Beaglebone Robotic Projects Grimmett Richard

BeagleBone Black is a low-cost, open hardware computer uniquely suited to interact with sensors and actuators directly and over the Web. Introduced in April 2013 by BeagleBoard.org, a community of developers first established in early 2008, BeagleBone Black is used frequently to build vision-enabled robots, home automation systems, artistic lighting systems, and countless other do-it-yourself and professional projects. BeagleBone variants include the original BeagleBone and the newer BeagleBone Black, both hosting a powerful 32-bit, super-scalar ARM Cortex A8 processor capable of running numerous mobile and desktop-capable operating systems, typically variants of Linux including Debian, Android, and Ubuntu. Yet, BeagleBone is small enough to fit in a small mint tin box. The "Bone" may be used in a wide variety of projects from middle school science fair projects to senior design projects to first prototypes of very complex systems. Novice users may access the power of the Bone through the user-friendly BoneScript software, experienced through a Web browser in most major operating systems, including Microsoft Windows, Apple Mac OS X, or the Linux operating systems. Seasoned users may take full advantage of the Bone's power using the underlying Linux-based operating system, a host of feature extension boards (Capes) and a wide variety of Linux community open source libraries. This book provides an introduction to this powerful computer and has been designed for a wide variety of users including the first time novice through the seasoned embedded system design professional. The book contains background theory on system operation coupled with many well-documented, illustrative examples. Examples for novice users are centered on motivational, fun robot projects while advanced projects follow the theme of assistive technology and image-processing applications.

A dozen fiendishly fun projects for the Raspberry Pi! This wickedly inventive guide shows you how to create all kinds of entertaining and practical projects with Raspberry Pi operating system and programming environment. In Raspberry Pi Projects for the Evil Genius, you'll learn how to build a Bluetooth-controlled robot, a weather station, home automation and security controllers, a universal remote, and even a minimalist website. You'll also find out how to establish communication between Android devices and the RasPi. Each fun, inexpensive Evil Genius project includes a detailed list of materials, sources for parts, schematics, and lots of clear, well-illustrated instructions for easy assembly. The larger workbook-style layout makes following the step-by-step instructions a breeze. Build these and other devious devices: LED blinker MP3 player Camera controller Bluetooth robot Earthquake detector Home automation controller Weather station Home security controller RFID door latch Remote power controller Radon detector Make Great Stuff! TAB, an imprint of McGraw-Hill Professional, is a leading publisher of DIY technology books for makers, hackers, and electronics

hobbyists.

The Raspberry Pi B2 is an inexpensive embedded processor that provides a high-performance Linux development environment. This book is a fast-paced guide that will show you how to use Raspberry Pi technology to build a biped robot that can interact with its environment. We start off by explaining the basics of getting your Raspberry Pi up and running, ready to be mounted on your biped platform. After this, you will be introduced to the art of constructing a mechanism for the biped platform. You will then learn to develop a vision system for your robot, as well as a means by which you can control and monitor it. At the end of this book, you will have learned enough to build a complex biped robot that can walk, turn, find its way, and "see" its environment.

BeagleBone is an inexpensive web server, Linux desktop, and electronics hub that includes all the tools you need to create your own projects—whether it's robotics, gaming, drones, or software-defined radio. If you're new to BeagleBone Black, or want to explore more of its capabilities, this cookbook provides scores of recipes for connecting and talking to the physical world with this credit-card-sized computer. All you need is minimal familiarity with computer programming and electronics. Each recipe includes clear and simple wiring diagrams and example code to get you started. If you don't know what BeagleBone Black is, you might decide to get one after scanning these recipes. Learn how to use BeagleBone to interact with the physical world Connect force, light, and distance sensors Spin servo motors, stepper motors, and DC motors Flash single LEDs, strings of LEDs, and matrices of LEDs Manage real-time input/output (I/O) Work at the Linux I/O level with shell commands, Python, and C Compile and install Linux kernels Work at a high level with JavaScript and the BoneScript library Expand BeagleBone's functionality by adding capes Explore the Internet of Things

Learn how to use a Raspberry Pi in conjunction with an Arduino to build a basic robot with advanced capabilities. Getting started in robotics does not have to be difficult. This book is an insightful and rewarding introduction to robotics and a catalyst for further directed study. You'll be led step by step through the process of building a robot that uses the power of a Linux based computer paired with the simplicity of Arduino. You'll learn why the Raspberry Pi is a great choice for a robotics platform; its strengths as well as its shortcomings; how to overcome these limitations by implementing an Arduino; and the basics of the Python programming language as well as some of the more powerful features. With the Raspberry Pi you can give your project the power of a Linux computer, while Arduino makes interacting with sensors and motors very easy. These two boards are complimentary in their functions; where one falters the other performs admirably. The book also includes references to other great works to help further your growth in the exciting, and now accessible, field of smart robotics. As a bonus, the final chapter of the book demonstrates the real power of the

Raspberry Pi by implementing a basic vision system. Using OpenCV and a standard USB web cam, you will build a robot that can chase a ball. What You'll Learn Install Raspbian, the operating system that drives the Raspberry Pi Drive motors through an I2C motor controller Read data through sensors attached to an Arduino Who This Book Is For Hobbyists and students looking for a rapid start in robotics. It assumes no technical background. Readers are guided to pursue the areas that interest them in more detail as they learn.

Many people think of Linux as a computer operating system, running on users' desktops and powering servers. But Linux can also be found inside many consumer electronics devices. Whether they're the brains of a cell phone, cable box, or exercise bike, embedded Linux systems blur the distinction between computer and device. Many makers love microcontroller platforms such as Arduino, but as the complexity increases in their projects, they need more power for applications, such as computer vision. The BeagleBone is an embedded Linux board for makers. It's got built-in networking, many inputs and outputs, and a fast processor to handle demanding tasks. This book introduces you to both the original BeagleBone and the new BeagleBone Black and gets you started with projects that take advantage of the board's processing power and its ability to interface with the outside world.

Simon introduces the broad range of applications for embedded software and then reviews each major issue facing developers, offering practical solutions, techniques, and good habits that apply no matter which processor, real-time operating systems, methodology, or application is used.

This book is for enthusiasts who want to use the Raspberry Pi to build complex robotics projects. With the aid of the step-by-step instructions in this book, you can construct complex robotics projects that can move, talk, listen, see, swim, or fly. No previous Raspberry Pi robotics experience is assumed, but even experts will find unexpected and interesting information in this invaluable guide.

This book begins with the premise that energy demands are directing scientists towards ever-greener methods of power management, so highly integrated power control ICs (integrated chip/circuit) are increasingly in demand for further reducing power consumption. A timely and comprehensive reference guide for IC designers dealing with the increasingly widespread demand for integrated low power management Includes new topics such as LED lighting, fast transient response, DVS-tracking and design with advanced technology nodes Leading author (Chen) is an active and renowned contributor to the power management IC design field, and has extensive industry experience Accompanying website includes presentation files with book illustrations, lecture notes, simulation circuits, solution manuals, instructors' manuals, and program downloads

Exciting new capabilities to enable even easier DIY robotics with BeagleBone BlueAbout This Book* Build powerful

robots with the all new BeagleBone Blue* Communicate with your robot and teach it to detect and respond to its environment* Control walking, rolling, swimming, and flying robots with your iOS and Android mobile devicesWho This Book Is ForThis book is for anyone who is curious about using new, low-cost hardware to create robotic projects and have previously been the domain of research labs, major universities, or defence departments. Some programming experience would be useful, but if you know how to use a personal computer, you can use this book to construct far more complex systems than you would have thought possible.What You Will Learn* Power on and configure the BeagleBone Blue* Get to know Simple programming techniques to enable the unique hardware capabilities of the BeagleBone Blue.* Connect standard hardware to enable your projects to see, speak, hear, and move* Build advanced capabilities into your projects, such as GPS and sonar sensors* Build complex projects that can fly, or go under or on the waterIn DetailBeagleBone Blue is effectively a small, light, cheap computer in a similar vein to Raspberry Pi and Arduino. It has all of the extensibility of today's desktop machines, but without the bulk, expense, or noise. This project guide provides step-by-step instructions that enable anyone to use this new, low-cost platform in some fascinating robotics projects. By the time you are finished, your projects will be able to see, speak, listen, detect their surroundings, and move in a variety of amazing ways.The book begins with unpacking and powering up the components. This includes guidance on what to purchase and how to connect it all successfully, and a primer on programming the BeagleBone Blue. You will add additional software functionality available from the open source community, including making the system see using a webcam, hear using a microphone, and speak using a speaker.You will then learn to use the new hardware capability of the BeagleBone Blue to make your robots move, as well as discover how to add sonar sensors to avoid or find objects. Later, you will learn to remotely control your robot through iOS and Android devices. At the end of this book, you will see how to integrate all of these functionalities to work together, before developing the most impressive robotics projects: Drone and Submarine.Style and approachDevelop practical example projects with detailed explanations, combine the projects in a vast number of ways to create different robot designs, or work through them in sequence to discover the full capability of the BeagleBone Blue.

If you are a developer with some hardware or electrical engineering experience who wants to learn how to use embedded machine-learning capabilities and get access to a GNU/Linux device driver to collect data from a peripheral or to control a device, this is the book for you.

Master the capabilities of Qlik Sense to design and deploy solutions that address all the Business Intelligence needs of your organization Key Features Create compelling dashboards and visualizations with your data by leveraging Qlik Sense's self-service model Perform data loading and model efficient solutions with faster performance and better

governance Master Qlik Sense's APIs and develop powerful mashups and fantastic extensions for visualizations and other components that run across all platforms Book Description Qlik Sense is a powerful, self-servicing Business Intelligence tool for data discovery, analytics and visualization. It allows you to create personalized Business Intelligence solutions from raw data and get actionable insights from it. This book is your one-stop guide to mastering Qlik Sense, catering to all your organizational BI needs. You'll see how you can seamlessly navigate through tons of data from multiple sources and take advantage of the various APIs available in Qlik and its components for guided analytics. You'll also learn how to embed visualizations into your existing BI solutions and extend the capabilities of Qlik Sense to create new visualizations and dashboards that work across all platforms. We also cover other advanced concepts such as porting your Qlik View applications to Qlik Sense,and working with Qlik Cloud. Finally, you'll implement enterprise-wide security and access control for resources and data sources through practical examples. With the knowledge gained from this book, you'll have become the go-to expert in your organization when it comes to designing BI solutions using Qlik Sense. What you will learn Understand the importance of self-service analytics and the IKEA-effect Explore all the available data modeling techniques and create efficient and optimized data models Master security rules and translate permission requirements into security rule logic Familiarize yourself with different types of Master Key Item(MKI) and know how and when to use MKI. Script and write sophisticated ETL code within Qlik Sense to facilitate all data modeling and data loading techniques Get an extensive overview of which APIs are available in Qlik Sense and how to take advantage of a technology with an API Develop basic mashup HTML pages and deploy successful mashup projects Who this book is for This book is for Business Intelligence professionals and Data Analysts who want to become experts in using Qlik Sense. If you have extensively used QlikView in the past and are looking to transition to Qlik Sense, this book will also help you. A fundamental understanding of how Qlik Sense works and its features is all you need to get started with this book.

In-depth instruction and practical techniques for buildingwith the BeagleBone embedded Linux platform Exploring BeagleBone is a hands-on guide to bringinggadgets, gizmos, and robots to life using the popular BeagleBoneembedded Linux platform. Comprehensive content and deep detailprovide more than just a BeagleBone instructionmanual—you'll also learn the underlying engineeringtechniques that will allow you to create your own projects. Thebook begins with a foundational primer on essential skills, andthen gradually moves into communication, control, and advancedapplications using C/C++, allowing you to learn at your own pace.In addition, the book's companion website featuresinstructional videos, source code, discussion forums, and more, toensure that you have everything you need. The BeagleBone's small size, high performance, low cost,and extreme adaptability have made it a favorite developmentplatform, and the

Linux software base allows for complex yetflexible functionality. The BeagleBone has applications in smartbuildings, robot control, environmental sensing, to name a few;and, expansion boards and peripherals dramatically increase thepossibilities. Exploring BeagleBone provides areader-friendly guide to the device, including a crash coursein computer engineering. While following step by step, you can: Get up to speed on embedded Linux, electronics, andprogramming Master interfacing electronic circuits, buses and modules, withpractical examples Explore the Internet-connected BeagleBone and the BeagleBonewith a display Apply the BeagleBone to sensing applications, including videoand sound Explore the BeagleBone's Programmable Real-TimeControllers Hands-on learning helps ensure that your new skills stay withyou, allowing you to design with electronics, modules, orperipherals even beyond the BeagleBone. Insightful guidance andonline peer support help you transition from beginner to expert asyou master the techniques presented in Exploring BeagleBone,the practical handbook for the popular computing platform.

Exciting new capabilities to enable even easier DIY robotics with BeagleBone Blue About This Book Build powerful robots with the all new BeagleBone Blue Communicate with your robot and teach it to detect and respond to its environment Control walking, rolling, swimming, and flying robots with your iOS and Android mobile devices Who This Book Is For This book is for anyone who is curious about using new, low-cost hardware to create robotic projects and have previously been the domain of research labs, major universities, or defence departments. Some programming experience would be useful, but if you know how to use a personal computer, you can use this book to construct far more complex systems than you would have thought possible. What You Will Learn Power on and configure the BeagleBone Blue Get to know Simple programming techniques to enable the unique hardware capabilities of the BeagleBone Blue. Connect standard hardware to enable your projects to see, speak, hear, and move Build advanced capabilities into your projects, such as GPS and sonar sensors Build complex projects that can fly, or go under or on the water In Detail BeagleBone Blue is effectively a small, light, cheap computer in a similar vein to Raspberry Pi and Arduino. It has all of the extensibility of today's desktop machines, but without the bulk, expense, or noise. This project guide provides step-by-step instructions that enable anyone to use this new, low-cost platform in some fascinating robotics projects. By the time you are finished, your projects will be able to see, speak, listen, detect their surroundings, and move in a variety of amazing ways. The book begins with unpacking and powering up the components. This includes guidance on what to purchase and how to connect it all successfully, and a primer on programming the BeagleBone Blue. You will add additional software functionality available from the open source community, including making the system see using a webcam, hear using a microphone, and speak using a speaker. You will then learn to use the new hardware capability of the BeagleBone Blue to make your robots move, as well as discover how to add sonar sensors to avoid or find objects.

Later, you will learn to remotely control your robot through iOS and Android devices. At the end of this book, you will see how to integrate all of these functionalities to work together, before developing the most impressive robotics projects: Drone and Submarine. Style and approach Develop practical example projects with detailed explanations, combine the projects in a vast number of ways to create different robot designs, or work through them in sequence to discover the full capability of the BeagleBone Blue.

Utilize the powerful ingredients of Raspberry Pi to bring to life your amazing robots that can act, draw, and have fun with laser tags About This Book Learn to implement a number of features offered by Raspberry Pi to build your own amazing robots Understand how to add vision and voice to your robots. This fast-paced practical guide comprises a number of creative projects to take your Raspberry Pi knowledge to the next level Who This Book Is For This all-encompassing guide was created for anyone who is interested in expanding their knowledge in applying the peripherals of Raspberry Pi. If you have a fancy for building complex-looking robots with simple, inexpensive, and readily available hardware, then this book is ideal for you. Prior understanding of Raspberry Pi with simple mechanical systems is recommended. What You Will Learn Add sensors to your robot so that it can sense the world around it Know everything there is to know about accessing motors and servos to provide movement to the robotic platform Explore the feature of adding vision to your robot so it can "see" the world around it Refine your robot with the skill of speech recognition so that it can receive commands Polish your robot by adding speech output so it can communicate with the world around it Maximize the use of servos in Raspberry Pi to create a drawing robot Strengthen your robot by adding wireless communication skills so you can see what the robot is seeing and control it from a distance Build an unbelievable autonomous hexcopter controlled by Raspberry Pi In Detail The Raspberry Pi is a series of credit card-sized single-board computers developed in the UK by the Raspberry Pi Foundation with the intention of promoting the teaching of basic computer science in schools. The Raspberry Pi is known as a tiny computer built on a single circuit board. It runs a Linux operating system, and has connection ports for various peripherals so that it can be hooked up to sensors, motors, cameras, and more. Raspberry Pi has been hugely popular among hardware hobbyists for various projects, including robotics. This book gives you an insight into implementing several creative projects using the peripherals provided by Raspberry Pi. To start, we'll walk through the basic robotics concepts that the world of Raspberry Pi offers us, implementing wireless communication to control your robot from a distance. Next, we demonstrate how to build a sensible and a visionary robot, maximizing the use of sensors and step controllers. After that, we focus on building a wheeled robot that can draw and play hockey. To finish with a bang, we'll build an autonomous hexcopter, that is, a flying robot controlled by Raspberry Pi. By the end of this book, you will be a maestro in applying an array of different technologies to create almost any imaginable robot. Style

and approach This book is an easy-to-follow, project-based guide that throws you directly into the action of creating almost any imaginable robot through blueprints. It is full of step by step instructions and screenshots to help you build amazing robots in no time at all.

If you want a simple guide to building complex robots, then this book is for you. You'll need some programming knowledge and experience working with mechanical systems.

Develop practical example projects with detailed explanations; combine the projects in a vast number of ways to create different robot designs, or work through them in sequence to discover the full capability of the BeagleBone Black. This book is for anyone who is curious about using new, low-cost hardware to create robotic projects that have previously been the domain of research labs, major universities or Defence departments. Some programming experience would be useful, but if you know how to use a personal computer, you can use this book to construct far more complex systems than you would have thought possible.

Learn to build amazing robotic projects using the powerful BeagleBone Black. About This Book Push your creativity to the limit through complex, diverse, and fascinating projects Develop applications with the BeagleBone Black and open source Linux software Sharpen your expertise in making sophisticated electronic devices Who This Book Is For This Learning Path is aimed at hobbyists who want to do creative projects that make their life easier and also push the boundaries of what can be done with the BeagleBone Black. This Learning Path's projects are for the aspiring maker, casual programmer, and budding engineer or tinkerer. You'll need some programming knowledge, and experience of working with mechanical systems to get the complete experience from this Learning Path. What You Will Learn Set up and run the BeagleBone Black for the first time Get to know the basics of microcomputing and Linux using the command line and easy kernel mods Develop a simple web interface with a LAMP platform Prepare complex web interfaces in JavaScript and get to know how to stream video data from a webcam Find out how to use a GPS to determine where your sailboat is, and then get the bearing and distance to a new waypoint Use a wind sensor to sail your boat effectively both with and against the wind Build an underwater ROV to explore the underwater world See how to build an autonomous Quadcopter In Detail BeagleBone is a microboard PC that runs Linux. It can connect to the Internet and run OSes such as Android and Ubuntu. You can transform this tiny device into a brain for an embedded application or an endless variety of electronic inventions and prototypes. This Learning Path starts off by teaching you how to program the BeagleBone. You will create introductory projects to get yourselves acquainted with all the nitty gritty. Then we'll focus on a series of projects that are aimed at hobbyists like you and encompass the areas of home automation and robotics. With each project, we'll teach you how to connect several sensors and an actuator to the BeagleBone Black. We'll also create

robots for land, sea, and water. Yes, really! The books used in this Learning Path are: BeagleBone Black Cookbook BeagleBone Home Automation Blueprints Mastering BeagleBone Robotics Style and approach This practical guide transforms complex and confusing pieces of technology to become accessible with easy- to-succeed instructions. Through clear, concise examples, you will quickly get to grips with the core concepts needed to develop home automation applications with the BeagleBone Black.

Master multithreading and concurrent processing with C++ About This Book Delve into the fundamentals of multithreading and concurrency and find out how to implement them Explore atomic operations to optimize code performance Apply concurrency to both distributed computing and GPGPU processing Who This Book Is For This book is for intermediate C++ developers who wish to extend their knowledge of multithreading and concurrent processing. You should have basic experience with multithreading and be comfortable using C++ development toolchains on the command line. What You Will Learn Deep dive into the details of the how various operating systems currently implement multithreading Choose the best multithreading APIs when designing a new application Explore the use of mutexes, spin-locks, and other synchronization concepts and see how to safely pass data between threads Understand the level of API support provided by various C++ toolchains Resolve common issues in multithreaded code and recognize common pitfalls using tools such as Memcheck, CacheGrind, DRD, Helgrind, and more Discover the nature of atomic operations and understand how they can be useful in optimizing code Implement a multithreaded application in a distributed computing environment Design a C++-based GPGPU application that employs multithreading In Detail Multithreaded applications execute multiple threads in a single processor environment, allowing developers achieve concurrency. This book will teach you the finer points of multithreading and concurrency concepts and how to apply them efficiently in C++. Divided into three modules, we start with a brief introduction to the fundamentals of multithreading and concurrency concepts. We then take an in-depth look at how these concepts work at the hardware-level as well as how both operating systems and frameworks use these low-level functions. In the next module, you will learn about the native multithreading and concurrency support available in C++ since the 2011 revision, synchronization and communication between threads, debugging concurrent C++ applications, and the best programming practices in C++. In the final module, you will learn about atomic operations before moving on to apply concurrency to distributed and GPGPU-based processing. The comprehensive coverage of essential multithreading concepts means you will be able to efficiently apply multithreading concepts while coding in C++. Style and approach This book is filled with examples that will help you become a master at writing robust concurrent and parallel applications in C++.

This book is for anyone who has been curious about using Arduino to create robotic projects that were previously the

domain of research labs of major universities or defense departments. Some programming background is useful, but if you know how to use a PC, you can, with the aid of the step-by-step instructions in this book, construct complex robotic projects that can roll, walk, swim, or fly.

Fighting, biting, screaming and other behaviours that challenge the people dealing with them are often triggered by unsuitable surroundings or unrealistic demands. In this fresh and effective approach, Bo Hejlskov Elvén shows how identifying and adapting these problem areas can dramatically improve behaviour in people with autism and other developmental disabilities. This practical book explains how to reassess difficult situations and offers easy and effective strategies for eliciting positive responses without resorting to restraint and punishment. Based on the successful low-arousal approach, it is a proven method of stepping away from distress and towards calm, improving the quality of life of everyone involved. Helpful examples covering a wide range of developmental disabilities from autism to Down's Syndrome illustrate the positive changes that can be achieved. This empowering book will be invaluable to anyone attempting to deal with unproductive behaviour in individuals with developmental disabilities, whether at home or in a professional environment.

iOS 11, Swift 4, and Xcode 9 provide many new APIs for iOS developers. With this cookbook, you'll learn more than 170 proven solutions for tackling the latest features in iOS 11 and watchOS 4, including new ways to use Swift and Xcode to make your day-to-day app development life easier. This collection of code-rich recipes also gets you up to speed on continuous delivery and continuous integration systems. Ideal for intermediate and advanced iOS developers looking to work with the newest version of iOS, these recipes include reusable code on GitHub, so you can put them to work in your project right away. Among the topics covered in this book: New features in Swift 4 and Xcode 9 Tools for continuous delivery and continuous integration Snapshot testing and test automation Creating document-based applications Updated Map view and Core Location features iOS 11's Security and Password Autofill Data storage with Apple's Core Data Creating lively user interfaces with UI Dynamics Building iMessage applications and sticker packages Integrating Siri into your apps with Siri Kit Creating fascinating apps for Apple Watch

Building a Home Security System with BeagleBone is a practical, hands-on guide for practical, hands-on people. The book includes step-by-step instructions for assembling your own hardware on professionally manufactured PCB's and setting up the software on your system. This book is for anyone who is interested in alarm systems and how they work; for hobbyists and basement tinkerers who love to build things. If you want to build the hardware described in this book, you will need some basic soldering skills, but all the parts are of the thru-hole variety and are very easy to put together. When it comes to software, you can just run it as-is, but if you want to modify the code, you will need knowledge of Java

and IDEs.

This book is for programmers and developers who want to improve the performance of their R programs by making them run faster with large data sets or who are trying to solve a pesky performance problem.

An audience-centered approach to public speaking Public Speaking: An Audience-Centered Approach brings theory and practice together. Its distinctive and popular approach emphasizes the importance of analyzing and considering the audience at every point in the speech making process. This model of public speaking is the foundation of the text, and it guides students through the step-by-step process of public speaking, focusing their attention on the dynamics of diverse audiences, and narrowing the gap between the classroom and the real world. MyCommunicationLab is an integral part of the Beebe/Beebe program. MyCommunicationLab is an integral part of the Beebe/Beebe program. With extensive opportunities for the application of course content, MyCommunicationLab helps students become better speakers and master key public speaking concepts. Interactive videos provide students with the opportunity to watch and evaluate sample speeches. Online self-assessments and pre- and post-tests help students assess their comfort level with public speaking and their knowledge of the material. MediaShare allows students to post speeches and share them with classmates and instructors. ALERT: Before you purchase, check with your instructor or review your course syllabus to ensure that you select the correct ISBN. Several versions of Pearson's MyLab & Mastering products exist for each title, including customized versions for individual schools, and registrations are not transferable. In addition, you may need a CourseID, provided by your instructor, to register for and use Pearson's MyLab & Mastering products. Packages Access codes for Pearson's MyLab & Mastering products may not be included when purchasing or renting from companies other than Pearson; check with the seller before completing your purchase. Used or rental books If you rent or purchase a used book with an access code, the access code may have been redeemed previously and you may have to purchase a new access code. Access codes Access codes that are purchased from sellers other than Pearson carry a higher risk of being either the wrong ISBN or a previously redeemed code. Check with the seller prior to purchase. --

Start programming robots NOW! Learn hands-on, through easy examples, visuals, and code This is a unique introduction to programming robots to execute tasks autonomously. Drawing on years of experience in artificial intelligence and robot programming, Cameron and Tracey Hughes introduce the reader to basic concepts of programming robots to execute tasks without the use of remote controls. Robot Programming: A Guide to Controlling Autonomous Robots takes the reader on an adventure through the eyes of Midamba, a lad who has been stranded on a desert island and must find a way to program robots to help him escape. In this guide, you are presented with practical approaches and techniques to program robot sensors, motors, and translate your ideas into tasks a robot can execute autonomously. These techniques can be used on today's leading robot microcontrollers (ARM9 and ARM7) and robot platforms (including the wildly popular low-cost Arduino platforms, LEGO® Mindstorms EV3, NXT, and Wowee RS Media Robot) for your hardware/Maker/DIY projects. Along the way the reader will learn how to: Program robot sensors and motors Program a robot arm to perform a task Describe the robot's tasks and environments in a way that a robot can process using robot S.T.O.R.I.E.S. Develop a R.S.V.P. (Robot Scenario Visual Planning) used for designing the robot's tasks in an environment Program a robot to deal with the "unexpected" using robot S.P.A.C.E.S. Program robots safely using S.A.R.A.A. (Safe Autonomous Robot Application Architecture) Approach Program robots using Arduino C/C++ and Java languages Use robot programming techniques with LEGO® Mindstorms EV3, Arduino, and other ARM7 and ARM9-based robots.

This new field guide is based on the authors' groundbreaking Birds of the Indian Subcontinent (1998) and covers all the bird species found in India, Pakistan, Sri Lanka, Nepal, Bhutan, Bangladesh and the Maldives. The plates face the descriptions and maps for quick at-a-glance reference. Many of the plates have been repainted for this edition and a number of new species added. This guide also provides tables, summarising identification features of particularly difficult groups such as nightjars, warblers and rosefinches.

Work through a mix of amazing robotic projects using the Raspberry Pi Zero or the Raspberry Pi 3 About This Book Easy to follow instructions, yet the ones that help you build powerful robots, and exclusive coverage of mobile robots with the Pi Zero Build robots that can run, swim and fly and the cutting-edge dimension of robotics that is possible with the Raspberry Pi Zero and Pi 3 Interact with your projects wirelessly and make sci-fi possible, right in your home Who This Book Is For This book is for hobbyists and programmers who are excited about using the Raspberry Pi 3 and Raspberry Pi Zero. It is for those who are taking their first steps towards using these devices to control hardware and software and write simple programs that enable amazing projects. No programming experience is required, Just a little computer and mechanical aptitude and the desire to build some interesting projects. What You Will Learn Control a variety of different DC motors Add a USB webcam to see what your robot can see Attach a projector to project information Insert USB control hardware to control a complex robot with two legs Include speech recognition so that your projects can receive commands Add speech output to that the robot can communicate with the world around it Include wireless communication so that you can see what the robot is seeing and control the robot from a distance In Detail This book will allow you to take full advantage of Raspberry Pi Zero and Raspberry Pi 3 by building both simple and complex robotic projects. The book takes a mission-critical approach to show you how to build amazing robots and helps you decide which board to use for which type of robot. The book puts a special emphasis on designing mobile (or movable) robots using the Raspberry Pi Zero. The projects will show inexpensive, yet powerful, ways to take full advantage. It will teach you how to program Raspberry Pi, control the movement of your robot, and add features to your robots. Style and approach This fun and practical tutorial contain step-by-step instructions to get you hands-on building inexpensive projects. It contains mission-critical chapters and everything you need to know to get started.

Start building amazing projects with the Raspberry Pi right out of the box About This Book Explore the vast range of opportunities provided by Raspberry Pi and other hardware components such as a webcam, the Pi camera, and sensors Get hands-on experience with coding, networking, and hardware with the Raspberry Pi platform Learn through ample screenshots that offer a play-by-play account of how to implement Raspberry-Pi-based real-life projects Who This Book Is For What's the best way to learn how to use your Raspberry Pi? By example! If you want something exciting to do whilst getting to grips with what your Pi can offer, this is the book for you. With both simple and complex projects, you'll create a wide variety of cool toys and functions with your Raspberry Pi - all with minimal coding experience necessary. What You Will Learn Set up your Raspberry Pi and get it ready for some interesting real-life projects Work with images, videos, webcams, and the Pi camera and create amazing time-lapse videos Explore the amazing world of Minecraft Pi Get to know how to use PiGlow for GPIO programming Interface your Pi with Grove Sensors and implement IoT applications Build your own cluster with Raspberry Pi Understand the networking and network programming fundamentals In Detail Want to put your Raspberry Pi through its paces right out of the box? This tutorial guide is designed to get you learning all the tricks of the Raspberry Pi through building complete, hands-on hardware projects. Speed through the basics and then dive right in to development! Discover that you can do almost anything with your Raspberry Pi with a taste of almost everything. Get started with Pi Gaming as you learn how to set up Minecraft, and then program your own game with the help of Pygame. Turn the Pi into your own home security system with complete guidance on setting up a webcam spy camera and OpenCV

computer vision for image recognition capabilities. Get to grips with GPIO programming to make a Pi-based glowing LED system, build a complete functioning motion tracker, and more. Finally, get ready to tackle projects that push your Pi to its limits. Construct a complete Internet of Things home automation system with the Raspberry Pi to control your house via Twitter; turn your Pi into a super-computer through linking multiple boards into a cluster and then add in advanced network capabilities for super speedy processing! Style and approach This step-by-step guide to building Raspberry-Pi-based projects is explained in a conversational and easy-to-follow style. Each topic is explained sequentially in the process of creating real-life projects, and detailed explanations of the basic and advanced features of various Python libraries are also included.

This book follows a step-by-step, tutorial-based approach which will teach you how to develop your own super cluster using Raspberry Pi computers quickly and efficiently. Raspberry Pi Super Cluster is an introductory guide for those interested in experimenting with parallel computing at home. Aimed at Raspberry Pi enthusiasts, this book is a primer for getting your first cluster up and running. Basic knowledge of C or Java would be helpful but no prior knowledge of parallel computing is necessary.

Design and build land, air, and sea drones using Ardupilot with Pixhawk 2.1 About This Book Explore the best practices used by the top industry professionals that will not only help you build drones in time, but also build effective solutions to cater to. Navigate through the complexities of Ardupilot to put together a complete functional UAV and assemble your drone Learn through practical examples that help you build robust UAV flight and ground control components Who This Book Is For The primary audience for this book is anyone (enthusiasts and hobbyists) who dream of building their own drones. It will also help those who are trying to build UAVs for commercial purposes. Some prior experience with microcontrollers and electronics would be useful. What You Will Learn Kitbash "dumb" objects into smart ones Program Pixhawk for your drones Fabricate your own parts out of different materials Integrate Pixhawk into different types of drones Build and understand the significant difference between land, sea, and air drones Adapt old Pixhawk sensors to the new Pixhawk 2.1 plugs Become familiar with procedures for testing your new drones In Detail The Ardupilot platform is an application ecosystem that encompasses various OS projects for drone programming, flight control, and advanced functionalities.The Ardupilot platform supports many Comms and APIs, such as DroneKit, ROS, and MAVLink. It unites OS drone projects to provide a common codebase. With the help of this book, you will have the satisfaction of building a drone from scratch and exploring its many recreational uses (aerial photography, playing, aerial surveillance, and so on). This book helps individuals and communities build powerful UAVs for both personal and commercial purposes. You will learn to unleash the Ardupilot technology for building, monitoring, and controlling your drones.This is a step-by-step guide covering practical examples and instructions for assembling a drone, building ground control unit using microcontrollers, QgroundControl, and MissionPlanner. You can further build robotic applications on your drone utilizing critical software libraries and tools from the ROS framework. With the help of DroneKit and MAVLink (for reliable communication), you can customize applications via cloud and mobile to interact with your UAV. Style and approach Step-by-step instructions to help assemble your first drone with the Ardupilot platform.

This book collects papers selected by an international program committee for presentation at the 8th International Symposium on Distributed Autonomous Robotic Systems. The papers present state of the art research advances in the field of distributed robotics. What makes this book distinctive is the emphasis on using multiple robots and on making them autonomous, as opposed to being teleoperated. Novel algorithms, system architectures, technologies, and numerous applications are covered.

BeagleBone Robotic ProjectsPackt Publishing Ltd

Over the last few years, Linux has grown both as an operating system and a tool for personal and business use. Simultaneously becoming more user friendly and more powerful as a back-end system, Linux has achieved new plateaus: the newer filesystems have solidified, new commands and tools have appeared and become standard, and the desktop--including new desktop environments--have proved to be viable, stable, and readily accessible to even those who don't consider themselves computer gurus. Whether you're using Linux for personal software projects, for a small office or home office (often termed the SOHO environment), to provide services to a small group of colleagues, or to administer a site responsible for millions of email and web connections each day, you need quick access to information on a wide range of tools. This book covers all aspects of administering and making effective use of Linux systems. Among its topics are booting, package management, and revision control. But foremost in Linux in a Nutshell are the utilities and commands that make Linux one of the most powerful and flexible systems available. Now in its fifth edition, Linux in a Nutshell brings users up-to-date with the current state of Linux. Considered by many to be the most complete and authoritative command reference for Linux available, the book covers all substantial user, programming, administration, and networking commands for the most common Linux distributions. Comprehensive but concise, the fifth edition has been updated to cover new features of major Linux distributions. Configuration information for the rapidly growing commercial network services and community update services is one of the subjects covered for the first time. But that's just the beginning. The book covers editors, shells, and LILO and GRUB boot options. There's also coverage of Apache, Samba, Postfix, sendmail, CVS, Subversion, Emacs, vi, sed, gawk, and much more. Everything that system administrators, developers, and power users need to know about Linux is referenced here, and they will turn to this book again and again.

Over 30 recipes to develop custom drivers for your embedded Linux applications. Key Features Use Kernel facilities to develop powerful drivers Via a practical approach, learn core concepts of developing device drivers Program a custom character device to get access to kernel internals Book Description Linux is a unified kernel that is widely used to develop embedded systems. As Linux has turned out to be one of the most popular operating systems used, the interest in developing proprietary device drivers has also increased. Device drivers play a critical role in how the system performs and ensures that the device works in the manner intended. By offering several examples on the development of character devices and how to use other kernel internals, such as interrupts, kernel timers, and wait queue, as well as how to manage a device tree, you will be able to add proper management for custom peripherals to your embedded system. You will begin by installing the Linux kernel and then configuring it. Once you have installed the system, you will learn to use the different kernel features and the character drivers. You will also cover interrupts in-depth and how you can manage them. Later, you will get into the kernel internals required for developing applications. Next, you will implement advanced character drivers and also become an expert in writing important Linux device drivers. By the end of the book, you will be able to easily write a custom character driver and kernel code as per your requirements. What you will learn Become familiar with the latest kernel releases (4.19+/5.x) running on the ESPRESSObin devkit, an ARM 64-bit machine Download, configure, modify, and build kernel sources Add and remove a device driver or a module from the kernel Master kernel programming Understand how to implement character drivers to manage different kinds of computer peripherals Become well versed with kernel helper functions and objects that can be used to build kernel applications Acquire a knowledge of in-depth concepts to manage custom hardware with Linux from both the kernel and user space Who this book is for This book will help anyone who wants to develop their own Linux device drivers for embedded systems. Having basic hand-on with Linux operating system and embedded concepts is necessary. Unmanned aerial vehicles (UAV) have already become an affordable and cost-efficient tool to quickly map a targeted area for many emerging

applications in the arena of ecological monitoring and biodiversity conservation. Managers, owners, companies, and scientists are using professional drones equipped with high-resolution visible, multispectral, or thermal cameras to assess the state of ecosystems, the effect of disturbances, or the dynamics and changes within biological communities inter alia. We are now at a tipping point on the use of drones for these type of applications over natural areas. UAV missions are increasing but most of them are testing applicability. It is time now to move to frequent revisiting missions, aiding in the retrieval of important biophysical parameters in ecosystems or mapping species distributions. This Special Issue shows UAV applications contributing to a better understanding of biodiversity and ecosystem status, threats, changes, and trends. It documents the enhancement of knowledge in ecological integrity parameters mapping, long-term ecological monitoring based on drones, mapping of alien species spread and distribution, upscaling ecological variables from drone to satellite images: methods and approaches, rapid risk and disturbance assessment using drones, mapping albedo with UAVs, wildlife tracking, bird colony and chimpanzee nest mapping, habitat mapping and monitoring, and a review on drones for conservation in protected areas.

Leverage the WiFi chip to build exciting Quadcopters Key Features Learn to create a fully functional Drone with Arduino and ESP8266 and their modified versions of hardware. Enhance your drone's functionalities by implementing smart features. A project-based guide that will get you developing next-level drones to help you monitor a particular area with mobile-like devices. Book Description With the use of drones, DIY projects have taken off. Programmers are rapidly moving from traditional application programming to developing exciting multi-utility projects. This book will teach you to build industry-level drones with Arduino and ESP8266 and their modified versions of hardware. With this book, you will explore techniques for leveraging the tiny WiFi chip to enhance your drone and control it over a mobile phone. This book will start with teaching you how to solve problems while building your own WiFi controlled Arduino based drone. You will also learn how to build a Quadcopter and a mission critical drone. Moving on you will learn how to build a prototype drone that will be given a mission to complete which it will do it itself. You will also learn to build various exciting projects such as gliding and racing drones. By the end of this book you will learn how to maintain and troubleshoot your drone. By the end of this book, you will have learned to build drones using ESP8266 and Arduino and leverage their functionalities to the fullest. What you will learn Includes a number of projects that utilize different ESP8266 and Arduino capabilities, while interfacing with external hardware Covers electrical engineering and programming concepts, interfacing with the World through analog and digital sensors, communicating with a computer and other devices, and internet connectivity Control and fly your quadcopter, taking into account weather conditions Build a drone that can follow the user wherever he/she goes Build a mission-control drone and learn how to use it effectively Maintain your vehicle as much as possible and repair it whenever required Who this book is for If you are a programmer or a DIY enthusiast and keen to create a fully functional drone with Arduino and ESP8266, then this book is for you. Basic skills in electronics and programming would be beneficial. This book is not for the beginners as it includes lots of ideas not detailed how you can do that. If you are a beginner, then you might get lost here. The prerequisites of the book include a good knowledge of Arduino, electronics, programming in C or C++ and lots of interest in creating things out of nothing.

This book constitutes the refereed proceedings of the 18th Annual Conference on Towards Autonomous Robotics, TAROS 2017, held in Guildford, UK, in July 2017. The 43 revised full papers presented together with 13 short papers were carefully reviewed and selected from 66 submissions. The papers discuss robotics research drawn from a wide and diverse range of topics, such as swarm and multi-robotic systems; human-robot interaction; robotic learning and imitation; robot navigation, planning and safety; humanoid and bio-inspired robots; mobile robots and vehicles; robot testing and design; detection and recognition; learning and adaptive behaviours; interaction; soft and

reconfigurable robots; and service and industrial robots.