

Adaptive Terminal Sliding Mode Control For Nonlinear

This book presents some latest treatments of several specific, but fundamental problems about the data communication and control of smart microgrids. It provides readers some valuable insights into advanced control and communication of microgrids. With the help of mathematical tools, graduate students will benefit with a deep understanding of microgrids and explore some new research directions. In the meantime, this book gives various pictures and flowcharts to show how to address some challenges in microgrids. In addition, it provides solutions to several specific technical problems, which might be helpful as references for the R&D staff about power systems in utilities and industry. Specifically, the book introduces the applications of advanced control methods such as sliding mode control and model predictive control for microgrids. After getting in-depth understanding of these advanced control methods, the readers are able to design their own improved controllers for not only microgrids, but also for other real-world power plants. Besides, the readers will also learn how to design distributed transaction mechanisms for power market based on the cutting edge blockchain technology.

Gathering 20 chapters contributed by respected experts, this book reports on the latest advances in and applications of sliding mode control in science and engineering. The respective chapters address applications of sliding mode control in the broad areas of chaos theory, robotics, electrical engineering, physics, chemical engineering, memristors, mechanical engineering, environmental engineering, finance, and biology. Special emphasis has been given to papers that offer practical solutions, and which examine design and

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modeling involving new types of sliding mode control such as higher order sliding mode control, terminal sliding mode control, super-twisting sliding mode control, and integral sliding mode control. This book serves as a unique reference guide to sliding mode control and its recent applications for graduate students and researchers with a basic knowledge of electrical and control systems engineering.

As future generation electrical, information engineering and mechatronics become specialized and fragmented, it is easy to lose sight of the fact that many topics in these areas have common threads and, because of this, advances in one discipline may be transmitted to others. The 2011 International Conference on Electrical, Information Engineering and Mechatronics (EIEM 2011) is the first conference that attempts to follow the above idea of hybridization in electrical, information engineering, mechatronics and applications. This Proceedings of the 2011 International Conference on Electrical, Information Engineering and Mechatronics provides a forum for engineers and scientists to address the most innovative research and development including technical challenges and social, legal, political, and economic issues, and to present and discuss their ideas, results, works in progress and experience on all aspects of electrical, information engineering, mechatronics and applications. Engineers and scientists in academia, industry, and government will find a insights into the solutions that combine ideas from multiple disciplines in order to achieve something more significant than the sum of the individual parts in all aspects of electrical, information engineering, mechatronics and applications.

In recent years, entropy has been used as a measure of the degree of chaos in dynamical systems. Thus, it is important to study entropy in nonlinear systems. Moreover, there has been increasing interest in the last few years regarding the novel

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classification of nonlinear dynamical systems including two kinds of attractors: self-excited attractors and hidden attractors. The localization of self-excited attractors by applying a standard computational procedure is straightforward. In systems with hidden attractors, however, a specific computational procedure must be developed, since equilibrium points do not help in the localization of hidden attractors. Some examples of this kind of system are chaotic dynamical systems with no equilibrium points; with only stable equilibria, curves of equilibria, and surfaces of equilibria; and with non-hyperbolic equilibria. There is evidence that hidden attractors play a vital role in various fields ranging from phase-locked loops, oscillators, describing convective fluid motion, drilling systems, information theory, cryptography, and multilevel DC/DC converters. This Special Issue is a collection of the latest scientific trends on the advanced topics of dynamics, entropy, fractional order calculus, and applications in complex systems with self-excited attractors and hidden attractors.

Currently, the modelling and control of mechatronic and robotic systems is an open and challenging field of investigation in both industry and academia. The book encompasses the kinematic and dynamic modelling, analysis, design, and control of mechatronic and robotic systems, with the scope of improving their performance, as well as simulating and testing novel devices and control architectures. A broad range of disciplines and topics are included, such as robotic manipulation, mobile systems, cable-driven robots, wearable and rehabilitation devices, variable stiffness safety-oriented mechanisms, optimization of robot performance, and energy-saving systems.

This two-volume set of LNCS 12836 and LNCS 12837 constitutes - in conjunction with the volume LNAI 12838 - the refereed proceedings of the 17th International Conference on

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Intelligent Computing, ICIC 2021, held in Shenzhen, China in August 2021. The 192 full papers of the three proceedings volumes were carefully reviewed and selected from 458 submissions. The ICIC theme unifies the picture of contemporary intelligent computing techniques as an integral concept that highlights the trends in advanced computational intelligence and bridges theoretical research with applications. The theme for this conference is “Advanced Intelligent Computing Methodologies and Applications.” The papers are organized in the following subsections: Intelligent Computing in Computer Vision, Intelligent Control and Automation, Intelligent Modeling Technologies for Smart Cities, Machine Learning, and Theoretical Computational Intelligence and Applications.

The book addresses the latest advances in research and development in the field of informatics in control, robotics and automation. With more than twenty revised and extended articles covering the theoretical aspects as well as applications and their implementation, it offers a factual and well-balanced overview of the state of the art in the field. In addition, it highlights the trends in control of intelligent robots. The book is an up-to-date source of information and inspiration for researchers, engineers and PhD students.

Due to its abilities to compensate disturbances and uncertainties, disturbance observer based control (DOBC) is regarded as one of the most promising approaches for disturbance-attenuation. One of the first books on DOBC, Disturbance Observer Based Control: Methods and Applications presents novel theory results as well as best practices for applica

representative of the main current area of interest within the AI community.

Unmanned Aerial Systems: Theoretical Foundation and

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Applications presents some of the latest innovative approaches to drones from the point-of-view of dynamic modeling, system analysis, optimization, control, communications, 3D-mapping, search and rescue, surveillance, farmland and construction monitoring, and more. With the emergence of low-cost UAS, a vast array of research works in academia and products in the industrial sectors have evolved. The book covers the safe operation of UAS, including, but not limited to, fundamental design, mission and path planning, control theory, computer vision, artificial intelligence, applications requirements, and more. This book provides a unique reference of the state-of-the-art research and development of unmanned aerial systems, making it an essential resource for researchers, instructors and practitioners. Covers some of the most innovative approaches to drones Provides the latest state-of-the-art research and development surrounding unmanned aerial systems Presents a comprehensive reference on unmanned aerial systems, with a focus on cutting-edge technologies and recent research trends in the area 2011 International Conference in Electrics, Communication and Automatic Control Proceedings examines state-of-art and advances in Electrics, Communication and Automatic Control. This book presents developments in Power Conversion, Signal and image processing, Image & video Signal Processing. The conference brings together researchers, engineers, academic as well as industrial professionals from all over the world to promote the developments of Electrics, Communication and Automatic Control.

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The 2020 Chinese Automation Congress (CAC2020) will provide a platform for all scholars and technicians in automation and intelligent manufacturing from academy and industry to share ideas, and to present the latest scientific and technical advances

Adaptive Identification and Control of Uncertain Systems with Nonsmooth Dynamics reports some of the latest research on modeling, identification and adaptive control for systems with nonsmooth dynamics (e.g., backlash, dead zone, friction, saturation, etc). The authors present recent research results for the modelling and control designs of uncertain systems with nonsmooth dynamics, such as friction, dead-zone, saturation and hysteresis, etc., with particular applications in servo systems. The book is organized into 19 chapters, distributed in five parts concerning the four types of nonsmooth characteristics, namely friction, dead-zone, saturation and hysteresis, respectively. Practical experiments are also included to validate and exemplify the proposed approaches. This valuable resource can help both researchers and practitioners to learn and understand nonlinear adaptive control designs. Academics, engineers and graduate students in the fields of electrical engineering, control systems, mechanical engineering, applied mathematics and computer science can benefit from the book. It can be also used as a reference book on adaptive control for servo systems for students with some background in control engineering. Explains the latest research outputs on modeling, identification and adaptive control for systems with nonsmooth dynamics Provides practical application and experimental results

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for robotic systems, and servo motors

Mem-elements for Neuromorphic Circuits with Artificial Intelligence Applications illustrates recent advances in the field of mem-elements (memristor, memcapacitor, meminductor) and their applications in nonlinear dynamical systems, computer science, analog and digital systems, and in neuromorphic circuits and artificial intelligence. The book is mainly devoted to recent results, critical aspects and perspectives of ongoing research on relevant topics, all involving networks of mem-elements devices in diverse applications. Sections contribute to the discussion of memristive materials and transport mechanisms, presenting various types of physical structures that can be fabricated to realize mem-elements in integrated circuits and device modeling. As the last decade has seen an increasing interest in recent advances in mem-elements and their applications in neuromorphic circuits and artificial intelligence, this book will attract researchers in various fields. Covers a broad range of interdisciplinary topics between mathematics, circuits, realizations, and practical applications related to nonlinear dynamical systems, nanotechnology, analog and digital systems, computer science and artificial intelligence Presents recent advances in the field of mem-elements (memristor, memcapacitor, meminductor) Includes interesting applications of mem-elements in nonlinear dynamical systems, analog and digital systems, neuromorphic circuits, computer science and artificial intelligence

This book focuses on soft computing and how it can be applied to solve real-world problems arising in various

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domains, ranging from medicine and healthcare, to supply chain management, image processing and cryptanalysis. It gathers high-quality papers presented at the International Conference on Soft Computing: Theories and Applications (SoCTA 2020), organized online. The book is divided into two volumes and offers valuable insights into soft computing for teachers and researchers alike; the book will inspire further research in this dynamic field.

This volume includes extended and revised versions of a set of selected papers from the International Conference on Electric and Electronics (EEIC 2011) , held on June 20-22 , 2011, which is jointly organized by Nanchang University, Springer, and IEEE IAS Nanchang Chapter. The objective of EEIC 2011 Volume 2 is to provide a major interdisciplinary forum for the presentation of new approaches from Electrical engineering and controls, to foster integration of the latest developments in scientific research. 133 related topic papers were selected into this volume. All the papers were reviewed by 2 program committee members and selected by the volume editor Prof. Min Zhu. We hope every participant can have a good opportunity to exchange their research ideas and results and to discuss the state of the art in the areas of the Electrical engineering and controls.

In the recent years, fractional-order systems have been studied by many researchers in the engineering field. It was found that many systems can be described more accurately by fractional differential equations than by integer-order models. Advanced Synchronization Control and Bifurcation of Chaotic Fractional-Order Systems is a

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scholarly publication that explores new developments related to novel chaotic fractional-order systems, control schemes, and their applications. Featuring coverage on a wide range of topics including chaos synchronization, nonlinear control, and cryptography, this publication is geared toward engineers, IT professionals, researchers, and upper-level graduate students seeking current research on chaotic fractional-order systems and their applications in engineering and computer science. Maximizing reader insights into the latest technical developments and trends involving wind turbine control and monitoring, fault diagnosis, and wind power systems, 'Wind Turbine Control and Monitoring' presents an accessible and straightforward introduction to wind turbines, but also includes an in-depth analysis incorporating illustrations, tables and examples on how to use wind turbine modeling and simulation software. Featuring analysis from leading experts and researchers in the field, the book provides new understanding, methodologies and algorithms of control and monitoring, computer tools for modeling and simulation, and advances the current state-of-the-art on wind turbine monitoring and fault diagnosis; power converter systems; and cooperative & fault-tolerant control systems for maximizing the wind power generation and reducing the maintenance cost. This book is primarily intended for researchers in the field of wind turbines, control, mechatronics and energy; postgraduates in the field of mechanical and electrical engineering; and graduate and senior undergraduate students in engineering wishing to expand their knowledge of wind energy systems. The

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book will also interest practicing engineers dealing with wind technology who will benefit from the comprehensive coverage of the theoretic control topics, the simplicity of the models and the use of commonly available control algorithms and monitoring techniques.

The conference will provide an excellent platform for knowledge exchange between researchers, scientists, academicians and engineers working in the areas of automation, process, scientific research and analysis

This event calls for local and international participation

This volume includes extended and revised versions of a set of selected papers from the International Conference on Electric and Electronics (EEIC 2011) , held on June 20-22 , 2011, which is jointly organized by Nanchang University, Springer, and IEEE IAS Nanchang Chapter.

The objective of EEIC 2011 Volume 1 is to provide a major interdisciplinary forum for the presentation of new approaches from Electronics and Signal Processing, to foster integration of the latest developments in scientific research. 133 related topic papers were selected into this volume. All the papers were reviewed by 2 program committee members and selected by the volume editor Prof. Wensong Hu. We hope every participant can have a good opportunity to exchange their research ideas and results and to discuss the state of the art in the areas of the Electronics and Signal Processing.

This two-volume set of LNCS 12463 and LNCS 12464 constitutes - in conjunction with the volume LNAI 12465 - the refereed proceedings of the 16th International Conference on Intelligent Computing, ICIC 2020, held in Bari, Italy, in October 2020. The 162 full papers of the

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three proceedings volumes were carefully reviewed and selected from 457 submissions. The ICIC theme unifies the picture of contemporary intelligent computing techniques as an integral concept that highlights the trends in advanced computational intelligence and bridges theoretical research with applications. The theme for this conference is "Advanced Intelligent Computing Methodologies and Applications." Papers related to this theme are especially solicited, addressing theories, methodologies, and applications in science and technology.

"Advanced Sliding Mode Control for Mechanical Systems: Design, Analysis and MATLAB Simulation" takes readers through the basic concepts, covering the most recent research in sliding mode control. The book is written from the perspective of practical engineering and examines numerous classical sliding mode controllers, including continuous time sliding mode control, discrete time sliding mode control, fuzzy sliding mode control, neural sliding mode control, backstepping sliding mode control, dynamic sliding mode control, sliding mode control based on observer, terminal sliding mode control, sliding mode control for robot manipulators, and sliding mode control for aircraft. This book is intended for engineers and researchers working in the field of control. Dr. Jinkun Liu works at Beijing University of Aeronautics and Astronautics and Dr. Xinhua Wang works at the National University of Singapore.

Study on Adaptive Fuzzy Terminal Sliding-Mode Control and Adaptive Terminal Sliding-Function ControlA Robust

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Adaptive Terminal Sliding Mode Control for Rigid Robotic Manipulators
Sliding Mode Control in Electro-Mechanical Systems
CRC Press

The book is a collection of contributions concerning the theories, applications and perspectives of Variable Structure Systems (VSS). Variable Structure Systems have been a major control design methodology for many decades. The term Variable Structure Systems was introduced in the late 1950's, and the fundamental concepts were developed for its main branch Sliding Mode Control by Russian researchers Emelyanov and Utkin. The 20th Century has seen the formation and consolidation of VSS theory and its applications. It has also seen an emerging trend of cross-fertilization and integration of VSS with other control and non-control techniques such as feedback linearization, passivity based control, adaptive and learning control, system identification, pulse width modulation, H_∞ geometric and algebraic methods, artificial intelligence, modeling and optimization, neural networks, fuzzy logic, to name just a few. This trend will continue and flourish in the new millennium. To reflect these major developments in the 20th Century, this book - cludes 16 specially invited contributions from well-known experts in VSS theory and applications, covering a wide range of topics. The first chapter, "First Stage of VSS: People and Events" written by Vadim Utkin, the founder of VSS, oversees and documents the historical developments of VSS in the 20th Century, including many interesting events not known to the West until now. The second chapter, "An Integrated Learning Variable Structure

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Control Method” written by Jian-Xin Xu, addresses an important issue regarding control integration between variable structure control and learning control.

Advances in Reconfigurable Mechanisms and Robots I provides a selection of key papers presented in The Second ASME/IFTOMM International Conference on Reconfigurable Mechanisms and Robots (ReMAR 2012) held on 9th -11th July 2012 in Tianjin, China. This ongoing series of conferences will be covered in this ongoing collection of books. A total of seventy-eight papers are divided into seven parts to cover the topology, kinematics and design of reconfigurable mechanisms with the reconfiguration theory, analysis and synthesis, and present the current research and development in the field of reconfigurable mechanisms including reconfigurable parallel mechanisms. In this aspect, the recent study and development of reconfigurable robots are further presented with the analysis and design and with their control and development. The bio-inspired mechanisms and subsequent reconfiguration are explored in the challenging fields of rehabilitation and minimally invasive surgery. Advances in Reconfigurable Mechanisms and Robots I further extends the study to deployable mechanisms and foldable devices and introduces applications of reconfigurable mechanisms and robots. The rich-content of Advances in Reconfigurable Mechanisms and Robots I brings together new developments in reconfigurable mechanisms and robots and presents a new horizon for future development in the field of reconfigurable mechanisms and robots.

This book constitutes the refereed proceedings of the Third International Conference on Cognitive Systems and Signal Processing, ICCSIP2016, held in Beijing, China, in December 2016. The 59 revised full papers presented were carefully

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reviewed and selected from 171 submissions. The papers are organized in topical sections on Control and Decision; Image and Video; Machine Learning; Robotics; Cognitive System; Cognitive Signal Processing.

The sliding mode control methodology has proven effective in dealing with complex dynamical systems affected by disturbances, uncertainties and unmodeled dynamics. Robust control technology based on this methodology has been applied to many real-world problems, especially in the areas of aerospace control, electric power systems, electromechanical systems, and robotics. Sliding Mode Control and Observation represents the first textbook that starts with classical sliding mode control techniques and progresses toward newly developed higher-order sliding mode control and observation algorithms and their applications. The present volume addresses a range of sliding mode control issues, including: *Conventional sliding mode controller and observer design *Second-order sliding mode controllers and differentiators *Frequency domain analysis of conventional and second-order sliding mode controllers *Higher-order sliding mode controllers and differentiators *Higher-order sliding mode observers *Sliding mode disturbance observer based control *Numerous applications, including reusable launch vehicle and satellite formation control, blood glucose regulation, and car steering control are used as case studies Sliding Mode Control and Observation is aimed at graduate students with a basic knowledge of classical control theory and some knowledge of state-space methods and nonlinear systems, while being of interest to a wider audience of graduate students in electrical/mechanical/aerospace engineering and applied mathematics, as well as researchers in electrical, computer, chemical, civil, mechanical, aeronautical, and industrial engineering, applied mathematicians, control engineers, and

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physicists. Sliding Mode Control and Observation provides the necessary tools for graduate students, researchers and engineers to robustly control complex and uncertain nonlinear dynamical systems. Exercises provided at the end of each chapter make this an ideal text for an advanced course taught in control theory.

The book presents the newest results of the major world research groups working in the area of Variable Structure Systems and Sliding Mode Control (VSS/SMC). The research activity of these groups is coordinated by the IEEE Technical Committee on Variable Structure Systems (VSS) and Sliding Modes (SM). The presented results include the reports of the research groups collaborating in a framework of the Unión European Union – México project of Fondo de Cooperación Internacional en Ciencia y Tecnología (FONCICYT) 93302 titled "Automatization and Monitoring of Energy Production Processes via Sliding Mode Control". The book starts with the overview of the sliding mode control concepts and algorithms that were developed and discussed in the last two decades. The research papers are combined in three sections: Part I: VSS and SM Algorithms and their Analysis Part II: SMC Design Part III: Applications of VSS and SMC. The book will be of interests of engineers, researchers and graduate students working in the area of the control systems design. Novel mathematical theories and engineering concepts of control systems are rigorously discussed and supported by numerous applications to practical tasks.

In this book, leading researchers present their current work in the challenging area of chaos control in nonlinear circuits and systems, with emphasis on practical methodologies, system design techniques and applications. A combination of overview, tutorial and technical articles, the book describes state-of-the-art research on significant problems in this area. The scope and aim of this book are to bridge the gap

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between chaos control methods and circuits and systems. It is an ideal starting point for anyone who needs a fundamental understanding of controlling chaos in nonlinear circuits and systems.

The book is devoted to systems with discontinuous control. The study of discontinuous dynamic systems is a multifacet problem which embraces mathematical, control theoretic and application aspects. Times and again, this problem has been approached by mathematicians, physicists and engineers, each profession treating it from its own positions.

Interestingly, the results obtained by specialists in different disciplines have almost always had a significant effect upon the development of the control theory. It suffices to mention works on the theory of oscillations of discontinuous nonlinear systems, mathematical studies in ordinary differential equations with discontinuous righthand parts or variational problems in nonclassic statements. The unremitting interest to discontinuous control systems enhanced by their effective application to solution of problems most diverse in their physical nature and functional purpose is, in the author's opinion, a cogent argument in favour of the importance of this area of studies. It seems a useful effort to consider, from a control theoretic viewpoint, the mathematical and application aspects of the theory of discontinuous dynamic systems and determine their place within the scope of the present-day control theory. The first attempt was made by the author in 1975-1976 in his course on "The Theory of Discontinuous Dynamic Systems" and "The Theory of Variable Structure Systems" read to post-graduates at the University of Illinois, USA, and then presented in 1978-1979 at the seminars held in the Laboratory of Systems with Discontinuous Control at the Institute of Control Sciences in Moscow.

This book reflects the latest developments in variable structure systems (VSS) and sliding mode control (SMC),

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highlighting advances in various branches of the VSS/SMC field, e.g., from conventional SMC to high-order SMC, from the continuous-time domain to the discrete-time domain, from theories to applications, etc. The book consists of three parts and 16 chapters: in the first part, new VSS/SMC algorithms are proposed and their properties are analyzed, while the second focuses on the use of VSS/SMC techniques to solve a variety of control problems; the third part examines the applications of VSS/SMC to real-time systems. The book introduces postgraduates and researchers to the state-of-the-art in VSS/SMC field, including the theory, methodology, and applications. Relative academic disciplines include Automation, Mathematics, Electrical Engineering, Mechanical Engineering, Instrument Science and Engineering, Electronic Engineering, Computer Science and Technology, Transportation Engineering, Energy and Power Engineering, etc.

Adaptive Sliding Mode Neural Network Control for Nonlinear Systems introduces nonlinear systems basic knowledge, analysis and control methods, and applications in various fields. It offers instructive examples and simulations, along with the source codes, and provides the basic architecture of control science and engineering. Introduces nonlinear systems' basic knowledge, analysis and control methods, along with applications in various fields Offers instructive examples and simulations, including source codes Provides the basic architecture of control science and engineering These proceedings present selected research papers from CISC'16, held in Xiamen, China. The topics include Multi-agent system, Evolutionary Computation, Artificial Intelligence, Complex systems, Computation intelligence and soft computing, Intelligent control, Advanced control

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technology, Robotics and applications, Intelligent information processing, Iterative learning control, Machine Learning, and etc. Engineers and researchers from academia, industry, and government can get an insight view of the solutions combining ideas from multiple disciplines in the field of intelligent systems.

This book describes the advances and applications in Sliding mode control (SMC) which is widely used as a powerful method to tackle uncertain nonlinear systems. The book is organized into 21 chapters which have been organised by the editors to reflect the various themes of sliding mode control. The book provides the reader with a broad range of material from first principles up to the current state of the art in the area of SMC and observation presented in a clear, matter-of-fact style. As such it is appropriate for graduate students with a basic knowledge of classical control theory and some knowledge of state-space methods and nonlinear systems. The resulting design procedures are emphasized using Matlab/Simulink software.

Tutors can design entry-level courses in robotics with a strong orientation to the fundamental discipline of manipulator control pdf solutions manual Overheads will save a great deal of time with class preparation and will give students a low-effort basis for more detailed class notes Courses for senior undergraduates can be designed around Parts I – III;

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these can be augmented for masters courses using Part IV

Apply Sliding Mode Theory to Solve Control Problems Interest in SMC has grown rapidly since the first edition of this book was published. This second edition includes new results that have been achieved in SMC throughout the past decade relating to both control design methodology and applications. In that time, Sliding Mode Control (SMC) has continued to gain increasing importance as a universal design tool for the robust control of linear and nonlinear electro-mechanical systems. Its strengths result from its simple, flexible, and highly cost-effective approach to design and implementation. Most importantly, SMC promotes inherent order reduction and allows for the direct incorporation of robustness against system uncertainties and disturbances. These qualities lead to dramatic improvements in stability and help enable the design of high-performance control systems at low cost. Written by three of the most respected experts in the field, including one of its originators, this updated edition of Sliding Mode Control in Electro-Mechanical Systems reflects developments in the field over the past decade. It builds on the solid fundamentals presented in the first edition to promote a deeper understanding of the conventional SMC methodology, and it examines new design principles in order to broaden the

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application potential of SMC. SMC is particularly useful for the design of electromechanical systems because of its discontinuous structure. In fact, where the hardware of many electromechanical systems (such as electric motors) prescribes discontinuous inputs, SMC becomes the natural choice for direct implementation. This book provides a unique combination of theory, implementation issues, and examples of real-life applications reflective of the authors' own industry-leading work in the development of robotics, automobiles, and other technological breakthroughs.

Provides comprehensive coverage of the most recent developments in the theory of non-Archimedean pseudo-differential equations and its application to stochastics and mathematical physics--offering current methods of construction for stochastic processes in the field of p-adic numbers and related structures. Develops a new theory for parabolic equat

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