

The Hitchhiker's Guide to Python takes the journeyman Pythonista to true expertise. More than any other language, Python was created with the philosophy of simplicity and parsimony. Now 25 years old, Python has become the primary or secondary language (after SQL) for many business users. With popularity comes diversity—and possibly dilution. This guide, collaboratively written by over a hundred members of the Python community, describes best practices currently used by package and application developers. Unlike other books for this audience, The Hitchhiker's Guide is light on reusable code and heavier on design philosophy, directing the reader to excellent sources that already exist.

Program your own MicroPython projects with ease—no prior programming experience necessary! This DIY guide provides a practical introduction to microcontroller programming with MicroPython. Written by an experienced electronics hobbyist, Python for Microcontrollers: Getting Started with MicroPython features eight start-to-finish projects with clear, easy-to-follow instructions for each. You will learn how to use sensors, store data, control motors and other devices, and work with expansion boards. From there, you'll discover how to design, build, and program all kinds of entertaining and practical projects of your own. • Learn MicroPython and object-oriented programming basics • Interface with a PC and load files, programs, and modules • Work with the LEDs, timers, and converters • Control external devices using serial interfaces and PWM • Build and program a let ball detector using the three-axis accelerometer • Install and program LCD and touch-sensor expansion boards • Record and play sounds using the AMP audio board

Build exciting robotics projects such as mobile manipulators, self-driving cars, and industrial robots powered by ROS, machine learning, and virtual reality Key Features Create and program cool robotic projects using powerful ROS libraries Build industrial robots like mobile manipulators to handle complex tasks Learn how reinforcement learning and deep learning are used with ROS Book Description Nowadays, heavy industrial robots placed in workcells are being replaced by new age robots called cobots, which don't need workcells. They are used in manufacturing, retail, banks, energy, and healthcare, among other domains. One of the major reasons for this rapid growth in the robotics market is the introduction of an open source robotics framework called the Robot Operating System (ROS). This book covers projects in the latest ROS distribution, ROS Melodic Morenia with Ubuntu Bionic (18.04). Starting with the fundamentals, this updated edition of ROS Robotics Projects introduces you to ROS-2 and helps you understand how it is different from ROS-1. You'll be able to model and build an industrial mobile manipulator in ROS and simulate it in Gazebo 9. You'll then gain insights into handling complex robot applications using state machines and working with multiple robots at a time. This ROS book also introduces you to new and popular hardware such as Nvidia's Jetson Nano, Asus Tinker Board, and Beaglebone Black, and allows you to explore interfacing with ROS. You'll learn as you build interesting ROS projects such as self-driving cars, making use of deep learning, reinforcement learning, and other key AI concepts. By the end of the book, you'll have gained the confidence to build interesting and intricate projects with ROS. What you will learn Grasp the basics of ROS and understand ROS applications Uncover how ROS-2 is different from ROS-1 Handle complex robot tasks using state machines Communicate with multiple robots and collaborate to build apps with them Explore ROS capabilities with the latest embedded boards such as Tinker Board S and Jetson Nano Discover how machine learning and deep learning techniques are used with ROS Build a self-driving car powered by ROS Teleoperate your robot using Leap Motion and a VR headset Who this book is for If you're a student, hobbyist, professional, or anyone with a passion for learning robotics and interested in learning about algorithms, motion control, and perception capabilities from scratch, this book is for you. This book is also ideal for anyone who wants to build a new product and for researchers to make the most of what's already available to create something new and innovative in the field of robotics.

Develop practical example projects with detailed explanations; combine the projects in a vast number of ways to create different robot designs, or work through them in sequence to discover the full capability of the BeagleBone Black. This book is for anyone who is curious about using new, low-cost hardware to create robotic projects that have previously been the domain of research labs, major universities or Defence departments. Some programming experience would be useful, but if you know how to use a personal computer,

you can use this book to construct far more complex systems than you would have thought possible.

Start building amazing projects with the Raspberry Pi right out of the box About This Book Explore the vast range of opportunities provided by Raspberry Pi and other hardware components such as a webcam, the Pi camera, and sensors Get hands-on experience with coding, networking, and hardware with the Raspberry Pi platform Learn through ample screenshots that offer a play-by-play account of how to implement Raspberry-Pi-based real-life projects Who This Book Is For What's the best way to learn how to use your Raspberry Pi? By example! If you want something exciting to do whilst getting to grips with what your Pi can offer, this is the book for you. With both simple and complex projects, you'll create a wide variety of cool toys and functions with your Raspberry Pi - all with minimal coding experience necessary. What You Will Learn Set up your Raspberry Pi and get it ready for some interesting real-life projects Work with images, videos, webcams, and the Pi camera and create amazing time-lapse videos Explore the amazing world of Minecraft Pi Get to know how to use PiGlow for GPIO programming Interface your Pi with Grove Sensors and implement IoT applications Build your own cluster with Raspberry Pi Understand the networking and network programming fundamentals In Detail Want to put your Raspberry Pi through its paces right out of the box? This tutorial guide is designed to get you learning all the tricks of the Raspberry Pi through building complete, hands-on hardware projects. Speed through the basics and then dive right in to development! Discover that you can do almost anything with your Raspberry Pi with a taste of almost everything. Get started with Pi Gaming as you learn how to set up Minecraft, and then program your own game with the help of Pygame. Turn the Pi into your own home security system with complete guidance on setting up a webcam spy camera and OpenCV computer vision for image recognition capabilities. Get to grips with GPIO programming to make a Pi-based glowing LED system, build a complete functioning motion tracker, and more. Finally, get ready to tackle projects that push your Pi to its limits. Construct a complete Internet of Things home automation system with the Raspberry Pi to control your house via Twitter; turn your Pi into a super-computer through linking multiple boards into a cluster and then add in advanced network capabilities for super speedy processing! Style and approach This step-by-step guide to building Raspberry-Pi-based projects is explained in a conversational and easy-to-follow style. Each topic is explained sequentially in the process of creating real-life projects, and detailed explanations of the basic and advanced features of various Python libraries are also included.

In-depth instruction and practical techniques for buildingwith the BeagleBone embedded Linux platform Exploring BeagleBone is a hands-on guide to bringinggadgets, gizmos, and robots to life using the popular BeagleBoneembedded Linux platform. Comprehensive content and deep detailprovide more than just a BeagleBone instructionmanual—you'll also learn the underlying engineeringtechniques that will allow you to create your own projects. Thebook begins with a foundational primer on essential skills, andthen gradually moves into communication, control, and advancedapplications using C/C++, allowing you to learn at your own pace.In addition, the book's companion website featuresinstructional videos, source code, discussion forums, and more, toensure that you have everything you need. The BeagleBone's small size, high performance, low cost,and extreme adaptability have made it a favorite developmentplatform, and the Linux software base allows for complex yetflexible functionality. The BeagleBone has applications in smartbuildings, robot control, environmental sensing, to name a few;and, expansion boards and peripherals dramatically increase thepossibilities. Exploring BeagleBone provides areader-friendly guide to the device, including a crash coursein computer engineering. While following step by step, you can: Get up to speed on embedded Linux, electronics, andprogramming Master interfacing electronic circuits, buses and modules, withpractical examples Explore the Internet-connected BeagleBone and the BeagleBonewith a display Apply the BeagleBone to sensing applications, including videoand sound Explore the BeagleBone's Programmable Real-TimeControllers Hands-on learning helps ensure that your new skills stay withyou, allowing you to design with electronics, modules, orperipherals even beyond the BeagleBone. Insightful guidance andonline peer support help you transition from beginner to expert asyou master the techniques presented in Exploring BeagleBone,the practical handbook for the popular computing platform.

Design, build, and program your own remarkable robots with JavaScript and open source hardware About This Book Learn how to leverage Johnny-Five's Read, Eval, Print Loop, and Event API to write robot code with JavaScript Unlock a world of exciting possibilities by hooking your JavaScript-programmed robots up to the internet and using external data and APIs Move your project code from the Arduino Uno to a multitude of other robotics platforms Who This Book Is For If you've worked with Arduino before or are new to electronics and would like to try writing sketches in JavaScript, then this book is for you! Basic knowledge of JavaScript and Node.js will help you get the most out of this book. What You Will Learn Familiarise yourself with Johnny-Five Read, Eval, and Print Loop (REPL) to modify and debug robotics code in real time Build robots with basic output devices to create projects that light up, make noise, and more Create projects with complex output devices, and employ the Johnny-Five API to simplify the use of components that require complex interfaces, such as I2C Make use of sensors and input devices to allow your robotics projects to survey the world around them and accept input from users Use the Sensor and Motor objects to make it much easier to move your robotics projects Learn about the Animation API that will allow you to program complex movements using timing and key frames Bring in other devices to your Johnny-Five projects, such as USB devices and remotes Connect your Johnny-Five projects to external APIs and create your own Internet of Things! In Detail There has been a rapid rise in the use of JavaScript in recent times in a variety of applications, and JavaScript robotics has seen a rise in popularity too. Johnny-Five is a framework that gives NodeBots a consistent API and platform across several hardware systems. This book walks you through basic robotics projects including the physical hardware builds and the JavaScript code for them. You'll delve into the concepts of Johnny-Five and JS robotics. You'll learn about various

components such as Digital GPIO pins, PWM output pins, Sensors, servos, and motors to be used with Johnny-Five along with some advanced components such as I2C, and SPI. You will learn to connect your Johnny-Five robots to internet services and other NodeBots to form networks. By the end of this book, you will have explored the benefits of the Johnny-Five framework and the many devices it unlocks. Style and approach This step-by-step guide to the Johnny-Five ecosystem is explained in a conversational style, packed with examples and tips. Each chapter also explores the Johnny-Five documentation to enable you to start exploring the API on your own.

BeagleBone is an inexpensive web server, Linux desktop, and electronics hub that includes all the tools you need to create your own projects—whether it's robotics, gaming, drones, or software-defined radio. If you're new to BeagleBone Black, or want to explore more of its capabilities, this cookbook provides scores of recipes for connecting and talking to the physical world with this credit-card-sized computer. All you need is minimal familiarity with computer programming and electronics. Each recipe includes clear and simple wiring diagrams and example code to get you started. If you don't know what BeagleBone Black is, you might decide to get one after scanning these recipes. Learn how to use BeagleBone to interact with the physical world Connect force, light, and distance sensors Spin servo motors, stepper motors, and DC motors Flash single LEDs, strings of LEDs, and matrices of LEDs Manage real-time input/output (I/O) Work at the Linux I/O level with shell commands, Python, and C Compile and install Linux kernels Work at a high level with JavaScript and the BoneScript library Expand BeagleBone's functionality by adding capes Explore the Internet of Things

If you are a programmer, scientist, or someone interested in modern computer technology that goes beyond the typical PC, then this book will show you the outstanding possibilities of cluster computing with modern embedded systems based on ARM architecture. Whether you need a high-speed or low-cost scalable cluster for simulations or want to try something new, this book is the right guide for you.

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